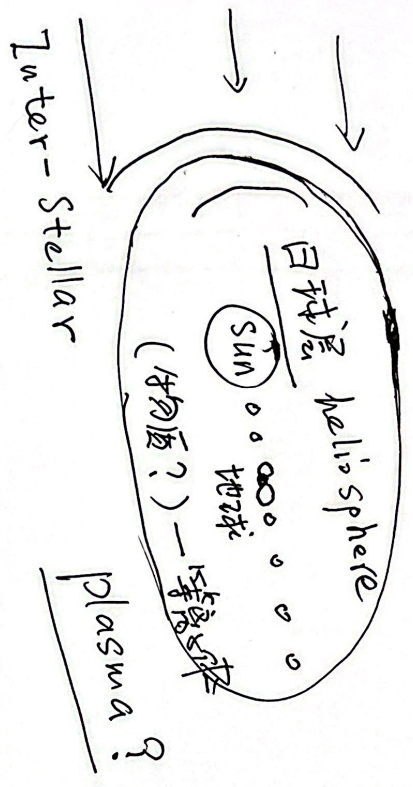
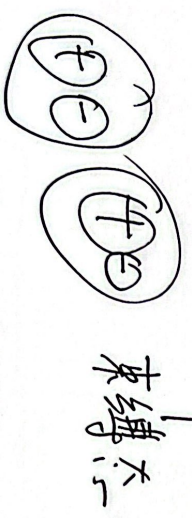


太空？物质？



自然界中的 plasma?

三态：固、液、气 (分子)

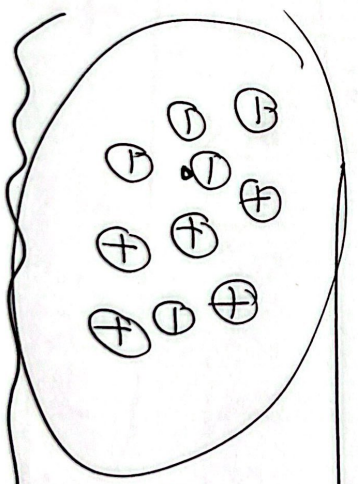


温度：平均动能

$$\frac{3k_B T}{2} \quad (k, eV)$$

$$\left. \begin{matrix} 1eV \sim 11600 K \\ 10keV \sim 100MK \end{matrix} \right\} \Rightarrow \text{电离 (复合)}$$

电离 \rightarrow ? 电性 (库仑作用) [等离子体]



第四态

多体长程库仑作用

集体行为

振荡现象

屏蔽现象

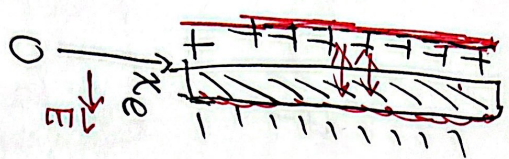
库仑碰撞

1.2 集体行为的几种表现与等离子体振荡

1.2.1 等离子体振荡 (plasma oscillation), Langmuir 波/模

(2)

$n_p = n_e = n_0$



$$m_e \frac{d^2 x_e}{dt^2} = qE = -eE$$

$$E = \frac{\sigma}{\epsilon_0} = \frac{n x_e e}{\epsilon_0}$$

\Rightarrow

$$\frac{d^2 x_e}{dt^2} = - \frac{n e^2}{m_e \epsilon_0} x_e$$

$$x_e = -w_{pe}^2 t e$$

$$w_{pe}^2 = \frac{n e^2}{m_e \epsilon_0}$$

$$\sim \cos(w_{pe} t e)$$

$$w_{pe} \propto \sqrt{n}$$

$$q_i = Z_i e, m_i \Rightarrow w_{pi}^2 = \frac{n Z_i^2 e^2}{m_i \epsilon_0}$$

$$w_p^2 = w_{pe}^2 + w_{pi}^2 = \alpha w_{pe}^2 \quad (\text{第四题})$$

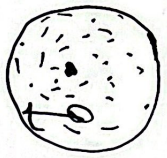
$$w_{pe}^2 \propto \frac{1}{m_e}, w_{pi}^2 \propto \frac{1}{m_i}, \frac{m_p}{m_e} \sim 1836$$

$$f_{pe} = \frac{w_{pe}}{2\pi} \approx 9 \sqrt{n_e (\text{cm}^{-3})} \text{ kHz}$$

太阳大气 10^8 cm^{-3} $f_{pe} \sim 90 \text{ MHz}$

1.2.2 德拜屏蔽 (Debye Shielding)

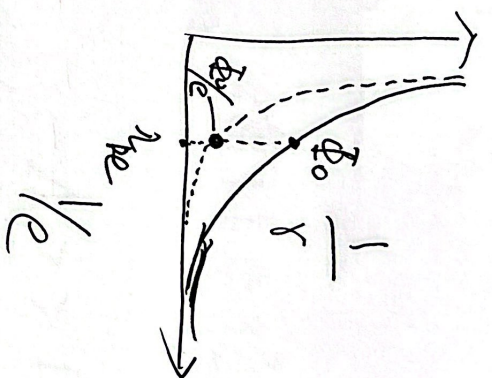
(3)



$$\Phi_0 = \frac{q}{4\pi\epsilon_0 r} \propto \frac{1}{r}$$

有效屏蔽的范围.

Φ_0 热场中的热平衡分布函数



热平衡分布函数

$$n_e = n_0 \exp\left(\frac{e\Phi(r)}{k_B T_e}\right)$$

$e\Phi(r) \ll k_B T_e$
热平衡 粒子的能量

$$n_e \approx n_0 \left(1 + \frac{e\Phi(r)}{k_B T_e}\right)$$

$$\rho_e = -en_e + n_p e$$

$$= -8n_e \cdot e$$

$$\nabla \cdot \vec{E} = \frac{\rho_e}{\epsilon_0} = -\frac{e n_e}{\epsilon_0} \Rightarrow \nabla^2 \Phi = \frac{e n_e}{\epsilon_0}$$

$$\Rightarrow \nabla^2 \Phi =$$

$$\frac{e^2 N_0 \Phi(r)}{k_B T_e \epsilon_0} = \frac{\Phi(r)}{\lambda_D^2}$$

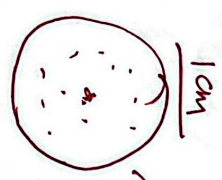
$$n_e(r) = n_0 \exp\left(\frac{e\Phi(r)}{k_B T_e}\right) \Rightarrow \frac{d^2 n_e(r)}{dr^2} = \frac{n_e(r)}{\lambda_D^2}$$

$$\Rightarrow n_e(r) = n_0 \exp\left(-\frac{r}{\lambda_D}\right) + n_1$$

1.2.3 准中性与响应时间

(5)

准中性: $n_{e0} = \sum_i Z_i n_{i0}$



$\frac{4}{3}\pi r^3 n / 10^4$
 $n = 10^{14} \text{ cm}^{-3}$

$\Rightarrow E = 6 \times 10^5 \text{ V/m}$

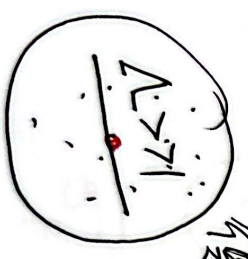
$4\pi r^2 E$

响应时间: $\lambda_e / v_{the} = \sqrt{\frac{k_B T_e \epsilon_0}{n_0 e^2}} / \sqrt{\frac{k_B T_e}{m_e}} = \sqrt{\frac{m_e \epsilon_0}{n_0 e^2}} = \frac{1}{\omega_{pe}}$

1.2.4 判据 $L \gg \lambda_e$, ($L \gg \lambda_e, T \gg \tau$), (电子 \gg 库仑相互作用)

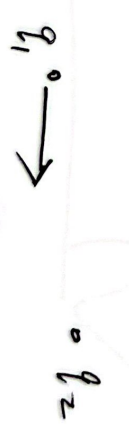
1.3 库仑碰撞 (经典库仑相互作用).

德拜球



大角度散射 $\theta \sim \frac{\pi}{2}$

小角度散射 $\theta \ll 1$



$\tan(\frac{\theta}{2}) = \frac{\frac{1}{2} q_2}{\frac{1}{2} q_1} = \frac{q_2}{q_1} \sim \frac{\theta_c}{2}$

大角度散射截面: $\frac{\pi R^2}{4}$

面: πR^2

$$\left(\frac{R}{2}\right) = \frac{q_1 q_2}{8\pi \epsilon_0 b c}$$

$$\sim \sigma_N \sim \sigma_F$$



$\frac{R}{2}, \lambda_{De}$

(6)

某一次碰撞 (i)

$$\bar{\sigma}_F = \frac{\sigma_F}{N}$$

$$\Delta \theta_{ij} = \frac{q_1 q_2}{8\pi \epsilon_0 b c p}$$

$$\Delta \theta_{ij} = \Delta \theta_{i1} + \Delta \theta_{i2} + \dots + \Delta \theta_{iN}$$

$$j=1, 2, \dots$$

$$\bar{\theta}_c = \sqrt{\sum_i \theta_{ci}^2} = \left[\frac{1}{\pi a_D^2} \int_{R_L}^{R_D} \Delta \theta_{ij}^2 2\pi p d\rho \right]^{1/2}$$

$$\Delta \theta_{ij}^2 = \frac{q_1^2 q_2^2}{8\pi^2 \epsilon_0^2 E_c^2 p^2}$$

$$= \left[\frac{q_1^2 q_2^2}{8\pi^2 \epsilon_0^2 E_c^2} \ln\left(\frac{R_D}{R_L}\right) \right]^{1/2}$$

$$\sqrt{N} \bar{\theta}_c = \frac{\pi}{2} \Rightarrow N = \left(\frac{\pi}{2/\bar{\theta}_c}\right)^2$$

$$\frac{16\pi^2 \epsilon_0^2 E_c^2 p^2}{4 q_1^2 q_2^2}$$

$$\frac{\pi^2 \lambda_D^2}{4} \frac{q_1^2 q_2^2}{8\pi^2 \epsilon_0^2 E_c^2} \ln\left(\frac{R_D}{R_L}\right)$$

$$\sum_{i=1}^N \left(\sum_{j=1}^N \Delta \theta_{ij} \right)^2 = N \bar{\theta}_c^2$$

$$\frac{\lambda_D}{R_L} = 6 \lambda$$

$$\bar{\sigma}_F = \frac{\pi \lambda_D^2}{N}$$

$$\sim \frac{4 R_D^2}{\pi} \frac{q_1^2 q_2^2}{8\pi^2 \epsilon_0^2 E_c^2}$$

$$= \frac{3^2}{\pi^2} \sigma_N \ln 6 \lambda \Rightarrow \sigma_N < \bar{\sigma}_F$$

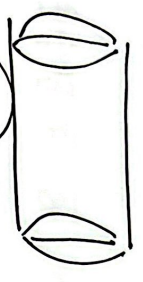
$$\ln(6\lambda)$$

$$\sim 5 \sigma_N \sim \frac{2 R_L^2}{4}$$

比较

$$\frac{\rho_f \sigma_F}{n} = 1$$

$$T = \frac{\lambda_f}{v_{the}}, \quad \nu = \frac{v_{the}}{\lambda_f} = v_{the} \cdot n \cdot \sigma_F \quad (7)$$



$$\rho_f \cdot \sigma_F \cdot n = 1$$

$$\nu \propto \sqrt{T} \cdot n / T^2 \sim \boxed{N T^{-3/2}}$$

对于高温、低密度等离子体，常可忽略库仑碰撞

无碰撞等离子体
Collisionless Plasma

1.4 等离子体中的辐射

1.5 描述方法：粒子碰撞、单粒子轨道

粒子碰撞

速度分布函数

相空间

磁流体力学 (MHD)

(单流体)、双流体

流体力学近似

n, \vec{v}, T

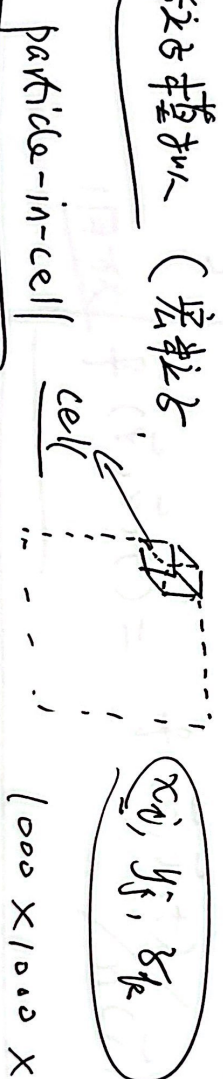
1.5 数学描述方法

多粒子体系 (自由电荷) :

$$\left\{ \begin{aligned} \vec{F} &= m_a \vec{a} = m_a \frac{d\vec{v}}{dt} = q_a (\vec{E} + \vec{v} \times \vec{B}), \quad i=1, \dots, N \\ \nabla \cdot \vec{E} &= \rho_a / \epsilon_0 \\ \nabla \cdot \vec{B} &= 0 \\ \nabla \times \vec{E} &= -\partial \vec{B} / \partial t \\ \nabla \times \vec{B} &= M_0 \vec{j} + M_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} \end{aligned} \right.$$

$$\rho_a = \sum_a n_a q_a \quad \vec{j} = \sum_a n_a q_a \vec{v}_a$$

① 给定 \vec{E}, \vec{B} , 分析单粒子轨道



② 粒子模拟 (宏粒子)

10^{10}

计算资源 \rightarrow 研究小尺度的物理问题 ? 电子, 质子

③ 流体方程近似

(粒子动力学)

近似条件: 碰撞足够频繁, 成团

$n, \vec{v}, T, p \sim nkT$ (PRT)

磁流体方程

kinetic scale

粒子尺度 vs. 流体方程尺度

λ / λ_{De} 大 / 宏观

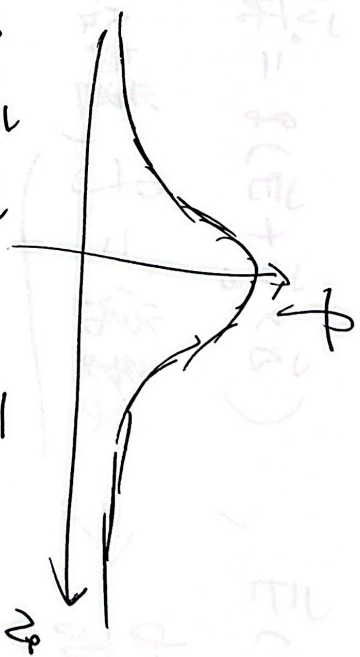
$\frac{\partial n}{\partial t} + \nabla \cdot (n \vec{v}) = 0$ 质量守恒

$\rho \frac{d\vec{v}}{dt} = -\nabla p + \vec{j} \times \vec{B} + \rho \vec{g}$

④ 动力学理论 (Kinetic Theory)

$$f(\vec{r}, \vec{v}, t)$$

$d\vec{r}$



$$\int d^3v f(\vec{r}, \vec{v}, t) = n(\vec{r}, t)$$

零阶矩

归一化

$$f(\vec{r}, \vec{v}, t) = \frac{f(\vec{r}, \vec{v}, t)}{n(\vec{r}, t)}$$

$$\int \vec{v} f(\vec{r}, \vec{v}, t) d^3v = n\vec{u}(\vec{r}, t)$$

- 一阶矩

二阶矩

$$\int m \vec{v} \vec{v} f(\vec{r}, \vec{v}, t) d^3v = \int m (\vec{u} + \vec{w})(\vec{u} + \vec{w}) f d^3v$$

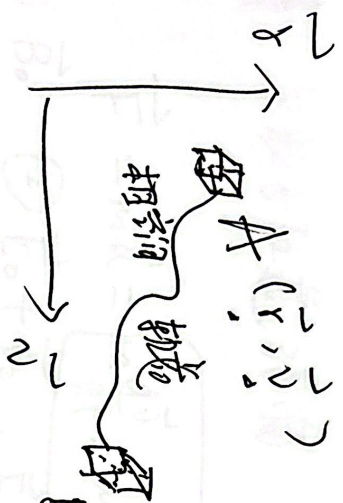
六维相空间

$$\vec{p} = \int m m \vec{v} \vec{v} f d^3v$$

$$f(\vec{r}, \vec{v}, t)$$

phase space

$$= m n \vec{u} + \vec{p}$$



$$\vec{F} = m \frac{d\vec{v}}{dt} = q(\vec{E} + \vec{v} \times \vec{B}) \quad (10)$$

沿轨迹, $f = \text{常数} \Rightarrow \frac{df}{dt} = 0$

$$\frac{df(\vec{r}, \vec{v}, t)}{dt} = 0 = \frac{d}{dt} f(\vec{r}(t), \vec{v}(t), t)$$

$$\frac{d}{dt} = \frac{\partial}{\partial t} + \vec{v} \cdot \nabla$$

$$\Rightarrow \frac{df}{dt} = \frac{\partial f}{\partial t} + \frac{d\vec{r}(t)}{dt} \cdot \frac{\partial f}{\partial \vec{r}} + \frac{d\vec{v}(t)}{dt} \cdot \frac{\partial f}{\partial \vec{v}}$$

$$\frac{d\vec{r}(t)}{dt} = \vec{v}, \quad \frac{d\vec{v}}{dt} = \vec{a}$$

$$\frac{\partial}{\partial \vec{r}} \sim \nabla_{\vec{r}}, \quad \frac{\partial}{\partial \vec{v}} \sim \nabla_{\vec{v}}$$

$$\frac{df}{dt} = \frac{\partial f}{\partial t} + \vec{v} \cdot \nabla_{\vec{r}} f + \vec{a} \cdot \nabla_{\vec{v}} f = 0$$

$$\frac{\partial f}{\partial t} + \vec{v} \cdot \nabla_{\vec{r}} f + \frac{q}{m} (\vec{E} + \vec{v} \times \vec{B}) \cdot \nabla_{\vec{v}} f = 0$$

(Vlasov 方程)

无碰撞 Boltzmann 方程

$$\left(\frac{\partial f}{\partial t}\right)_c \propto (v_i - v_{ji}) \nabla$$

第二章 单粒子轨道理论

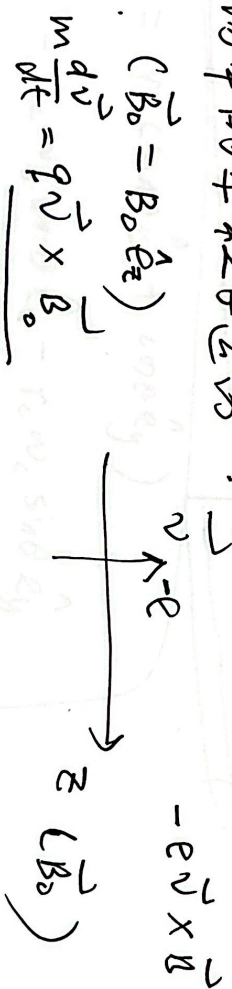
⑩ ⑪

$$\vec{F} = m\vec{a} = m \frac{d\vec{v}}{dt} = m \frac{d^2\vec{r}}{dt^2} = q(\vec{E} + \vec{v} \times \vec{B}) = q(\vec{E}(\vec{r}, t) + \vec{v} \times \vec{B}(\vec{r}, t))$$

- ① \vec{B}_0
- ② $\vec{E}_0 + \vec{B}_0, \vec{E}_0 + \vec{B}_0$
- ③ $\vec{B} = \vec{B}_0 + \vec{B}_1 + \vec{B}_2$
- ④ $\vec{E} = \vec{E}_0 + \vec{E}_1, \vec{E}_0(t)$

2.1 均匀外场中的单粒子运动

2.1.1 ... 磁... ($\vec{B}_0 = B_0 \hat{e}_z$)



$$m \frac{d^2x}{dt^2} = q \frac{B_0}{m} \frac{dy}{dt} \Rightarrow \frac{d^2x}{dt^2} = \frac{qB_0}{m} y$$

$$\frac{d^2y}{dt^2} = -\left(\frac{qB_0}{m}\right)^2 y$$

$$\frac{q^2 B_0^2}{m^2} = \omega_c^2, \quad \omega_c = \frac{qB_0}{m}, \quad \Omega_c = \frac{1}{2} \frac{qB_0}{m}$$

$$\left. \begin{aligned} v_x &= v_{L0} \cos(\omega_c t + \alpha) \\ v_y &= -v_{L0} \sin(\omega_c t + \alpha) \end{aligned} \right\} \Rightarrow \begin{cases} x = x_0 + \frac{v_{L0}}{\omega_c} \sin(\omega_c t + \alpha) \\ y = y_0 + \frac{v_{L0}}{\omega_c} \cos(\omega_c t + \alpha) \end{cases} \Rightarrow (x-x_0)^2 + (y-y_0)^2 = \left(\frac{v_{L0}}{\omega_c}\right)^2$$

$$r_c = \left| \frac{v_{L0}}{\omega_c} \right| = \frac{v_{L0}}{\Omega_c} = r_c^2$$

对于电子, 右旋; 质子, 左旋

$$\Omega_c = \frac{eB}{m_e} \Rightarrow \Omega_{cp} = \frac{eB}{m_p}$$

$$B = 10G, \quad \Omega_{cp} = ? \quad 2.8 \text{ MHz } B(G) = 28 \text{ MHz}$$

$$r_{ce} \sim \frac{v_{L0}}{\Omega_c} \sim \frac{\sqrt{10} r_{pe}}{\Omega_c} \sim \frac{e v_{L0} B}{m_e \Omega_c^2} \propto \sqrt{m_e}$$

2.1.2 带电粒子的漂移 (Drift)

$$m \frac{d\vec{v}}{dt} = q(\vec{E}_0 + \vec{v} \times \vec{B}_0)$$

$$\vec{E}_0 + \vec{v}_D \times \vec{B}_0 = 0$$

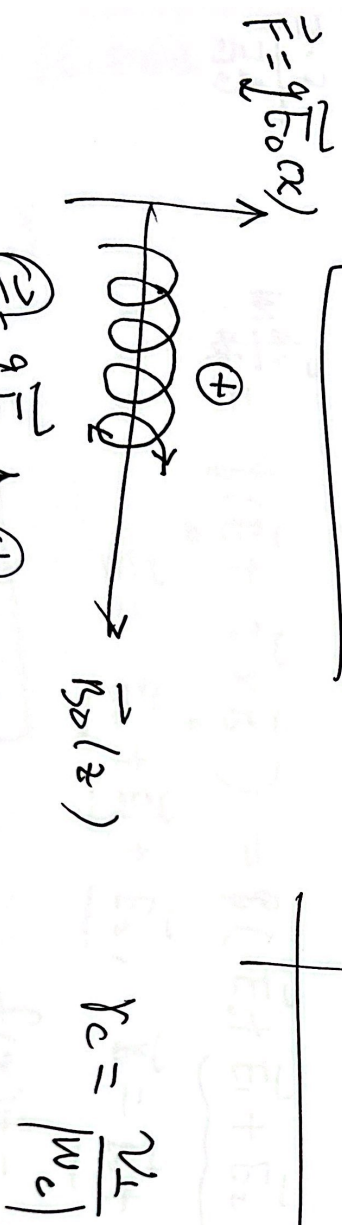
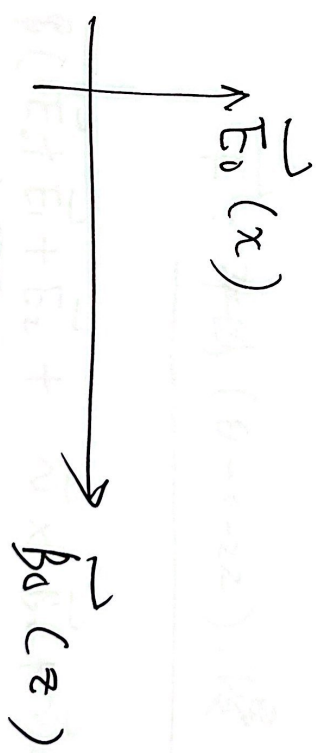
$$\vec{v} = \vec{v}_D + \vec{v}'$$

$$m \frac{d\vec{v}'}{dt} = q \vec{v}' \times \vec{B}_0$$

$$\vec{v}_D \times \vec{B}_0 = -\vec{E}_0 \Rightarrow (\vec{v}_D \times \vec{B}_0) \times \vec{B}_0 = -\vec{v}_D B_0^2 = -\vec{E}_0 \times \vec{B}_0$$

$$\vec{v}_D = \frac{\vec{E}_0 \times \vec{B}_0}{B_0^2}$$

$$\vec{v}'_{DF} = \frac{\vec{F} \times \vec{B}_0}{q B_0^2}$$



$$r_c = \frac{v_D}{|\omega_c|}$$

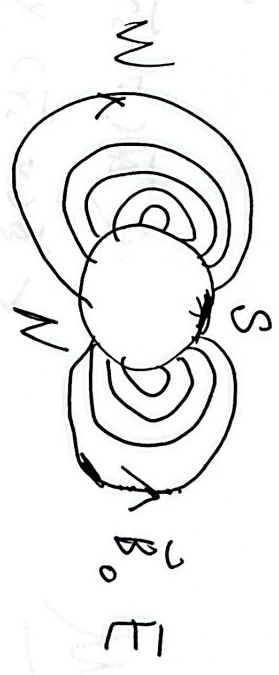


回旋轨道不闭合 \Rightarrow 引导中心

(横向) 漂移

漂移 \vec{v}_D 与 q, m 无关! \Rightarrow 整体漂移.

2.1.3 电场与任意外加磁场中的电子源耦合



$$\vec{v}_{Dq} = \frac{m \vec{g} \times \vec{B}}{q B^2}$$

$$\vec{v}_{DF} = \frac{\vec{F} \times \vec{B}}{q B^2}$$

恒定磁场

$$m \frac{d\vec{v}}{dt} = \vec{F} + q \vec{v} \times \vec{B}_0$$

\vec{F} : 平均 ($\theta \sim 0-2\pi$). 慢变化 ($\tau \gg \frac{1}{\Omega_c}$)

$$m \frac{d\vec{v}}{dt} = q(\vec{E} + \vec{v} \times \vec{B}) = q(\vec{E}_0 + \vec{E}_1 + \vec{E}_2 + \vec{v} \times \vec{B}_0 + \vec{v} \times \vec{B}_1 + \vec{v} \times \vec{B}_2)$$

$$\vec{E} = \vec{E}_0 + \vec{E}_1 + \vec{E}_2, \quad \vec{B} = \vec{B}_0 + \vec{B}_1 + \vec{B}_2$$

$$\vec{r} = \vec{R} + \vec{r}_c$$

$$\vec{r}_c = r_c (\sin \theta \hat{e}_r + \cos \theta \hat{e}_\theta)$$

$$\vec{r}_c \cdot \nabla = r_c (\sin \theta \partial_x + \cos \theta \partial_y)$$

$$f(x) \approx f(x_0) + f'(x_0)(x-x_0) + \frac{f''(x_0)}{2}(x-x_0)^2$$

$$\vec{E} = \vec{E}_0(r) + \vec{r}_c \cdot \nabla \vec{E} \Big|_R + \frac{1}{2} \vec{r}_c (\vec{r}_c \cdot \nabla) \cdot \nabla \vec{E} \Big|_R$$

(自行练习)



2.2 弱变化磁物中粒子的运动

$\langle \vec{F} \rangle$ 若在周期 ($0 \leq \theta \leq 2\pi$) 上取平均.

$$\frac{d\vec{L}}{dt} = q \vec{v} \times \vec{B} = q \vec{v} \times (B_0 \hat{z} + \vec{r}_c \cdot \nabla \vec{B}) = \vec{F} + q \vec{v} \times B_0 \hat{z}$$

(15)

$$\langle \vec{F} \rangle = \langle q \vec{v} \times (B_0 \hat{z} + \vec{r}_c \cdot \nabla \vec{B}) \rangle$$

$$\vec{v} = \vec{v}_{DF} + \vec{v}_c$$

$$= \langle q \vec{v}_c \times (\vec{r}_c \cdot \nabla) \vec{B} \rangle = -\mu \nabla B$$

$$\langle \vec{F} \rangle = \frac{q^2}{m} \langle (\vec{r}_c \cdot \nabla) \vec{B} \times (\vec{r}_c \times B_0 \hat{z}) \rangle$$

$$\vec{A} \times (\vec{B} \times \vec{C}) = \vec{A} \cdot \vec{C} \vec{B} - \vec{A} \cdot \vec{B} \vec{C}$$

$$\langle \vec{F} \rangle = -\frac{q^2}{m} \langle (\vec{r}_c \cdot \nabla) \vec{B} \cdot B_0 \hat{z} - (\vec{r}_c \cdot \nabla) \vec{B} \cdot \vec{r}_c B_0 \rangle$$

同样, 可得: $\langle \vec{F}_1 \rangle = -\mu \nabla B$

$$\vec{r}_c \cdot \nabla = r_c \sin \theta \partial_x + r_c \cos \theta \partial_y$$

$$\vec{B} = B_x \hat{e}_x + B_y \hat{e}_y + B_z \hat{e}_z$$

$$B_0 = B_0 \hat{e}_z$$

$$\langle r_c \sin \theta \partial_x + r_c \cos \theta \partial_y \rangle B_x B_0 (r_c \sin \theta \hat{e}_x + r_c \cos \theta \hat{e}_y)$$

$$= \langle r_c^3 \sin^2 \theta \partial_x B_x B_0 \hat{e}_x + r_c^3 \cos^2 \theta \partial_y B_y B_0 \hat{e}_y \rangle$$

$$= \frac{B_0}{2} r_c^2 (\partial_x B_x \hat{e}_x + \partial_y B_y \hat{e}_y) \quad (\langle \sin^2 \theta \rangle = 1/2)$$

$$= -\frac{q^2 B_0}{m} \frac{r_c^2}{2} \nabla_{\perp} B$$

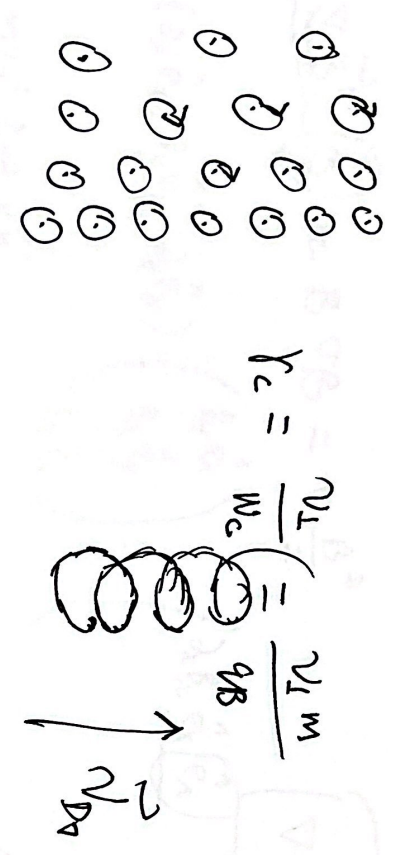
$$= -\frac{\mu v_{Te}^2}{2 B_0} \nabla_{\perp} B = -\mu \nabla_{\perp} B \sim \mu \nabla B$$

立刻可得

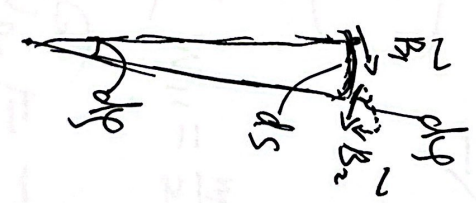
$$\vec{v}_{Drift} = \frac{-M \nabla B \times \vec{B}}{q B^2}$$

梯度漂移 — Gradient Drift

梯度漂移的图像：



$$r_c = \frac{v_{\perp}}{\omega_c} = \frac{v_{\perp} m}{q B}$$



$$\vec{dB} = \vec{B}_2 - \vec{B}_1$$

$$dp = \frac{ds}{r_c} = \frac{dB}{B}$$

$$\Rightarrow r_c = \frac{ds}{dB} B$$

$$\Rightarrow \frac{dB}{ds} = \frac{dB}{ds} \frac{1}{B}$$

$$\frac{dB}{ds} = \frac{1}{B} \cdot \nabla B$$

$$\Rightarrow r_c = \frac{1}{B^2} \cdot \nabla B$$

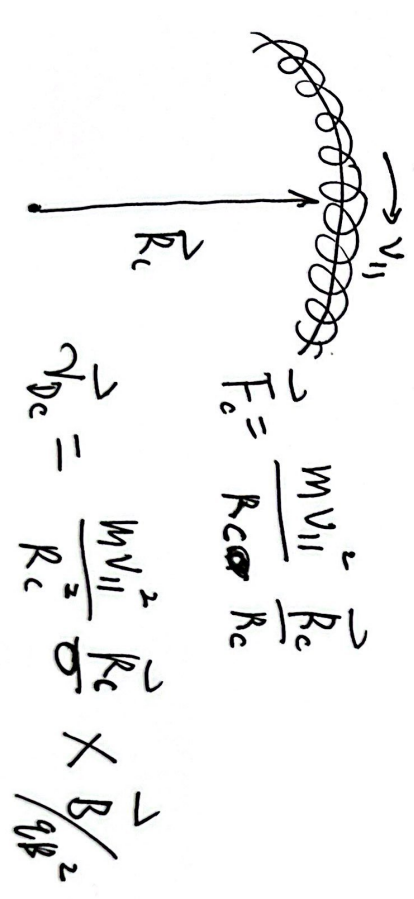


$$\vec{F}_c = \frac{m v_{\perp}^2}{B^2} \nabla B$$

$$\vec{F}_c = m v_{\perp}^2 \frac{1}{B^2} \nabla B$$

$$\vec{F}_c = \frac{1}{r_c} \frac{ds}{ds} \frac{1}{B} \cdot \left(-\frac{dB}{ds} \right)$$

2.2.2. 曲率漂移 (Curvature Drift)



$$\vec{F}_c = \frac{m v_{\parallel}^2}{R_c} \frac{\vec{R}_c}{R_c}$$

$$\vec{v}_{Drift} = \frac{m v_{\parallel}^2}{R_c} \frac{\vec{R}_c}{q B^2} \times \frac{\vec{B}}{q B^2}$$

地磁场的中 (76)

磁层：自东向西
电子：自西向东

环电流主要成因。

$$\vec{V}_D = \frac{m v_{II}^2}{B^2} \frac{\vec{B} \cdot \nabla \vec{B}}{B^2} \times \vec{B} / q B^2$$

4K 100 $\vec{B} \cdot \nabla \vec{B}$, 条件:

$$(\nabla \times \vec{B}) \times \vec{B} = 0$$

(17)

$$(\nabla \times \vec{B}) \times \vec{B} = (\vec{B} \cdot \nabla) \vec{B} - \nabla \vec{B} \cdot \vec{B} \neq 0$$

$$(\nabla \vec{B}) \cdot \vec{B} = B \nabla B = \nabla \frac{B^2}{2}$$

$$\nabla B^2 = 2 \vec{B} \cdot \nabla \vec{B}$$

$$\nabla \times \vec{B} = \mu_0 \vec{j}$$

$$\Rightarrow \vec{j} \times \vec{B} = 0 \quad (\text{Lorentz } \vec{v})$$

$$\begin{pmatrix} k_x \hat{e}_x \\ k_y \hat{e}_y \\ k_z \hat{e}_z \end{pmatrix} =$$

$$\left(\omega_{II} = \frac{m v_{II}^2}{2}, \quad \omega_L = \frac{m v_{II}^2}{2} \right)$$

$$\vec{V}_D = \frac{m v_{II}^2}{q B^4} \text{Bob} \times \vec{B} = - \frac{m v_{II}^2}{q B^3} \nabla B \times \vec{B} \Rightarrow$$

$$\vec{V}_D =$$

$$\vec{V}_{D\text{G}} + \vec{V}_{Dc} = - \frac{m v_{II}^2}{q B^3} \nabla B \times \vec{B}$$

$$\frac{dW_{||}}{dt} = - \frac{d(\mu B)}{dt} = - B \frac{d\mu}{dt} - \mu \frac{dB}{dt}$$

$$m \frac{dV_{||}}{dt} = - \mu \nabla_{||} B = - \mu \frac{dB}{dz}$$

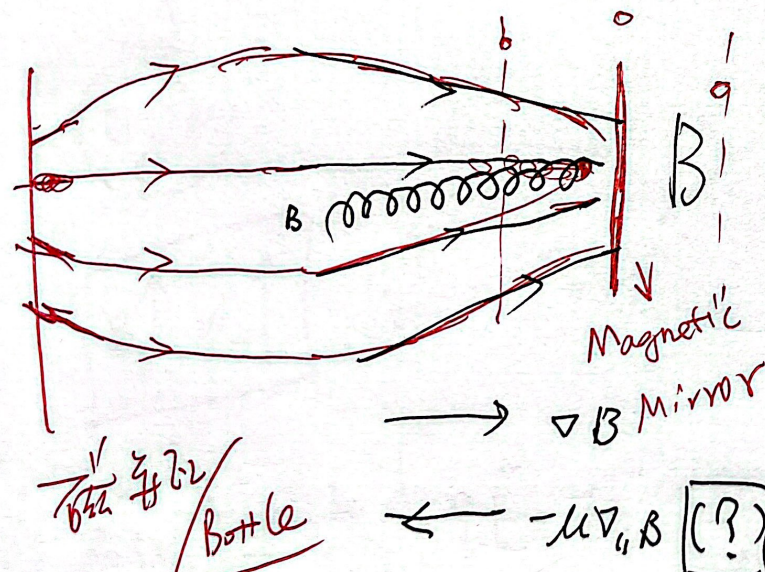
$$\frac{d}{dt}(W_{||}) = - \mu V_{||} \frac{dB}{dz}$$

$$\Rightarrow - \mu V_{||} \frac{\partial B}{\partial z} = - B \frac{d\mu}{dt} - \mu \frac{dB}{dt} \Rightarrow \frac{d\mu}{dt} = 0$$

$$\mu = \frac{W_{\perp}^2}{B}$$

Q: 有限度

$$W_{\perp \max} \sim W_0$$

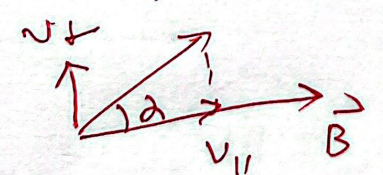


反弹点: 磁镜点

投掷角 pitch angle (α)

$$\alpha \gg \alpha_{\min} = ?$$

逃逸 / 约束条件:



$$\left. \begin{matrix} B_0 \\ B_{\max} \\ W_{||0} \\ W_{\perp 0} \end{matrix} \right\} \Rightarrow \begin{cases} W_{||0} + W_{\perp 0} = W_0 \\ \mu = \frac{W_{\perp}^2}{B} = \text{常量} \end{cases}$$

$$\frac{W_0}{B_m} = \frac{W_{\perp 0}}{B_0} \Rightarrow \frac{W_{\perp 0}}{W_0} = \frac{B_0}{B_m} \Rightarrow B_m = \left(\frac{W_{\perp 0}}{W_0}\right)^2 B_0 = B_0 / \sin^2 \alpha_0$$

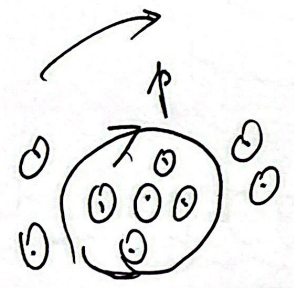
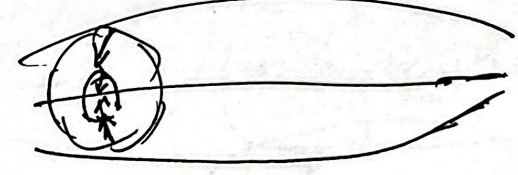
$$\sin^2 \alpha_0 \geq \frac{B_0}{B_{max}}$$

$$\alpha_0 \geq \arcsin \sqrt{\frac{B_0}{B_{max}}}$$

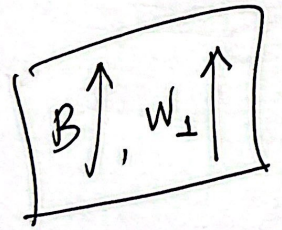
② 量变化

$$L \gg L_c, \quad \left| L_c \frac{\partial B}{\partial t} \right| \ll B$$

平行?



$$\frac{dB}{dt} = \frac{\partial B}{\partial t} + \vec{v} \cdot \nabla B$$



$$\frac{\partial \vec{B}}{\partial t} = -\nabla \times \vec{E}$$

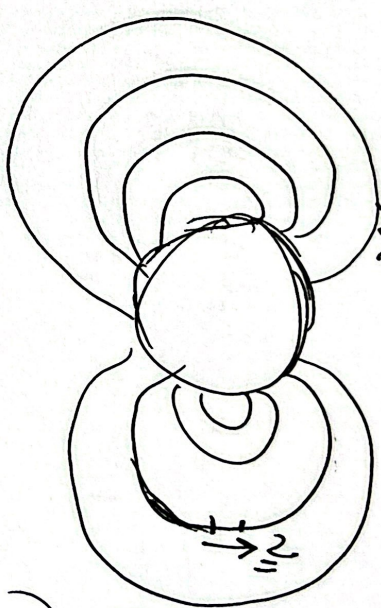
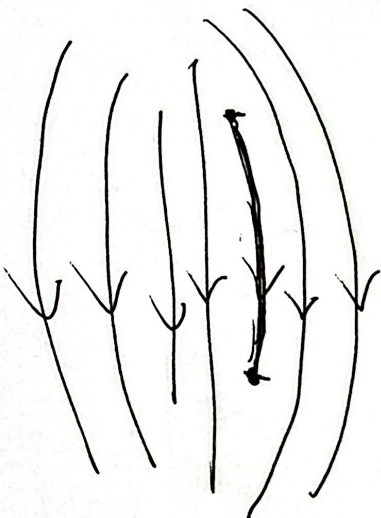
$$\frac{\Delta W_{\perp}}{\Delta t} = \frac{1}{L_c} \oint q \vec{E} \cdot d\vec{c} = \frac{q}{L_c} \oint \nabla \times \vec{E} \cdot d\vec{s} = -\frac{q}{L_c} \oint \frac{\partial B}{\partial t} \cdot d\vec{s} = +\frac{q}{L_c} S \frac{\partial B}{\partial t} = \mu \frac{\partial B}{\partial t}$$

$$W_{\perp} = \mu B, \quad \left(\frac{dW_{\perp}}{dt} \right) = \mu \frac{dB}{dt} + \left(B \frac{d\mu}{dt} \right) = \mu \frac{\partial B}{\partial t} \Rightarrow \frac{d\mu}{dt} = 0$$

$\mu = \frac{W_{\perp}}{B}$ 横向 (W_{\perp}) 不变量. 第一绝热不变量.
 Transverse Invariant. First Adiabatic Invariant.

2.2.4 纵向 (第一绝热) 不变量.

磁. 恒



$$J = \oint v_{||} ds$$

$$\frac{dJ}{dt} \Big|_{s,0}$$

- ① 回旋, ② 反弹, ③ 漂移

证: $J(\xi, s, t)$ (M字4页)

$$\xi = \mu B + \frac{m v_{||}^2}{2} \Rightarrow v_{||} = \pm \sqrt{\frac{2}{m} (\xi - \mu B)}$$

$$J(\xi, s, t) = \int_{s_1}^{s_2} \left(\frac{2}{m} (\xi - \mu B) \right) ds$$

$$\frac{dJ}{dt} = \frac{\partial J}{\partial t} \Big|_{\xi, s} + \left(\frac{\partial J}{\partial \xi} \right)_{s, t} \frac{d\xi}{dt} + \left(\frac{\partial J}{\partial s} \right)_{\xi, t} \frac{ds}{dt}$$

$$\frac{\partial J}{\partial t} \Big|_{\xi, s} = \int_{s_1}^{s_2} \left(-\frac{\mu}{m} \frac{\partial B}{\partial t} - \frac{2}{m} (\xi - \mu B) \right) ds$$

$$\left(\frac{\partial J}{\partial \xi} \right)_{s, t} = \int_{s_1}^{s_2} \frac{1}{m \sqrt{\frac{2}{m} (\xi - \mu B)}} ds$$

$$\frac{d\xi}{dt} = \frac{d(\xi_1 + \xi_2)}{dt} = \mu \frac{d \ln B}{dt} + \mu \frac{dv_{||}}{dt}$$

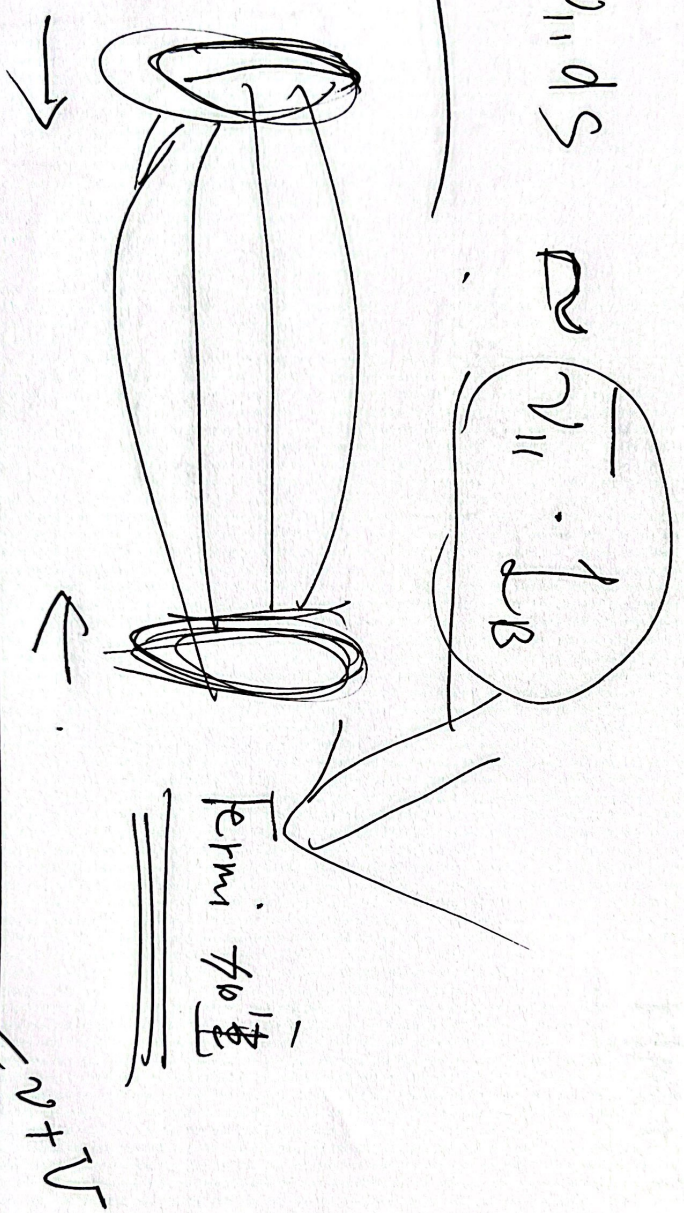
$$\frac{ds}{dt} = \frac{dv_{||}}{dt} + (v_{||} + v_D) \cdot \nabla B = \frac{dv_{||}}{dt} + v_{||} \frac{dB}{ds}$$

$$\int_A^B J ds = \underline{J(B)} - \underline{J(A)}$$

(21)

$$\Rightarrow \frac{dJ}{dt} = \int_{s_1}^{s_2} \frac{-\frac{h}{m} \frac{\partial k}{\partial x}}{v_{11}} ds + \mu \frac{\partial k}{\partial t} \int_{s_1}^{s_2} \frac{ds}{m v_{11}} \quad \text{no} \Rightarrow \underline{\text{J 是不变量}}$$

$$J = \oint v_{11} ds \quad \approx \quad \underline{v_{11} \cdot \int ds}$$



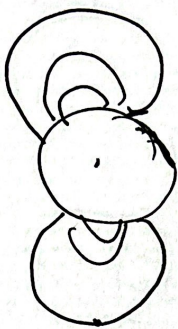
在拍子参考系中, v' \rightarrow $v' = -v - v$
 在实验室一中, v , $-v - 2V$

$$\Delta E = \frac{mv}{2} (v + 2V)^2 - \frac{mv^2}{2} = \underline{2m(vV + v^2)}$$

3) 第三绝热不变量: Φ 不变量



$$T \sim \frac{2\pi r}{v_D}$$



① M 不变量

太阳风存在延伸加热现象

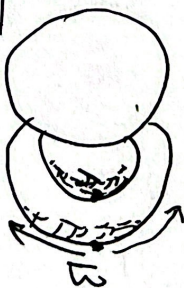
② ~~J 不变量~~

(Fermi 加速)

②



轭射带
长程存在



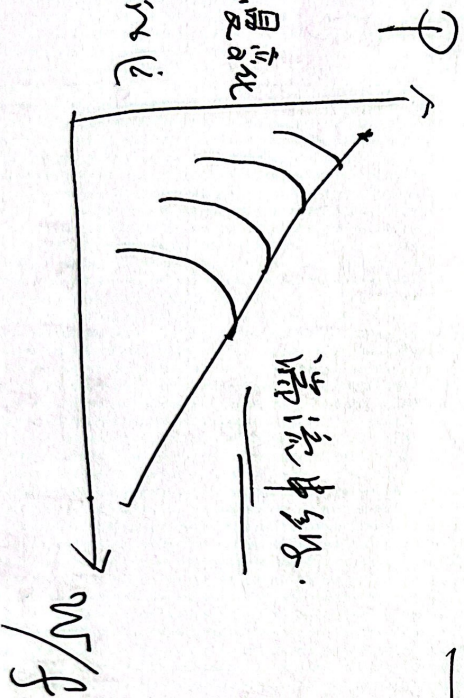
$$\vec{F} = q \langle \vec{v} \times \vec{B}_1 \rangle = -\mu \nabla B$$

$$\left. \begin{array}{l} -\mu \nabla_{||} B \\ -\mu \nabla_{\perp} B \end{array} \right\}$$

2.3

弱不均匀、小量扰动

物体中粒子的运动



湍流中运动

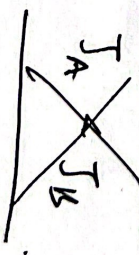
$$\vec{v}_{DF} = \frac{\vec{F} \times \vec{B}}{qB^2}$$

$$\langle q \vec{E}_2 \rangle = \langle q \frac{\vec{r}_c}{2} \cdot (\vec{r}_c \cdot \nabla) \cdot \nabla \vec{E} \rangle \sim \frac{q r_c^2}{4} \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \vec{E}$$

$$\vec{r}_c = r_c (\sin \theta \hat{e}_x + \cos \theta \hat{e}_y)$$

$$\langle \sin^2 \theta \rangle = \langle \cos^2 \theta \rangle = 1/2$$

$$v_{||A} L_A \leq v_{||B} L_B$$



$$\left. \begin{array}{l} B_A > B_B \Rightarrow L_A < L_B \\ v_{||A} > v_{||B} \Rightarrow v_{||A} < v_{||B} \end{array} \right\}$$

$$\vec{v}_0 E = \underbrace{\left(1 + \frac{v_c^2}{4} v_L^2\right)}_{\text{修正项}} \frac{\vec{E} \times \vec{B}}{B^2}$$

缓慢变化情况:

~~$$\frac{d\vec{v}}{dt} = \frac{q}{m} [\vec{E}(t) + \vec{v} \times \vec{B}]$$~~

$$\frac{d\vec{v}}{dt} = \frac{q}{m} [\vec{E}(t) + \vec{v} \times \vec{B}]$$

$$\vec{v}_{DE} = \frac{\vec{E} \times \vec{B}}{B^2}$$

$$\vec{v} = \vec{v}_c + \vec{v}_{DE}$$

$$(\vec{A} \times \vec{B}) \times \vec{B} = -A_{\perp} B^2$$

粒子受到力: $-m \frac{d\vec{v}_{DE}}{dt} \sim \vec{F}$

$$\vec{v}_{DP} = -\frac{m}{q} \frac{d\vec{v}_{DE}}{dt} \times \vec{B} = -\frac{m}{qB^2} \left(\frac{d\vec{E}}{dt} \times \vec{B} \right) \times \vec{B} = \frac{m}{qB^2} \left(\frac{d\vec{E}}{dt} \times \vec{B} \right) \times \vec{B} = \frac{m}{qB^2} \frac{d\vec{E}_{\perp}}{dt}$$

~~$$\frac{d\vec{v}_c}{dt} + \frac{d\vec{v}_{DE}}{dt} = \frac{q}{m} [\vec{E}(t) + \vec{v}_c \times \vec{B} + \vec{v}_{DE} \times \vec{B}]$$~~

$$\frac{m}{qB^2} \frac{d\vec{E}_{\perp}}{dt}$$

$$\vec{J}_p = n_p \left(\frac{M_p}{qB^2} + \frac{M_e}{qB^2} \right) \frac{d\vec{E}}{dt} = \frac{n(M_p + m_e)}{B^2} \frac{d\vec{E}}{dt} = \frac{\rho}{B^2} \frac{d\vec{E}}{dt}, \quad \text{缓慢变化}$$

$$\frac{\partial \vec{p}}{\partial t} = \vec{J}_p = \frac{\rho}{B^2} \frac{\partial \vec{E}}{\partial t} \Rightarrow \vec{p} = \frac{\rho \vec{E}}{B^2}, \quad \vec{D} = \epsilon_0 \vec{E} + \vec{p} = \left(\epsilon_0 \vec{E} + \frac{\rho}{B^2} \vec{E} \right) = \epsilon_0 \vec{E} \left(1 + \frac{\rho}{B^2 \epsilon_0} \right) = \epsilon_{eff} \vec{E}$$

带电
导体

$$\epsilon = 1 + \frac{\rho}{\epsilon_0} = 1 + \frac{\rho \mu_0}{\epsilon_0} , \quad \frac{1}{\mu_0 \epsilon_0} = c^2 \Rightarrow \epsilon = 1 + \frac{c^2}{(B^2/\mu_0 \rho)} = 1 + \frac{c^2}{v_A^2}$$



缓慢

电场无法穿入导体内部

$$v_A \ll c \Rightarrow \epsilon \gg 1$$

3.2 MHD 适用条件

单流体

大尺度、慢时标可以忽略电子质子差异，准中性

$$L \gg r_{cp}, T \gg T_{cp}, T_{wp}$$

$$L \gg \lambda_{De}, T \gg T_{wp}^{-1}$$

流体力学：成团，碰撞足够频繁。

磁流体

库仑碰撞、磁场 \rightarrow 约束/等效碰撞、异常碰撞：波粒作用

3.3 MHD 方程组

电子-质子 (e, p), 等离子体, $\alpha = e, p$.

$$\frac{\partial \rho_\alpha}{\partial t} + \nabla \cdot (\rho_\alpha \vec{v}_\alpha) = 0$$

$$\rho_\alpha \frac{d\vec{v}_\alpha}{dt} = -\nabla p_\alpha + \rho_\alpha \vec{g} + \rho_{q\alpha} (\vec{E} + \vec{v}_\alpha \times \vec{B}) + \vec{f}_{\alpha\beta}$$

$$\nabla \cdot \vec{E} = \rho_{\text{ext}} / \epsilon_0$$

$$\nabla \cdot \vec{B} = 0$$

$$\nabla \times \vec{E} = -\partial \vec{B} / \partial t$$

$$\nabla \times \vec{B} = \mu_0 \vec{j} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

$$\rho = \sum_\alpha n_\alpha q_\alpha$$

$$\vec{j} = \sum_\alpha n_\alpha q_\alpha \vec{v}_\alpha$$

$$\rho = n_e k_B T_e$$

$$\frac{\partial \rho}{\partial t} - \frac{\partial \rho}{\partial t}$$

$$0 = \mu_0 \nabla \cdot \vec{j} + \mu_0 \epsilon_0 \frac{\partial \nabla \cdot \vec{E}}{\partial t}$$

$$\Rightarrow \frac{\partial}{\partial t} (\nabla \cdot \vec{E} - \rho_{\text{ext}} / \epsilon_0) = 0$$

$$\frac{\partial(\rho_e + \rho_p)}{\partial t} + \nabla \cdot (\rho_e \vec{v}_e + \rho_p \vec{v}_p) = 0 \Rightarrow$$

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{v}) = 0$$

$$\vec{v} \cdot \vec{v}_p$$

① 质量守恒 $\rho = \rho_e + \rho_p$, $n_p = n_e = n$

$$\frac{\partial n}{\partial t} + \nabla \cdot (n \vec{v}) = 0$$

② $\rho \frac{d\vec{v}}{dt} = -\nabla(\rho_e + \rho_p) + \rho \vec{g} + \underbrace{\left[\frac{\vec{E}}{2} \rho_p + \frac{\vec{v}_p \times \vec{B}}{2} \right]}_{\rightarrow \vec{j} \times \vec{B}}$

$$\rho = \rho_e + \rho_p = n k_B T_e + n k_B T_p = 2 n k_B T$$

$$\rho \frac{d\vec{v}}{dt} = -\nabla \rho + \vec{j} \times \vec{B} + \rho \vec{g}$$

电荷守恒方程:

$$\frac{\partial \rho_q}{\partial t} + \nabla \cdot \vec{j} = 0$$

$$\vec{j} \times \vec{B} = 0$$

无电场

Force-free field

③ 安培定律:

$$\mu_0 \epsilon_0 = 1/c^2$$

$$\frac{B}{L} \sim \frac{1/E}{c^2 T} \quad \frac{B}{E} \sim \frac{T}{L} \quad c^2 = \frac{c^2}{v^2} \gg 1$$

$$\frac{E}{L} \sim \frac{B}{L} \Rightarrow \frac{E}{B} \sim \frac{L}{T} = v$$

$$\nabla \times \vec{B} = \mu_0 \vec{j}$$

无旋, 势场

$$\nabla \times \vec{B} = 0$$

$$\vec{j} \times \vec{B} = \frac{\nabla \times \vec{B}}{\mu_0} \times \vec{B} = \frac{1}{\mu_0} (\vec{B} \cdot \nabla \vec{B} - \frac{\nabla B^2}{2}) = -\nabla \left(\frac{B^2}{2\mu_0} \right) + \frac{\vec{B} \cdot \nabla \vec{B}}{\mu_0}$$

$$\frac{\epsilon_0 E^2}{2} \nabla \cdot \left[\frac{\vec{B}^2}{2\mu_0} \right]$$

$$\rho \frac{d\vec{v}}{dt} = -\nabla \left(p + \frac{B^2}{2\mu_0} \right) + \frac{\vec{B} \cdot \nabla \vec{B}}{\mu_0} + \rho \vec{g}$$

热压 磁压

$-\nabla p$: (P) 热压的平衡效果 (热压梯度力)

$$-\nabla \phi_B = -\nabla \frac{B^2}{2\mu_0} \quad B \rightarrow B \quad (\text{磁压梯度力}) \rightarrow \text{磁压}$$

$$\frac{\vec{B} \cdot \nabla \vec{B}}{\mu_0}$$

$$-\frac{\vec{R}_c}{R_c}$$

$$\frac{\vec{B} \cdot \nabla \vec{B}}{B^2}$$

磁压平衡

* 欧姆定律

$$\vec{j} = \sigma \vec{E}, \quad \vec{E} = \frac{\vec{j}}{\eta}$$

$$\rho_p \frac{d\vec{v}}{dt} = -\nabla p + e n (\vec{E} + \vec{v} \times \vec{B}) + \vec{f}_{ep}$$

电子的方程 (Text 欧姆定律):

$$m_e n \vec{E} = -\nabla p_e - e n (\vec{v} \times \vec{B}) + \vec{f}_{pe} - \rho_e \frac{d\vec{v}}{dt}$$

流体之坐标系: $\vec{j}' = \sigma \vec{E}'$

以 \vec{v} 为参考系

实验室坐标系:

~~$\vec{j} = \sigma(\vec{E} + \vec{v} \times \vec{B})$~~

$$\vec{j} = \sigma (\vec{E} + \vec{v} \times \vec{B})$$

$$\vec{E} + \vec{v} \times \vec{B} = \frac{\vec{j}}{\sigma}$$

$$\vec{E} = -\vec{v} \times \vec{B} + \frac{\vec{j}}{\sigma}, \quad \eta = \frac{1}{\sigma}$$

$$\vec{E} = -\vec{v} \times \vec{B}$$

$$\vec{E} + \vec{v} \times \vec{B} = 0$$

取理想 MHD. ($\sigma \rightarrow \infty$)

$$(\eta = 0)$$

感应方程

$$\frac{\partial \vec{B}}{\partial t} = -\nabla \times \vec{E}$$

$$\nabla \cdot \vec{B} = 0$$

$$\nabla \cdot \vec{E} = \frac{\rho_f}{\epsilon_0} \quad \checkmark$$

$$\nabla \cdot \vec{B} = 0$$

$$\frac{\partial \vec{B}}{\partial t} = -\nabla \times (-\vec{v} \times \vec{B} + \frac{\vec{j}}{\sigma})$$

$$\frac{\partial \vec{B}}{\partial t} = \nabla \times (\vec{v} \times \vec{B}) - \nabla \times (\eta \nabla \times \vec{B} / \mu_0)$$

$$= \nabla \times (\vec{v} \times \vec{B}) - \frac{\eta}{\mu_0} \nabla \times (\nabla \times \vec{B})$$

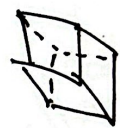
$$= \nabla \times (\vec{v} \times \vec{B}) + \frac{\eta}{\mu_0} \nabla^2 \vec{B}$$

$$\frac{\partial \vec{B}}{\partial t} = \nabla \times (\vec{v} \times \vec{B}) + \mu_m \nabla^2 \vec{B}$$

$$\Leftrightarrow \left(\frac{\partial \vec{B}}{\partial t} = -\nabla \times \vec{E}, \quad \vec{E} = -\vec{\nabla} \times \vec{A} + \nabla \psi \right)$$

MHD 方程组:

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{v}) = 0$$



$$\frac{d\rho}{dt} + \rho \nabla \cdot \vec{v} = 0$$

$$\left(\frac{d}{dt} = \frac{\partial}{\partial t} + \vec{v} \cdot \nabla \right)$$

$$\rho \frac{d\vec{v}}{dt} = -\nabla p + \vec{j} \times \vec{B} + \rho \vec{g}$$

$$p = 2nk_B T$$

$$\vec{j} = \sum n_q q \vec{v}_q \times \vec{B}$$

$$\nabla \times \vec{B} = \mu_0 \vec{j}$$

$$\frac{\partial \vec{B}}{\partial t} = -\nabla \times \vec{E} = \nabla \times (\vec{v} \times \vec{B}) + \mu_0 \nabla^2 \vec{B}$$

$$\vec{E} + \vec{v} \times \vec{B} = \frac{\vec{j}}{\sigma}$$

$$\nabla \times (\nabla \times \vec{B}) = -\nabla^2 \vec{B}$$

$$\frac{\partial}{\partial t} \left(\frac{\rho}{\gamma - 1} \right) + \nabla \cdot \left(\frac{\rho \vec{v}}{\gamma - 1} \right) + \rho \nabla \cdot \vec{v} = \frac{j^2}{\sigma}$$

$$= \frac{j^2}{\sigma}$$

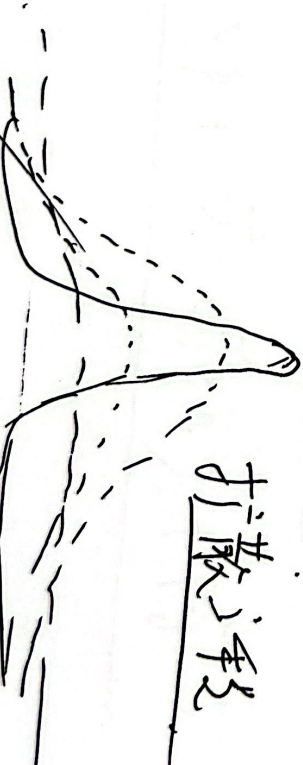
$$\frac{d}{dt} \left(\frac{\rho}{\gamma - 1} \right) = 0$$

$$p = c \rho^\gamma$$

$$\eta_m = \frac{1}{\sigma \mu_0}$$

$$\frac{\partial T}{\partial t} \propto \eta_m \nabla^2 T$$

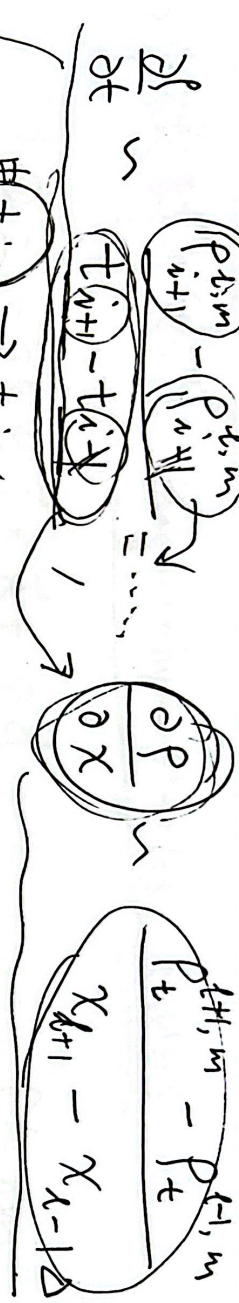
$\rho, \vec{v}, \vec{B}, p$



扩散过程

8个参数, 8个方程

$$\nabla \cdot \vec{B} = 0, \quad \nabla \cdot \vec{E} = \frac{\rho_a}{\epsilon_0}$$



$t_{i+1} \rightarrow t_{i+1}$

函数变化

1° 边界条件
2° 边界条件

$t_1 \rightarrow t_2 \rightarrow t_3 \rightarrow t_4$

$$\rho_{i+1} = \rho_i + \Delta t * (\dots)$$

$$v_x \left(v_x \frac{\partial}{\partial x} + v_y \frac{\partial}{\partial y} + v_z \frac{\partial}{\partial z} \right) v_x + v_y \left(v_x \frac{\partial}{\partial x} + v_y \frac{\partial}{\partial y} + v_z \frac{\partial}{\partial z} \right) v_y + v_z \left(v_x \frac{\partial}{\partial x} + v_y \frac{\partial}{\partial y} + v_z \frac{\partial}{\partial z} \right) v_z$$

能量密度方程: 动能 $\frac{\rho v^2}{2}$, 磁能 $\frac{B^2}{2\mu_0}$, 内能 $\frac{p}{\gamma-1}$, 热能 $\frac{\rho G M_0}{r}$

$$\rho \vec{v} \cdot d\vec{v} = \frac{\partial}{\partial t} \left(\frac{\rho v^2}{2} \right) + \nabla \cdot \left(\frac{\rho v^2}{2} \vec{v} \right)$$

$$\rho \vec{v} \cdot \left(\frac{\partial \vec{v}}{\partial t} + \vec{v} \cdot \nabla \vec{v} \right) = \rho \frac{\partial}{\partial t} \left(\frac{v^2}{2} \right) + \rho \vec{v} \cdot \left(\vec{v} \cdot \nabla \vec{v} \right)$$

$$\vec{v} \cdot \left(v_x \frac{\partial}{\partial x} + v_y \frac{\partial}{\partial y} + v_z \frac{\partial}{\partial z} \right) \vec{v}$$

3.4 磁静平衡态 Magneto hydro statics = MHS

$$0 = -\nabla p + \vec{j} \times \vec{B} + \rho \vec{g} \quad \rho = \underline{\underline{\eta_{mp}}}$$

$$\left| \frac{\rho \frac{dv}{dt}}{\mu_0 \vec{j} \times \vec{B}} \right| \sim \frac{\rho V}{T} / \frac{B^2}{\mu_0} \sim \left(\frac{LV}{T} \right) / \left(\frac{B^2}{\mu_0} \right) = \frac{V^2}{V_A^2} \ll 1 \quad v \ll v_A = \frac{B}{\mu_0 \rho}$$

§ 3.4.1 忽略重力 $-\nabla p + \vec{j} \times \vec{B} = 0 = -\nabla(p + p_B) + \frac{\vec{B} \cdot \nabla \vec{B}}{\mu_0} = 0$

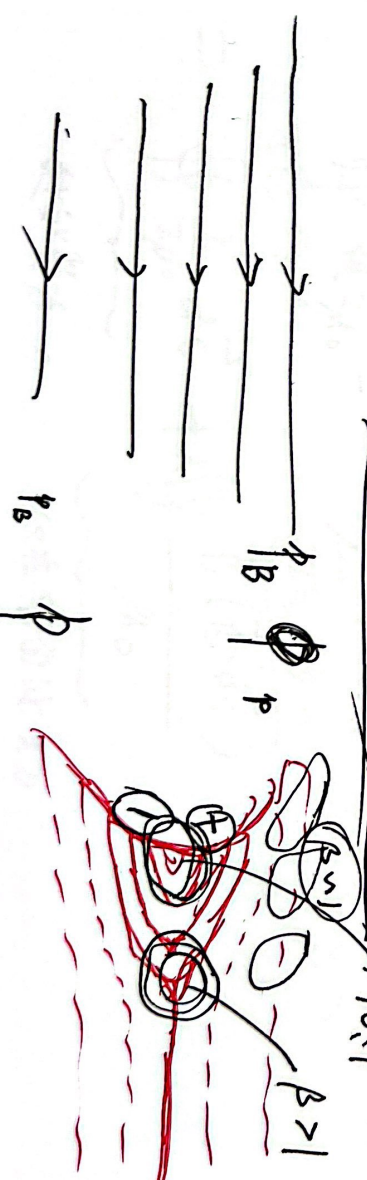
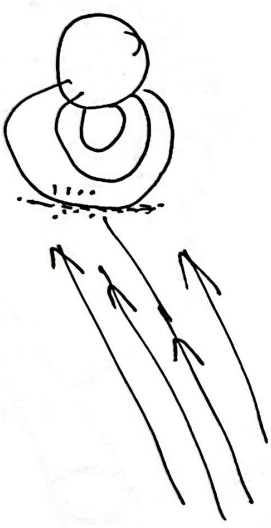
$$\frac{p/L}{\frac{B^2}{\mu_0 L}} \sim \frac{p}{\frac{B^2}{\mu_0}} = \frac{\beta}{2} \quad \beta = \frac{p}{p_B} \quad \text{等离子体压与磁压之比}$$

无量纲参数

$\beta \gg 1, \beta_{m1}, \beta \ll 1$

$p \gg p_B, p \sim p_B, p \ll p_B$
 热一, 温 $\beta \ll 1$ 冷等离子体

$-\nabla p + \vec{j} \times \vec{B} = -\nabla(p + p_B) + \frac{\vec{B} \cdot \nabla \vec{B}}{\mu_0} = 0$
 垂直的力线, $-\nabla(p + p_B) = 0$ 总压平衡



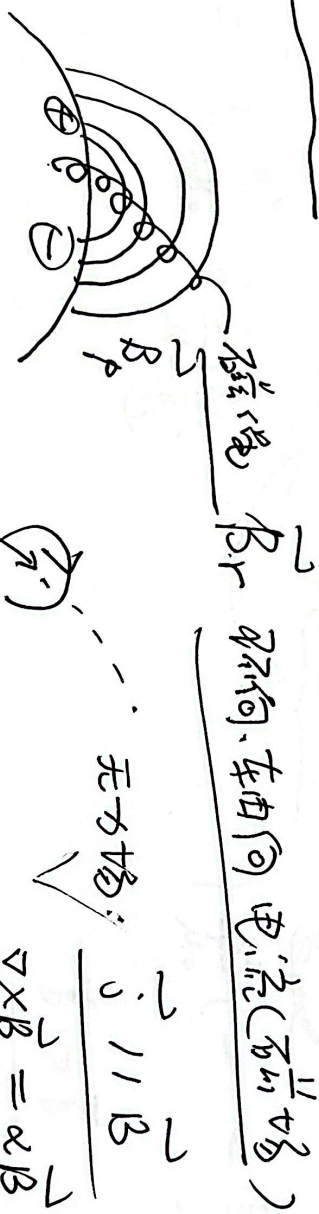
3.4.2 无场与热场

$$\vec{E} = \vec{j} \times \vec{B} \quad (\text{仅 } \beta \text{ 等离子体})$$

$$\int_{\text{vol}} -\text{grad} = 0$$

$$\sum \vec{j} \times \vec{B}_i = 0 \quad -\text{grad} \rho + \frac{\vec{B} \cdot \nabla \vec{B}}{\mu_0} = 0$$

$$\rho = -\text{grad} = 0$$



无场: $\vec{j} \parallel \vec{B}$
 $\nabla \times \vec{B} = \alpha \vec{B}$

证明: 对于无场, 有

$$\vec{M} \vec{j} = \nabla \times \vec{B}$$

$$\Rightarrow (\vec{B} \cdot \nabla) \alpha = 0$$

沿磁力线, α 是一个常数.

3.4.3 磁压力与磁张力

$$\vec{f} = -\text{grad} \rho + \frac{\vec{B} \cdot \nabla \vec{B}}{\mu_0}$$

$$-\text{grad} \cdot (\rho \vec{I} \otimes \frac{\vec{B} \vec{B}}{\mu_0})$$

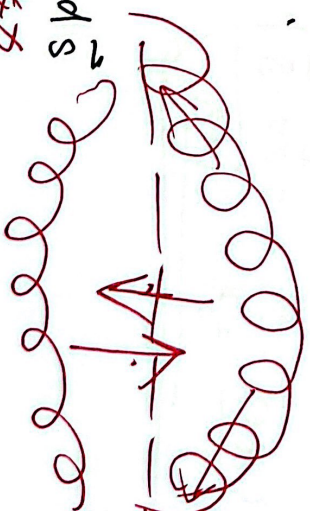
$$\nabla \times \vec{B} = 0$$



$$\oint \vec{f} \cdot d\vec{r} = - \oint \frac{\rho}{2\mu_0} \vec{I} \cdot d\vec{s} - \frac{\vec{B} \cdot \nabla \vec{B}}{\mu_0} \cdot d\vec{s}$$

$$= - \oint \frac{\rho}{2\mu_0} d\vec{s} + \oint \frac{\vec{B} \cdot d\vec{s}}{\mu_0}$$

处处受力, 仅在端面处受力.



$$\vec{f} = \vec{j} \times \vec{B} =$$

$$-\nabla \frac{B^2}{2\mu_0} + \frac{\vec{B} \cdot \nabla \vec{B}}{\mu_0} = -\nabla \frac{B^2}{2\mu_0} - \nabla \left(\frac{B^2}{2\mu_0} \right) + \frac{\vec{B} \cdot \nabla (B^2)}{\mu_0}$$

$$\vec{B} \cdot \nabla = B \frac{\partial}{\partial s}$$

$$= -\nabla \frac{B^2}{2\mu_0}$$

$$- \frac{\partial(B^2/2\mu_0)}{\partial s} s + \left(\frac{B^2}{\mu_0} \right) s$$

$$+ \frac{\partial(B^2)}{\partial s} \frac{B^2}{\mu_0}$$

$$\frac{\partial(B^2)}{\partial s}$$

$$= -\nabla \frac{B^2}{2\mu_0}$$

$$+ \frac{B^2}{\mu_0} \left(- \frac{\partial(B^2)}{\partial s} \right)$$

$$+ \frac{B^2}{\mu_0} \left(- \frac{\partial(B^2)}{\partial s} \right)$$

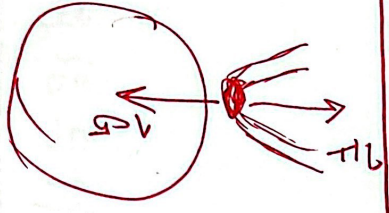
$$\frac{\partial(B^2)}{\partial s}$$

平行分量抵消

$$\vec{B} \cdot \nabla B$$

$$\frac{B^2}{\mu_0}$$

$$\vec{B} \cdot \nabla (B^2)$$

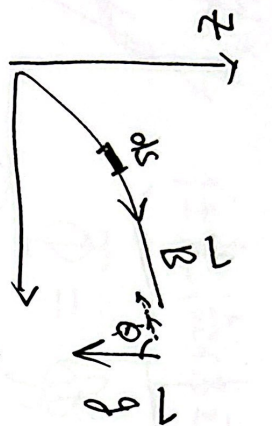


3.4.5

$$\frac{\vec{B} \cdot \nabla B}{B^2} = - \frac{R_c}{R_c^2} \quad (2.35)$$



3.4.5 重力分层大气的标高 (MHS)



$$0 = -\nabla_{||} p + \rho g_{||} = -\frac{dp}{ds} + \rho g \cos\theta$$

$$ds = \frac{dz}{\cos\theta}$$

$$p = 2n k_B T = 2 \rho_p k_B T / m_p$$

地球附近: $H \approx 5000 \text{ km} \Rightarrow H \sim 300 \text{ km}$

$$1 R_0 = 6.95 \times 10^5 \text{ km} \sim 4 \times 10^{-4} R_0$$

日冕附近: $H \sim 1 \text{ MK}, \Rightarrow H \sim 60 \text{ Mm} \sim 6 \times 10^4 \text{ km}$

$$\Rightarrow -\frac{dp}{dz} = \rho g$$

$$\Rightarrow -\frac{2k_B T}{m_p} \frac{dp}{dz} = \rho g$$

$$\Rightarrow \frac{1}{p} \frac{dp}{dz} = -\frac{m_p g}{2k_B T} \frac{1}{dz}$$

定义 $H = \frac{2k_B T}{m_p g}$

$$p = p_0 e^{-z/H}$$

$$p = p_0 e^{-z/H}$$

3.5 磁冻结与扩散

理想 (ideal) MHD: $\sigma \rightarrow \infty, \eta_{lm} = \frac{1}{\sigma \mu_0} \rightarrow 0$

$$\frac{D\vec{B}}{Dt} = -\nabla \times \vec{E} = \nabla \times (\vec{v} \times \vec{B}) + \eta_{lm} \nabla^2 \vec{B}$$

未耗散 (resistive) MHD: σ 有限, \checkmark

$$\frac{\partial \vec{B}}{\partial t} = \nabla \times (\vec{v} \times \vec{B})$$

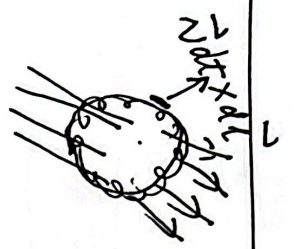
$$R_m = \frac{VB}{\Delta B} \sim \frac{VB}{\eta_{lm} B / L_B} \sim \frac{L_B V}{\eta_{lm}}$$

估计: $\frac{L_B}{V} \sim \frac{0.01 R_0}{1 \text{ km/s}} \sim 10^6 \sim 10^7 \text{ m}$
 $\eta_{lm} \sim 1 \text{ m}^2/\text{s}$
 $R_m \sim 10^{10}$

3.5.1 Alfvén

磁冻结定理

任意流体之回路中所包含的 Φ 不随时间变化。



$$\Phi = \oint \vec{B} \cdot d\vec{S}, \quad \frac{d\Phi}{dt} = 0$$

$$\frac{d}{dt} \left(\oint \vec{B} \cdot d\vec{S} \right) = \oint \frac{\partial \vec{B}}{\partial t} \cdot d\vec{S} + \oint \vec{B} \cdot (\nabla \times \vec{v}) \cdot d\vec{l}$$

$$\oint \frac{\partial \vec{B}}{\partial t} \cdot d\vec{S} + \oint \vec{B} \times \vec{v} \cdot d\vec{l} = \oint \frac{\partial \vec{B}}{\partial t} \cdot d\vec{S} + \oint (\vec{v} \times \vec{B}) \cdot d\vec{l}$$

$$= \oint \frac{\partial \vec{B}}{\partial t} \cdot d\vec{S} - \oint \nabla \times (\vec{v} \times \vec{B}) \cdot d\vec{S} = 0$$

证明:

$$\frac{d(\vec{B} \cdot \vec{v})}{dt} = \frac{\vec{B} \cdot \nabla \vec{v}}{\rho}$$

$$\frac{1}{\rho} \frac{d\vec{B}}{dt} \cdot \vec{v} - \frac{1}{\rho} \frac{d\rho}{dt} = \frac{1}{\rho} \left(\frac{\partial \vec{B}}{\partial t} + \vec{v} \cdot \nabla \vec{B} \right) - \frac{\vec{v}}{\rho} \cdot (\nabla \times \vec{v} + \nabla \rho)$$

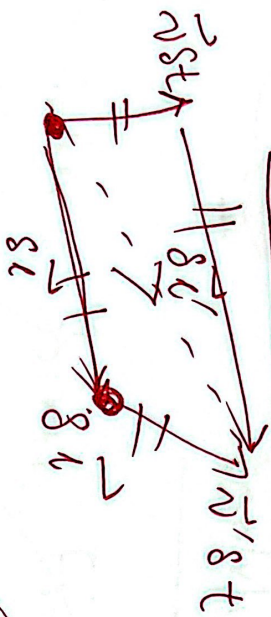
$$= \frac{1}{\rho} \left(\nabla \times (\vec{v} \times \vec{B}) + \vec{v} \cdot \nabla \vec{B} \right) + \frac{\vec{v}}{\rho} \cdot \nabla \rho = 0$$

$$\frac{\partial \vec{B}}{\partial t} + \vec{v} \cdot \nabla \vec{B} + \vec{v} \cdot \nabla \rho = 0$$





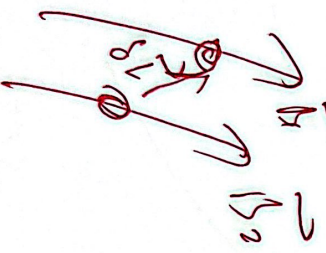
证明: $\frac{d(s_l \cdot \vec{n})}{dt} = \vec{s}_l \cdot \vec{v}$



$$\vec{s}_l + \vec{n}' dt = \vec{s}_l' + \vec{n} s_t$$

$$\frac{(\vec{s}_l' - \vec{s}_l)}{dt} = \vec{v}' - \vec{v} \equiv \vec{s}_l \cdot \vec{v}$$

如果两个流体之构线之 (s_l) , 在 $t=0$ 时, 与 \vec{B} 垂直, 则 $s_l(t)$ 与 \vec{B} 垂直



$$\frac{d(B/p)}{dt} = \vec{B} \cdot \vec{v}$$

$$\frac{d(s_l)}{dt} = \vec{s}_l \cdot \vec{v}$$

$$\left| \frac{B}{p} \right| = \alpha |s_l|$$

B/p 与 s_l 满足同样的方程

$$\frac{dA}{dt} = A \cdot \vec{v}$$

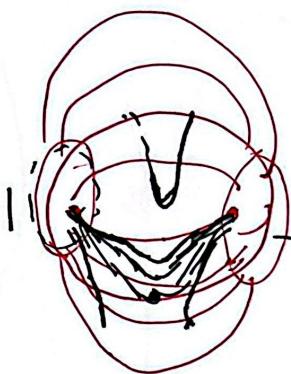
$$\frac{dC}{dt} = \vec{e} \cdot \vec{v}$$

$$A = \alpha C$$

磁场中的机械

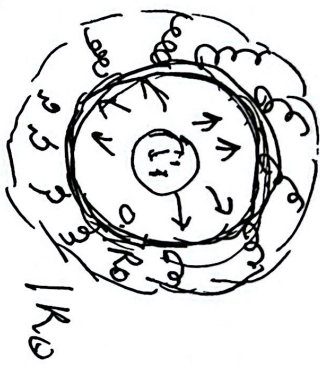
发电机效应

① 太阳发电机 (Solar Dynamo)



较差自转. $0.7 R_{\odot}$

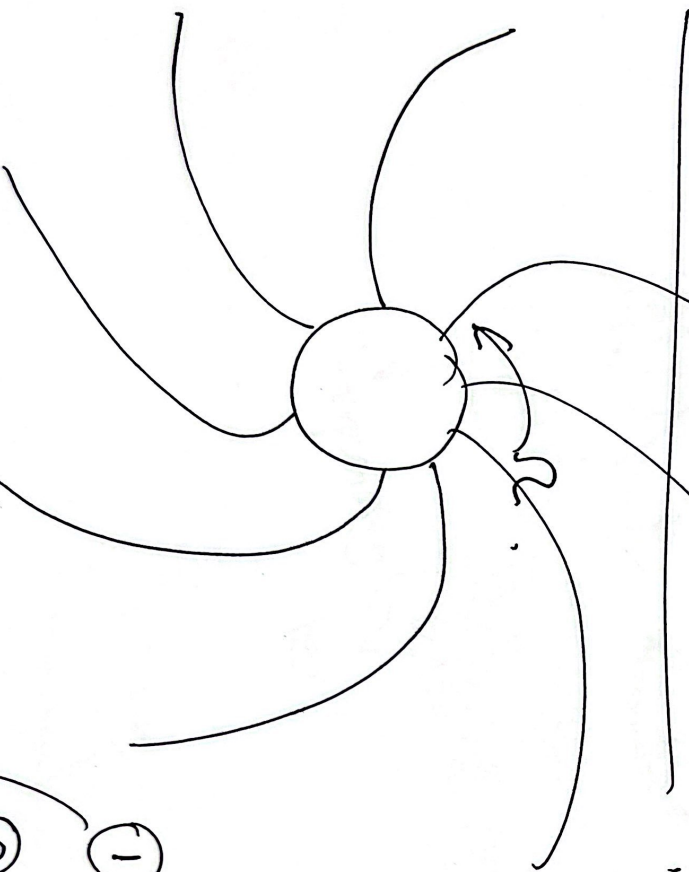
tachline layer



$$\nabla \frac{B^2}{2\mu_0} \sim \rho \frac{d\vec{v}}{dt}$$

白磁层

② Parker's Spiral Field



$$\Theta_{\text{MKS}} \leftarrow \frac{4 \times 10^5}{2.7 \times 10^{-6} \times 1.5 \times 10^{11}}$$

$$1 = c g \theta \Rightarrow$$

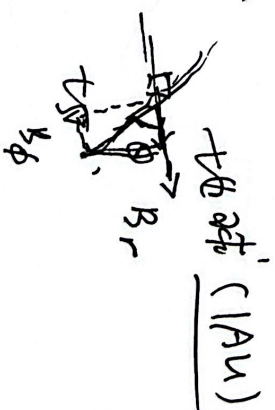
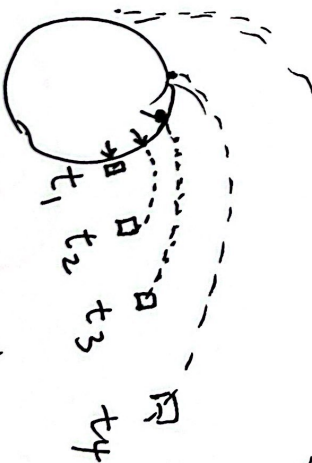
$$\frac{v_r}{v_{\phi}} = \frac{B_r}{B_{\phi}} \Rightarrow$$

$$\frac{B_r}{B_{\phi}} = \frac{v_r}{\Omega r} = \frac{400 \text{ km/s}}{2.7 \times 10^{-6} \times 1.5 \times 10^{11} \text{ m}}$$

- ① 共转轴心
- ② 空子空参考系

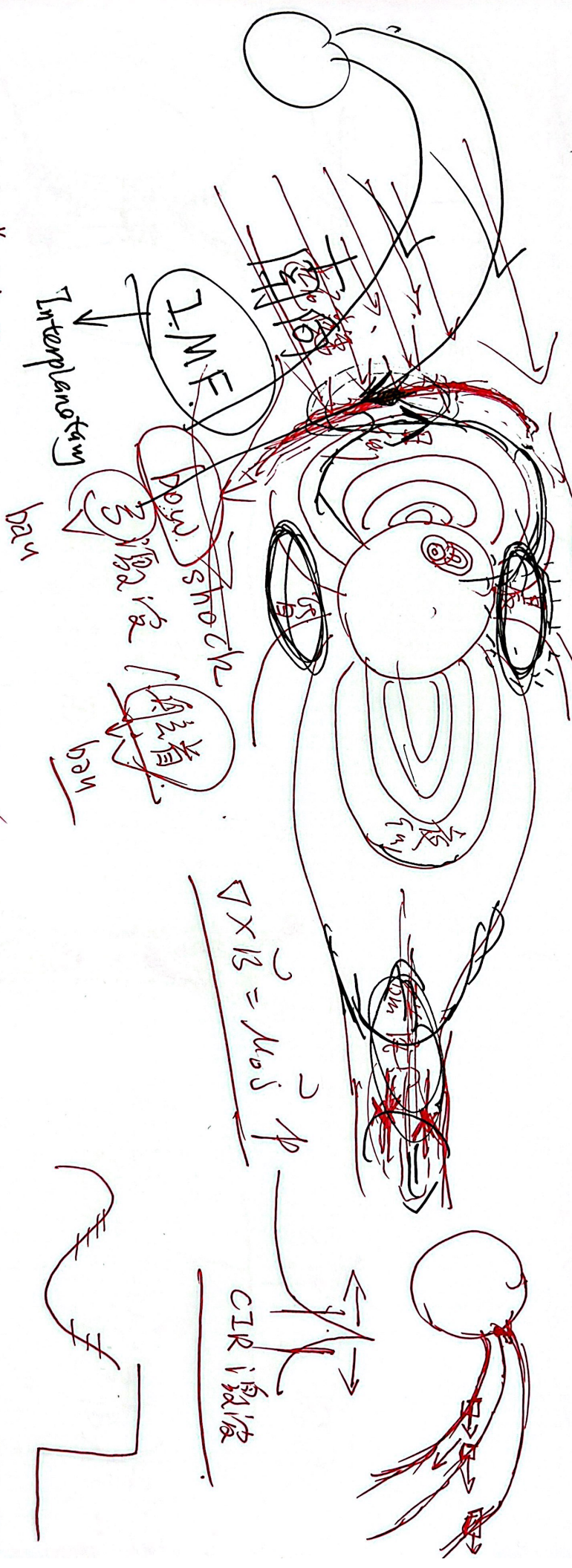
$$\vec{v}' = v_r \vec{e}_r - \Omega r \vec{e}_{\phi}, \vec{v}' \perp \vec{B}$$

$$\vec{v} = v_r \vec{e}_r \sim 400 \text{ km/s}$$



- 1) Solar Dynamo.
- 2) Parker's spiral field
- 3) CIR: 共转相互作用

4) 太阳风 - 磁层相互作用



3.5.2 磁扩散

$$\frac{\partial \mathbf{B}}{\partial t} = \nabla \times (\nu \nabla \times \mathbf{B})$$

$$\nu \sim \frac{L_m^2}{\tau}$$

$$L_B \sim \frac{v}{\omega} \sim \frac{10^6 \text{ km}}{1 \text{ s}} \sim 10^6 \text{ km}$$

扩散时间

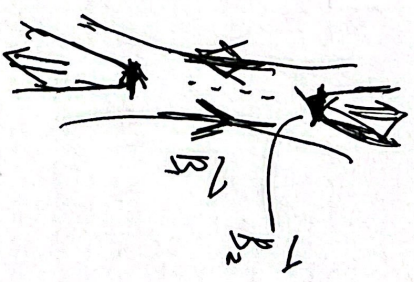
$$\tau \sim \frac{L_B^2}{\nu} \sim \frac{L_B^2}{\nu} \Rightarrow \tau_B = \frac{L_B^2}{\nu}$$

$$\tau_B \sim \frac{(10^6 \text{ km})^2}{1 \text{ s}} \sim 10^{12} \text{ s}$$

Sweet-Parker 模式 (小量, 稳态 Sweet-Parker 模式)



流入区, 流出区, 耗散区 (扩散区) 冻结条件 磁岛破坏 (magnetic flux)



重联率: reconnection rate

$$M = \frac{v_{in}}{v_{out}} = \frac{v_1}{v_2} ?$$

决定 v_1 的是: 电阻效应.

$$\tau_B = L_B^2 / \eta_m$$

$$\eta_m = \frac{1}{\mu_0 \sigma}$$

$$\tau_B = L_B^2 \mu_0 \sigma$$

① 质量守恒: $\rho_1 v_1 \delta \cdot H = \rho_2 v_2 \delta \cdot H$

②

$$v_1 \Rightarrow B_1 \delta H = B_2 \delta H \Rightarrow$$

$$\frac{B_1}{B_2} = \frac{v_1}{v_2} \Rightarrow B_2 = \frac{v_1}{v_2} B_1$$

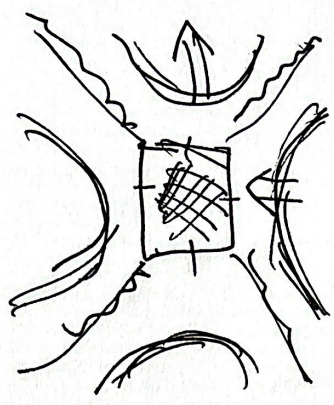
③ v_1, v_2 : $v_1 = \frac{g(\pm L_B)}{L_B^2 \mu_0 \sigma} = \frac{1}{\mu_0 \sigma \delta}$

$$\rho_1 v_1^2 \frac{\Delta}{2} \cdot \vec{j} \times \vec{B} \approx \frac{\Delta}{2} \cdot \frac{(\nabla \times B_1)}{\mu_0} \times \vec{B}_2 = \frac{\Delta}{2} \frac{B_1 B_2}{\mu_0 \sigma} = \frac{\Delta B^2 \sigma}{2 \mu_0 \sigma}$$

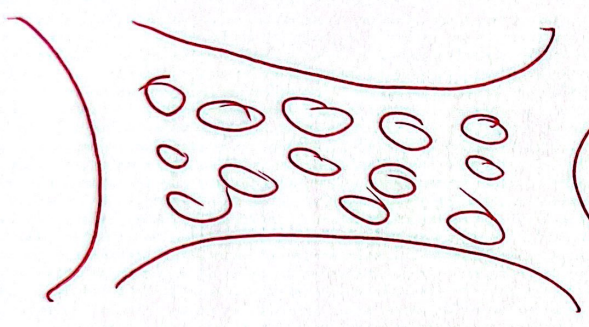
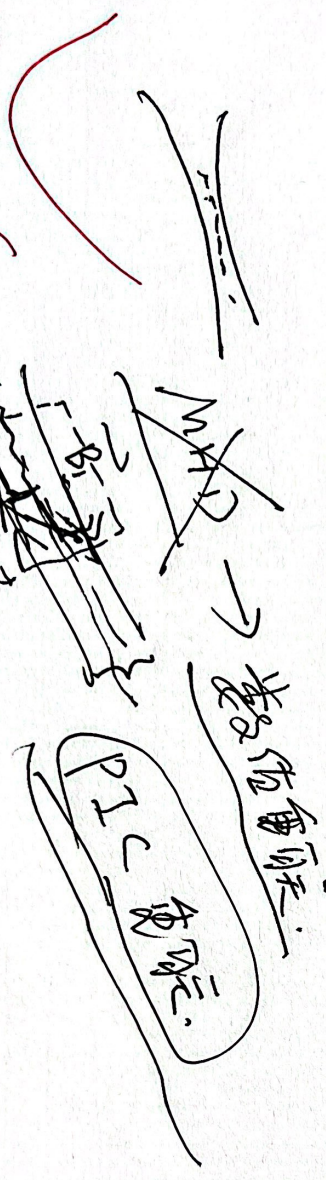
$$v_1, v_2^2 = \frac{B_1^2}{\mu_0 \sigma} = v_{A1}^2, v_2 = v_{A1}$$

$$M = \left(\frac{N_1}{N_2} \right) \left(\frac{\Delta}{\mu_0 \sigma N_1} \right) = \left(\frac{8^2}{\Delta} \right) \Rightarrow S = \sqrt{\frac{\Delta}{\mu_0 \sigma N_1}}, \quad M = \frac{S}{\Delta} = \frac{1}{\sqrt{\mu_0 \sigma N_1}}$$

$$\sqrt{\frac{1}{\mu_0 \sigma}} = 1, \quad \Delta \sim 10 \text{ km}, \quad N_1 \sim 1000 \text{ km/s}, \quad M \sim 10^{-5}$$

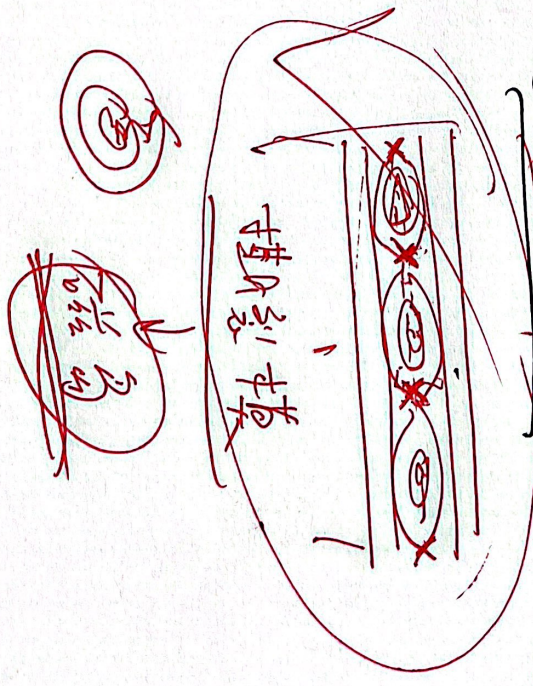


Petschek 模式



① Bz 的共振

② 自发共振 Spontaneous Res.



3.7 理想 MHD 线性化波模

8.1

3.7.1 流体与声波与真空电磁波

$$\frac{\partial p}{\partial t} + \nabla \cdot (\rho \vec{v}) = 0$$

$$\rho \frac{d\vec{v}}{dt} = \rho \left(\frac{\partial \vec{v}}{\partial t} + \vec{v} \cdot \nabla \vec{v} \right) = -\nabla p$$

$$p = c \rho^{\gamma}, \quad c = \frac{p_0}{\rho_0^{\gamma}}$$

$$p = c(\rho_0 + \rho')^{\gamma} = c \rho_0^{\gamma} + \gamma c \rho_0^{\gamma-1} \rho' + \dots$$

$$p' = \gamma c \rho_0^{\gamma-1} \rho'$$

线性化(小扰动近似),

$$\rho = \rho_0 + \rho', \quad \vec{v} \cdot \nabla \vec{v} = 0, \quad p = p_0 + p'$$

线性化处理:

$$\frac{\rho' \ll \rho_0}{(\rho_0 + \rho') \vec{v}}$$

$$p' \ll p_0$$

$$\rho' \cdot \vec{v} = 0, \quad \vec{v} \cdot \vec{v} = 0$$

$$\frac{\partial^2 p'}{\partial t^2} = c^2 \nabla^2 p'$$

$$c^2 = \frac{\gamma p_0}{\rho_0}$$

$$\Rightarrow \left\{ \begin{aligned} \frac{\partial p'}{\partial t} + \rho_0 \nabla \cdot \vec{v} &= 0 \\ \rho_0 \frac{\partial \vec{v}}{\partial t} = -\nabla p' &= -\gamma \frac{p_0}{\rho_0} \nabla p' \end{aligned} \right\}$$

$$\Rightarrow \rho_0 \frac{\partial \nabla \cdot \vec{v}}{\partial t} = -\gamma \frac{p_0}{\rho_0} \nabla^2 p'$$

$$p' \sin(\omega t + kx) \Rightarrow -\omega^2 p' = -c^2 k^2 p' \Rightarrow \boxed{w = kc}$$

$$w = \frac{2\pi}{T}, T = \frac{2\pi}{w}, f = \frac{2\pi}{T}, \lambda = \frac{2\pi}{k}$$

波动方程 $\nabla^2 \phi = \frac{\partial^2 \phi}{\partial t^2}$

$$\phi = \exp(i\vec{k} \cdot \vec{r} - i\omega t) = \sum_{\vec{k}} \phi$$

($\vec{k} \cdot \vec{r} - \omega t$) + $i \sin(\vec{k} \cdot \vec{r} - \omega t)$

$$\frac{\partial \phi}{\partial t} = -i\omega \phi, \nabla \cdot \phi = i\vec{k} \phi$$

$$\frac{\partial \phi}{\partial x} = i k_x \phi$$

FFT分析

$$-i\omega p' + i\vec{k} \cdot \vec{v} p_0 = 0$$

$$-i\omega p_0 \vec{v} = -c^2 i\vec{k} p' \Rightarrow -i\omega p_0 \vec{k} \cdot \vec{v} = -c^2 k^2 v p'$$

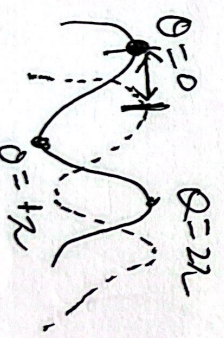
1 纵波 Longitudinal

Node

$$w^2 = k^2 c^2, w = kc$$

$$\frac{w}{k} = c, v = \frac{w}{k} = c$$

2 $\frac{p'}{p_0} = \frac{k \cdot \vec{v}}{w} = \frac{k v}{w} = \frac{v}{c}$



$$\vec{c}_s = c_s \frac{\vec{k}}{k}$$

$$\frac{\partial \vec{E}}{\partial t} = \dots$$

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

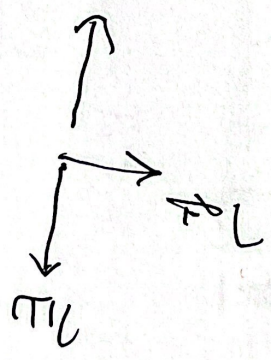
$$\vec{B} = \vec{B}_0 + \vec{B}', \quad \vec{E} = \vec{E}_0 + \vec{E}'$$

$$\nabla \times \vec{B} = \mu_0 \vec{j} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

$$\vec{k} \times \vec{E} = + \omega \vec{B} \Rightarrow \vec{k} \times (\vec{k} \times \vec{E}) = -\frac{\omega^2}{c^2} \vec{E}$$

$$\Rightarrow \omega = kc$$

$$\frac{d\omega}{dk} = c, \quad \frac{d\omega}{dk} = c$$



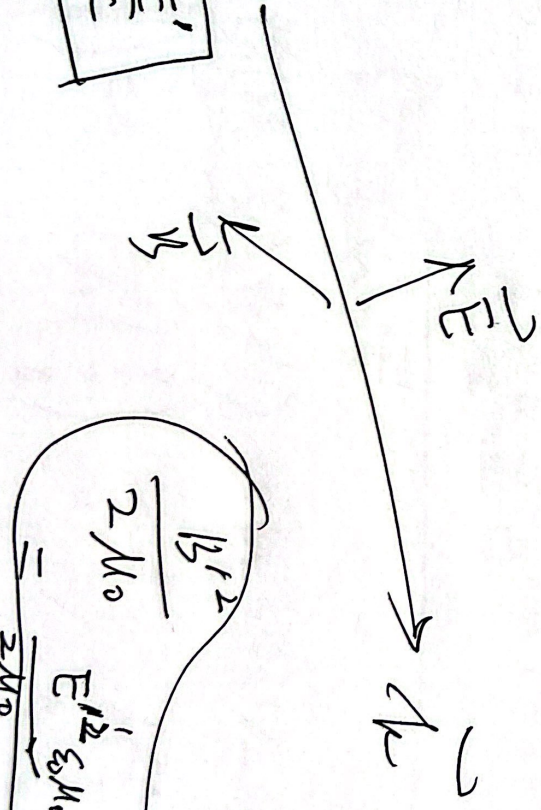
$\vec{E} \parallel \vec{k}$: 纵波

$\vec{E} \perp \vec{k}$: 横波

$$kE = \omega B$$

$$E = Bc$$

$$B' = \frac{E'}{c}$$

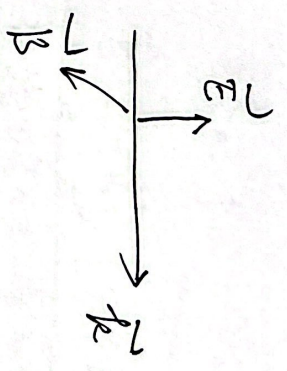


$$\frac{B'^2}{2\mu_0} = \frac{\epsilon_0 E'^2}{2}$$

$$\rho \frac{d^2 \vec{r}}{dt^2} = -\nabla \phi + \vec{j} \times \vec{r} + \rho \vec{g}$$

① $w = kc$, $c^2 = \frac{\gamma \rho_0}{\rho}$ 纵波 \vec{v}

② $\nabla \times \vec{B} = \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$
 $\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \Rightarrow w = kc$ 横波



③ 弦振动 $\vec{v} \perp \vec{k}$

$\frac{\partial^2 y}{\partial t^2} = \frac{T_0}{\rho} \frac{\partial^2 y}{\partial x^2}$

$\vec{v} = \sqrt{\frac{T_0}{\rho}}$



$$T_0 \sin \alpha_1 - T_0 \sin \alpha_2 = T_0 \tan \alpha_1 - T_0 \tan \alpha_2 = T_0 \frac{dy}{dx} \Big|_{x+dx} - T_0 \frac{dy}{dx} \Big|_x$$

$$= \rho dx \frac{d^2 y}{dt^2}$$

3.7.2 证明

① 寻找小扰动方程(线性化)对应的波动解, $A = \sum_{\vec{k}} \vec{A}_{\vec{k}} e^{i\vec{k} \cdot \vec{r} - i\omega t}$

背景知识, $\frac{\partial}{\partial t} \sim -i\omega$, $\nabla \sim i\vec{k}$

线性化后的方程组: 一阶(线性)齐次. 代入方程组.

$$\begin{pmatrix} \dots \\ \dots \\ \dots \end{pmatrix} = 0 \Rightarrow \vec{A} \begin{pmatrix} \dots \\ \dots \\ \dots \end{pmatrix} = 0 \Rightarrow \det(\vec{A}) = 0$$

3-7.3 自由场 Alfvén 波

① 小扰动近似

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{v}) = 0$$

$$\rho \frac{d\vec{v}}{dt} = -\nabla p + \vec{j} \times \vec{B} = -\nabla(\rho + p) + \frac{\vec{k} \cdot \nabla \vec{B}}{\mu_0}$$

$$\frac{\partial \vec{B}}{\partial t} = \nabla \times (\vec{v} \times \vec{B}), \quad \nabla \cdot \vec{B} = 0$$

$$\rho = (\rho, p)$$

$$\frac{d\vec{v}}{dt} = \frac{\partial \vec{v}}{\partial t} + \vec{v} \cdot \nabla \vec{v}$$

$$\rho_B = \frac{B^2}{2\mu_0} = \frac{(\vec{B}_0 + \vec{v}')^2}{2\mu_0} = \frac{B_0}{2\mu_0} + \frac{\rho_{B_0} \cdot \vec{B}'}{\mu_0} + \frac{(\vec{v}')^2}{2\mu_0}$$

③ $A = \sum_{\vec{k}} \vec{v} \cdot \vec{r} - i\omega t$

$$-i\omega \rho' + \vec{k} \cdot \nabla \rho_0 = 0$$

$$-i\omega \rho_0 \vec{v}' = -i c_s^2 \vec{k} \rho' - \vec{k} \cdot \frac{\rho_{B_0} \cdot \vec{v}'}{\mu_0} + \frac{i \vec{B}_0 \cdot \vec{k}}{\mu_0} \rho'$$

$$-i\omega \vec{B}' = \vec{k} \times (\vec{v}' \times \vec{B}_0), \quad \vec{k} \cdot \vec{B}' = 0$$

$$B_0 \cdot \rho_0 \cdot \nu_0 = 0, \quad \vec{E}_0 = 0, \quad \rho_0$$

$$\vec{B} = \vec{B}_0 + \vec{B}', \quad \rho = \rho_0 + \rho', \quad \nu, \vec{E}, \rho = \rho_0 + \rho'$$

② 线性化方程组

$$\frac{\partial \rho'}{\partial t} + \rho_0 \nabla \cdot \vec{v}' = 0$$

$$\rho_0 \frac{\partial \vec{v}'}{\partial t} = -c_s^2 \nabla \rho' - \nabla \left(\frac{\rho_{B_0} \cdot \vec{B}'}{\mu_0} + \frac{\rho_{B_0} \cdot \vec{v}'}{\mu_0} \right)$$

$$\frac{\partial \vec{B}'}{\partial t} = \nabla \times (\vec{v}' \times \vec{B}_0), \quad \vec{k} \cdot \vec{B}' = 0$$

消之, $\rho', B_0 \cdot B', B_0 \cdot B', \text{ 保留 } \vec{k} \cdot \vec{v}$.

① $\vec{k} \cdot \vec{v} = 0$, ② $\vec{k} \cdot \vec{v} \neq 0$

$\rho' = 0, \vec{k} \cdot \vec{B}' = 0$

$B_0 \cdot \vec{B}' = 0$



$\text{沿 } B_0 \text{ 方向 } \Rightarrow \vec{v} \cdot \vec{B}_0 = 0$

$\rho' = \frac{\vec{k} \cdot \vec{v}}{w}$

$-i\omega \vec{B}' = i(\vec{k} \cdot \vec{B}_0 \vec{v} - \vec{k} \cdot \vec{v} \vec{B}_0)$

$\vec{B}_0 \Rightarrow (\vec{k} \cdot \vec{B}_0)(\vec{v} \cdot \vec{B}_0) = 0$

$\rho' = 0 \rightarrow \text{不可压}$

$\vec{v} \perp \vec{B}' , \vec{v} \perp (\vec{k}, \vec{B}_0) \Rightarrow \vec{B}' \perp (\vec{k}, \vec{B}_0)$

$-i\omega \rho_0 \vec{v} = \frac{i\vec{B}_0 \cdot \vec{k}}{\mu_0} \vec{B}'$

$-i\omega \vec{B}' = i\vec{k} \cdot \vec{B}_0 \vec{v}$

$-i\omega \vec{B}' = i\vec{k} \cdot \vec{B}_0 \vec{v} = \frac{i\vec{B}_0 \cdot \vec{k}}{\mu_0} \vec{B}'$

$-i\omega \rho_0$

$\Rightarrow \omega^2 \vec{B}' = \frac{(\vec{k} \cdot \vec{B}_0)^2}{\rho_0 \mu_0} \vec{B}'$

剪切 Alfvén 波

$w = k \cdot \vec{v}_A$

Shear Alfvén wave

$= k_{\parallel} v_A = k v_A \cos \theta$

$\Rightarrow \omega^2 = \left(\frac{\vec{k} \cdot \vec{B}_0}{\mu_0 \rho_0} \right)^2$

$\Rightarrow \omega^2 = (\vec{k} \cdot \vec{v}_A)^2 \Rightarrow \vec{v}_A = \frac{\vec{B}_0}{\sqrt{\mu_0 \rho_0}}$

不可压剪切 Alfvén 波, $\omega = k v_A \cos \theta$, $(\vec{v}, \vec{B}') \perp (\vec{k}, \vec{B}_0)$

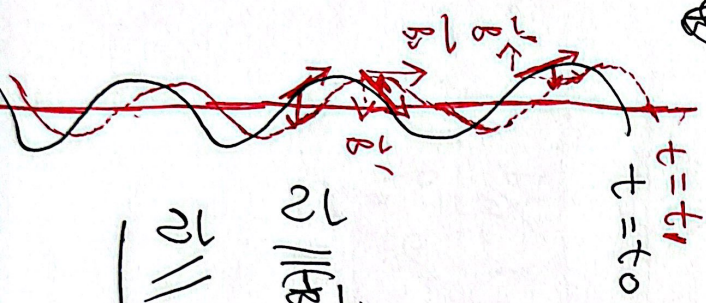
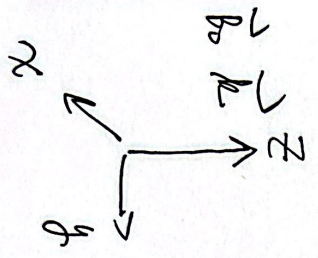
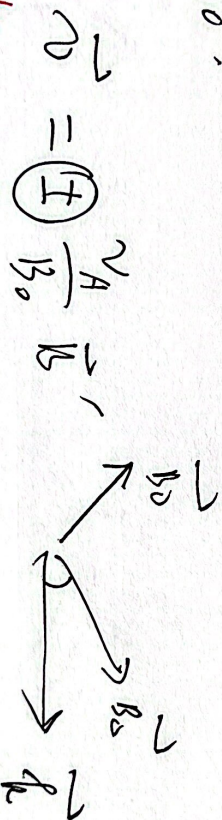
$$-\omega \rho_0 \vec{v} = \frac{B_0 \cdot \vec{k}}{\mu_0} \vec{B}' \Rightarrow -k v_A \vec{v} = \frac{B_0 \cdot \vec{k}}{\rho_0 \mu_0} \vec{B}'$$

$$\left| \frac{\vec{v}}{v_A} \right| = \frac{B_0 \cos \theta}{\sqrt{\mu_0 \rho_0}} = \frac{v_A}{B_0}$$

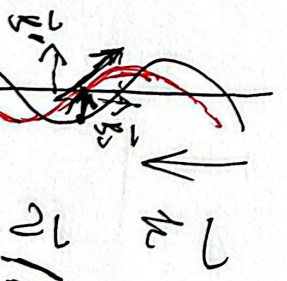
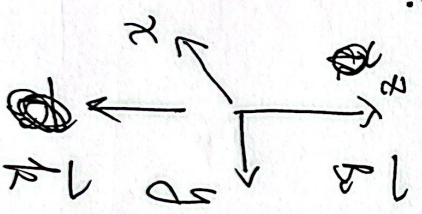
$$\left| \frac{\vec{v}}{v_A} \right| = \left| \frac{\vec{B}}{B_0} \right|$$

$$\frac{P'}{\rho_0} = -\frac{v}{c_s}$$

$$v_A = \frac{b_0}{\sqrt{\mu_0 \rho_0}}$$

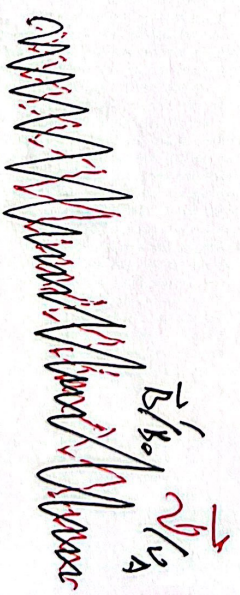


$$\vec{v} \parallel (\vec{k}') \quad \vec{v} \parallel \vec{B}'$$



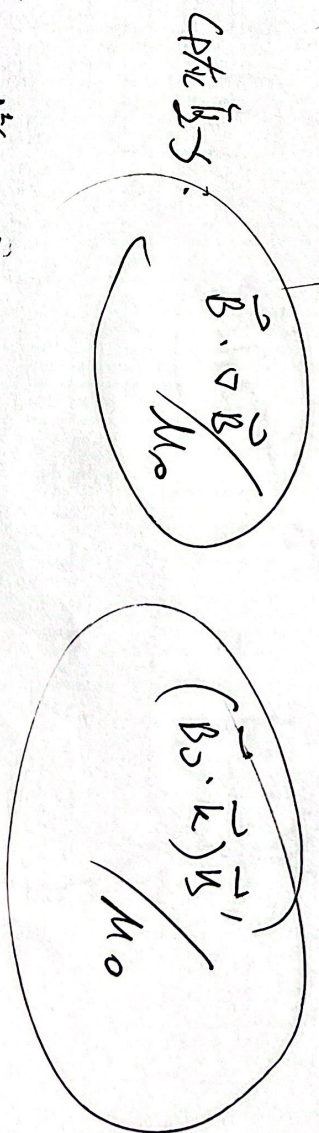
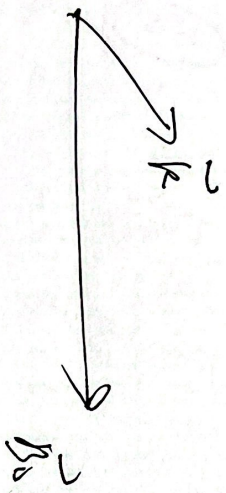
$$\vec{v} \parallel \vec{B}'$$

$$\vec{v} = -\frac{v_A}{b_0} \text{sign}(\vec{k} \cdot \vec{B}_0)$$

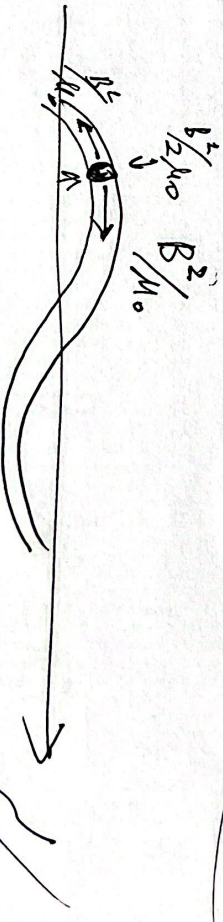


相速度 $v_p = \frac{\omega}{k} = v_A \cos \theta$, $v_g = \frac{d\omega}{dk_{\parallel}} e_z = v_A \sin \theta \hat{k}$

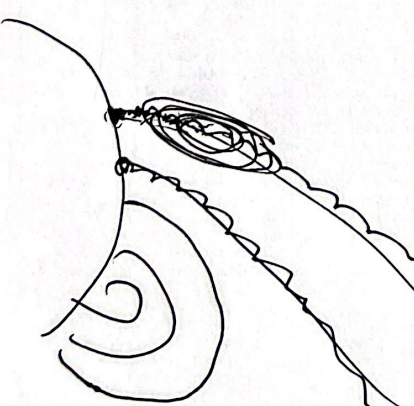
① $p' = 0, (\vec{B}, \vec{v}) \perp (\vec{k}, \vec{B}_0)$, $\left| \frac{\vec{v}}{v_A} \right| = \left| \frac{\vec{B}'}{B_0} \right|$, $\omega = k_{\parallel} v_A = k v_A \cos \theta$



$$v = \sqrt{\frac{T}{\rho}}$$



$$= \sqrt{\frac{B_0^2 / \mu_0 \cdot \rho}{\rho_0 \rho}} = \sqrt{\frac{B_0}{\mu_0 \rho_0}} = v_A$$



3.1.4 可压缩 MHD 波

① $\vec{k} \cdot \vec{v} = 0$ ($\rho' = 0$); ② $\vec{k} \cdot \vec{v} \neq 0$ ($\rho' \neq 0$), ?

剪切 Alfvén 波

$\rho_s^2 = 0$ (冷等离子体)

$\rho \frac{d\vec{v}}{dt} = -\nabla p_B + \frac{\vec{B} \cdot \nabla \vec{B}}{\mu_0}$

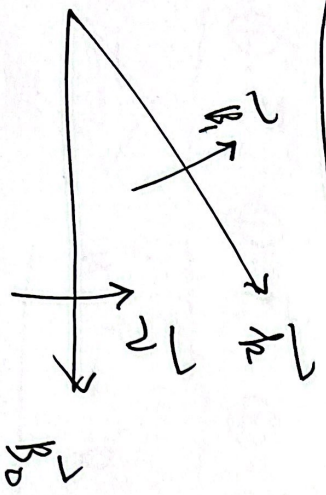
① $-i\omega \rho_0 \vec{v} = -i\vec{k} \cdot \vec{B}' + \frac{i\vec{B}_0 \cdot \vec{k}}{\mu_0} \vec{v} + \frac{i\vec{k} \cdot \vec{B}_0}{\mu_0} \vec{v}$

② $-i\omega \vec{B}_1 = -i\vec{k} \cdot \vec{B}' + i(\vec{B}_0 \cdot \vec{k}) \vec{v}$

共面定理: 15 年. (考虑热运动时成立)

$\frac{\partial \rho'}{\partial t} + \nabla \cdot (\rho \vec{v}) = 0$

$-i\omega \rho' + i\vec{k} \cdot \rho_0 \vec{v} = 0$



$\vec{k} \perp \vec{B}_0$

① $\vec{k} \Rightarrow -i\omega \rho_0 \vec{k} \cdot \vec{v} = -i\vec{k} \cdot \frac{\vec{B}_0 \cdot \vec{B}_1}{\mu_0}$

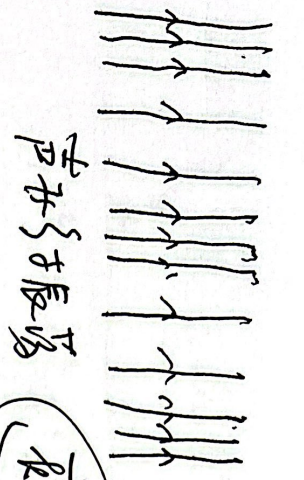
② $\vec{B}_0 \Rightarrow -i\omega \vec{B}_1 \cdot \vec{B}_0 = -i\vec{k} \cdot \vec{B}_0 \vec{k} \cdot \vec{v} \Rightarrow \omega \rho_0 \vec{k} \cdot \vec{v} = k^2 \frac{B_0^2}{\mu_0} \vec{k} \cdot \vec{v}$

Compressible Alfvén wave: 可压缩 Alfvén (阿尔芬-阿尔文) 波

恢复力 (restoring force): 磁压力 (\vec{k}) + 磁张力

剪切: 不可压缩 Alfvén 波

$\omega^2 = k^2 v_A^2$
 $\omega = k v_A$



(垂直传播) → 纵波
 疏密变化 $\vec{v} \parallel \vec{B}$

压缩作用:

$$\vec{E} = -\vec{v} \times \vec{B}_0$$

$\vec{v} \neq 0$

(2) $\vec{k} \cdot \vec{v} \neq 0$ ($\rho' \neq 0$), $c_s^2 \neq 0$

声波 ($-\nabla p$) + 可压 Alfvén 波 ($\vec{j} \times \vec{B}$) 的耦合 = 磁声波

<1> 基元定理 ✓ <2> 推号 $\omega = \omega(\vec{k})$

Magnetosonic Wave

- ①. $\vec{k} \cdot \vec{v} = 0$, ②. $\vec{k} \cdot \vec{B}_0 = 0$
- ①. $\vec{k} \cdot \vec{B}_0 = 0$, ②. $\vec{k} \cdot \vec{v} = 0$
- ①. $\vec{k} \cdot \vec{v} = 0$, ②. $\vec{k} \cdot \vec{B}_0 = 0$
- ①. $\vec{k} \cdot \vec{B}_0 = 0$, ②. $\vec{k} \cdot \vec{v} = 0$

$$\omega^4 - k^2 \omega^2 (c_s^2 + v_A^2) + k^2 c_s^2 (\vec{k} \cdot \vec{v}_A)^2 = 0 \quad \Rightarrow \quad \omega^2 = \frac{k^2}{2} \left[(c_s^2 + v_A^2) \pm \sqrt{(c_s^2 + v_A^2)^2 - 4c_s^2 v_A^2 \cos^2 \theta} \right]$$

$$\omega_p^2 = \left(\frac{\omega}{k}\right)^2 = \frac{(c_s^2 + v_A^2) \pm \sqrt{(c_s^2 + v_A^2)^2 - 4c_s^2 v_A^2 \cos^2 \theta}}{2}$$

快磁声波 Fast Magnetosonic wave (Fast wave/mode)

慢磁声波

快波? $-\vec{v} \cdot \vec{k} \rho, c_s^2 - \vec{v} \cdot \vec{k} \frac{\vec{B}_0 \cdot \vec{B}_0}{\mu_0}$

$$\frac{\rho_1}{\rho_0} = \frac{k \cdot \vec{v}}{\omega}$$

$$\vec{k} \cdot \vec{k} \Rightarrow -i\omega \int_0^{\vec{k} \cdot \vec{v}} = -i\omega k^2 \frac{\vec{B}_0 \cdot \vec{B}_0}{\mu_0} - i\omega k^2 \frac{\vec{k} \cdot \vec{v} \cdot \vec{v}}{\rho_0}$$

$$\frac{1}{\omega^2} \frac{P_1}{\rho} = \frac{1}{\rho} k^2 \frac{B_0 \cdot \vec{v}}{M_0} + \frac{1}{\rho} k^2 c^2 \rho P_1 \Rightarrow P_1 (\omega^2 - k^2 c^2) = k^2 \frac{B_0 \cdot \vec{v}}{M_0}$$

$$\left\{ \begin{array}{l} \omega^2 > k^2 c^2, \quad \text{同向波 (热压力与磁压力)} \\ \omega^2 < k^2 c^2, \quad k \end{array} \right.$$

分析 F, S 波色散关系:

$$F: \quad \theta = 0^\circ \text{ 时}, \quad \mathcal{N}_{PF \min}^2 = \frac{c^2 + v_A^2 + \sqrt{(c^2 - v_A^2)^2}}{2}$$

$$\theta = 90^\circ \text{ 时}, \quad = \frac{c^2 + v_A^2 + |c^2 - v_A^2|}{2}$$

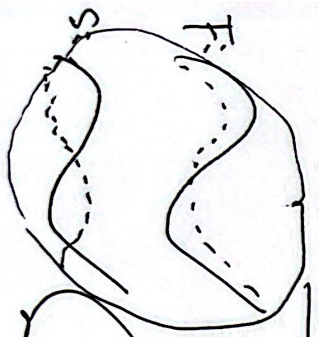
$$= \begin{cases} c^2 & c^2 \geq v_A^2 \\ v_A^2 & c^2 < v_A^2 \end{cases}$$

$$F: \quad \max(c^2, v_A^2) \leq \mathcal{N}_{PF}^2 \leq c^2 + v_A^2$$

S: $\theta = 0^\circ \text{ 时},$

$$\mathcal{N}_{PS \max}^2 = \min(c^2, v_A^2)$$

$$\theta = 90^\circ \text{ 时}, \quad \mathcal{N}_{PS \min}^2 = 0, \quad (\text{不传播}) = \min(c^2, v_A^2)$$



$$0 \leq \mathcal{N}_{PS}^2 \leq \min(c^2, v_A^2) \leq \max(c^2, v_A^2) \leq \mathcal{N}_{PF}^2 \leq c^2 + v_A^2$$

$$\vec{v}_p = \frac{v}{k} \vec{k}$$

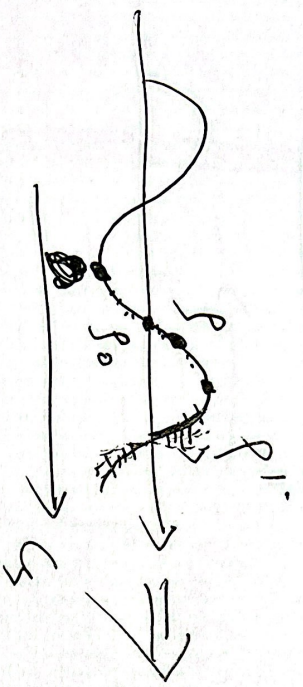
$$v_{p||} = \frac{v}{k} \cos \theta$$

$$v_{p\perp} = \frac{v}{k} \sin \theta$$

群速度：快波基本各向同性；慢波基本与 \vec{k}_0 平行，Alfvén 波与 \vec{k}_0 平行。

3.8 MHD 激波

3.8.1. 流体动力学激波



随机效应: (-维声速)

$$\frac{\rho'}{\rho_0} = \frac{v'}{c_{s0}}$$

$$c_{s0} = \frac{\gamma p_0}{\rho_0}$$

$$s' = \nu + c_s = \frac{2}{\gamma-1} (c_s - c_{s0}) + c_s$$

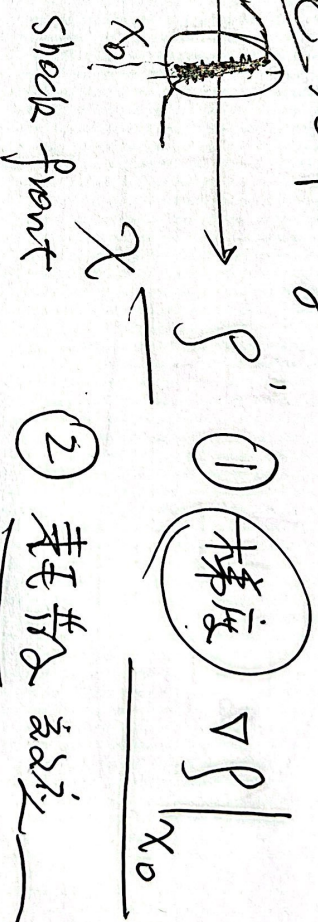
$$= c_{s0} \left[1 + \frac{\gamma+1}{\gamma-1} \left[\left(\frac{\rho}{\rho_0} \right)^{\frac{\gamma-1}{2}} - 1 \right] \right]$$

压缩区 $c_s' >$ 稀疏区 $c_s' \Rightarrow$

随机

非线性效应

Shock steepening



② 耗散效应

Shock

$$\frac{\delta \rho}{\rho} = \frac{\delta v}{c_s}$$

$$c_s^2 = \frac{\gamma p}{\rho}$$

$$\nu = \int_{\rho_0}^{\rho} \frac{c_s}{\rho} \delta \rho$$

$$p = p_0, \nu = 0$$

$$c_s^2 = \frac{\gamma p}{\rho} = c_{s0}^2 \left(\frac{p}{p_0} \right)^{\gamma-1}$$

$$c_{s0}^2 = \frac{\gamma p_0}{\rho_0}$$

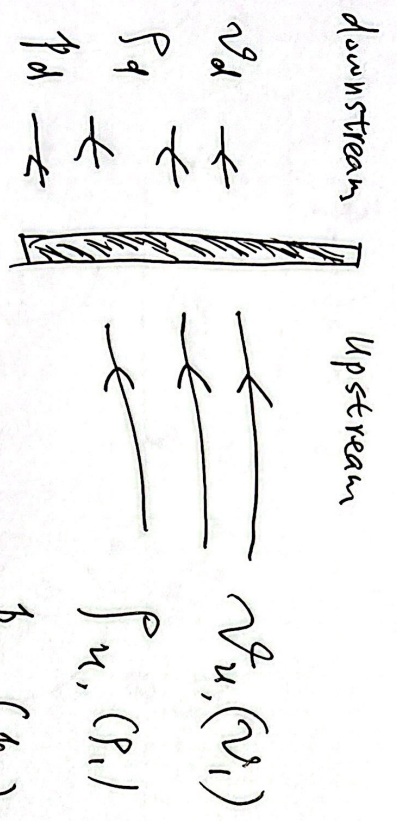
$$p = c_s^{\frac{2}{\gamma-1}}$$

$$= \left(\frac{\gamma p_0}{\rho_0} \right)^{\frac{2}{\gamma-1}} \left(\frac{\rho}{\rho_0} \right)^{\gamma-1}$$

$$\nu = \int_{\rho_0}^{\rho} c_{s0} \left(\frac{p}{p_0} \right)^{\frac{\gamma-1}{2}} \rho^{-1} d\rho$$

$$= \frac{2}{\gamma-1} \frac{c_{s0}}{\rho_0^{\frac{\gamma-1}{2}}} \rho^{\frac{\gamma-1}{2}} \Big|_{\rho_0}^{\rho} = \frac{2}{\gamma-1} (c_s - c_{s0})$$

3.8.2 流体中的激波 RH 跳跃关系 (jump conditions)



$$\left(\frac{\rho_d}{\rho_u}, \frac{v_d}{v_u}, \frac{p_d}{p_u}, \frac{T_d}{T_u} \right)$$

Shock frame

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{v}) = 0$$

$$\rho \left(\frac{\partial \vec{v}}{\partial t} + \vec{v} \cdot \nabla \vec{v} \right) = -\nabla p \Rightarrow \frac{\partial (\rho \vec{v})}{\partial t} + \nabla \cdot (\rho \vec{v} \vec{v}) + \nabla \cdot (p \vec{I}) = 0$$

$$\frac{\partial}{\partial t} \left[\rho \left(z + \frac{v^2}{2} \right) \right] + \nabla \cdot \left[\rho \left(z + \frac{v^2}{2} \right) \vec{v} \right] = -\nabla \cdot (p \vec{v}) \Rightarrow$$

$$\int \rho \vec{v} \cdot \vec{n} \Big|_u = \int \rho \vec{v} \cdot \vec{n} \Big|_d \Rightarrow \int \rho v_n \Big|_u = \int \rho v_n \Big|_d = 0$$

$$\int \rho \vec{v} \cdot \vec{n} + p \vec{n} \Big|_u = 0 \Rightarrow \int \rho v^2 + p \Big|_u = 0$$

$$\int \rho \left(z + \frac{v^2}{2} \right) \vec{v} + p \vec{n} \Big|_u = 0 \Rightarrow \int \rho \left(z + \frac{v^2}{2} \right) \vec{v} + p \vec{n} \Big|_u = 0$$

$$\rho \rho v + p = \rho \rho v + \frac{p}{\gamma - 1}$$

$$0 = \rho v + \frac{p}{\gamma - 1}$$

$$\int \rho \vec{v} \cdot \vec{n} + p \vec{n} \Big|_u = 0 \Rightarrow \int \rho v^2 + p \Big|_u = 0$$

$$\int \rho \vec{v} \cdot \vec{n} + p \vec{n} \Big|_u = 0 \Rightarrow \int \rho v^2 + p \Big|_u = 0$$

$$\int \rho \vec{v} \cdot \vec{n} + p \vec{n} \Big|_u = 0 \Rightarrow \int \rho v^2 + p \Big|_u = 0$$

$$\textcircled{1} \rho_u v_u = \rho_d v_d$$

$$\textcircled{2} \rho_u v_u^2 + p_u = \rho_d v_d^2 + p_d$$

$$\textcircled{3} \rho_u v_u^3 + \dots = \frac{\gamma}{\gamma-1} \frac{p_u \rho_u}{\rho_u} = \frac{\rho_d v_d^3}{z} + \frac{\gamma}{\gamma-1} \frac{p_d \rho_d}{\rho_d}$$

$$\textcircled{2}' \quad 1 + \frac{p_u}{\rho_u v_u^2} = \frac{1}{X} + \frac{p_d}{\rho_u v_u^2} \Rightarrow 1 + \frac{1}{\gamma M^2} = \frac{1}{X} + \frac{p_d}{\rho_u} \frac{1}{\rho_u M^2}$$

$$\textcircled{3}' \quad \frac{v_u^2}{z} + \frac{\gamma}{\gamma-1} \frac{p_u}{\rho_u} = \frac{v_d^2}{z} + \frac{\gamma}{\gamma-1} \frac{p_d}{\rho_d} \Rightarrow 1 + \frac{\gamma}{\gamma-1} \frac{p_u}{\rho_u v_u^2} = \frac{v_d^2}{z} + \frac{\gamma}{\gamma-1} \frac{p_d}{\rho_u v_u^2}$$

$$1 + \frac{2\gamma}{\gamma-1} \frac{1}{\gamma M^2} = \frac{1}{X^2} + \frac{2\gamma}{\gamma-1} \frac{p_d}{\rho_u} \frac{1}{\rho_u v_u^2} = \frac{1}{X^2} + \frac{2\gamma}{\gamma-1} \frac{p_d}{\rho_u} \frac{1}{\rho_u} \frac{1}{\gamma M^2}$$

$$X^2 \left(\frac{2}{M^2} + \gamma - 1 \right) = 2\gamma \left[X \left(1 + \frac{1}{\gamma M^2} \right) - 1 \right] + \gamma - 1 = 0$$

$$\Rightarrow X^2 (2 + (\gamma-1)M^2) - 2\gamma (M^2 + \frac{1}{2}) X + M^2 (\gamma+1) = 0$$

$$\Delta = 4(M^2-1)^2$$

$$X = \frac{2\gamma M^2 + 2 \pm \sqrt{4(M^2-1)^2}}{2(2 + (\gamma-1)M^2)} =$$

$$\begin{cases} X = \frac{\gamma M^2 + M^2}{2 + (\gamma-1)M^2} > 1 \\ X = \frac{2\gamma M^2 + 2 - 2M^2}{4 + 2\gamma M^2 - 2M^2} = 1 \end{cases} \quad (M > 1)$$

$$\textcircled{1} \text{ 压缩波 } X = \frac{\rho_d}{\rho_u} = \frac{v_u}{v_d}$$

$$\textcircled{2} \text{ 马赫数 } M = \frac{v_u}{c_{su}}, \quad c_{su}^2 = \frac{\gamma p_u}{\rho_u}$$

$$\textcircled{3} \quad \frac{p_d}{p_u}$$

$$\frac{p_u}{\rho_u v_u^2} = \frac{\gamma p_u}{\rho_u} \frac{1}{\gamma v_u^2} = \frac{1}{\gamma M^2}$$

$$M=1, \quad X=1; \quad M \rightarrow \infty, \quad X \rightarrow \frac{\gamma+1}{\gamma-1}$$

$$M > 1, \quad X > 1; \quad \left(\frac{v_u}{c_{s2}} \rightarrow \infty \right)$$

$$\gamma = \frac{5}{3}$$

$$X \rightarrow 4 \quad \checkmark$$

$$\frac{v_u}{v_d} \rightarrow 4$$

$$\frac{p_d}{p_u} = \frac{2\gamma M^2 - (\gamma - 1)}{\gamma + 1}$$



$$p = \rho R T$$

$$\frac{I_d}{I_u} = \frac{\rho_d \rho_u}{\rho_u \rho_d} = \frac{\rho_d}{\rho_u} \cdot \frac{1}{X}$$

$$\frac{\rho_u v_u^2}{\rho_u} = \gamma M^2$$

$$\left(\frac{v_d}{c_{s2}} \right)^2 = \frac{v_d^2}{v_u^2} \frac{v_u^2}{c_{s2}^2} = \frac{v_d^2}{v_u^2} \frac{\gamma p_d}{\rho_d} = \frac{1}{X^2}$$

$$M^2 = \frac{M^2}{X} \cdot \frac{\gamma + 1}{[2\gamma M^2 - (\gamma - 1)]}$$

激波：压缩、加热(压)，减速。slow down & heat up

3.8.3 MHD shock

- (1) 磁场
- (2) 磁化、波相速度
- (3) 耗散机制、磁雷诺数

$$\frac{\partial p}{\partial t} + \nabla \cdot (p \vec{v}) = 0$$

$$\frac{\partial (p \vec{v})}{\partial t} + \nabla \cdot [p \vec{v} \vec{v} + p \vec{I} + \frac{B^2}{2\mu_0} \vec{I} - \frac{\vec{B} \vec{B}}{\mu_0}] = 0$$

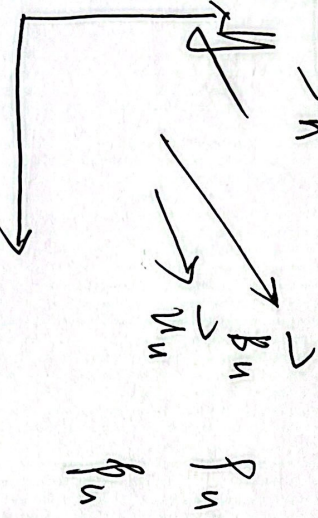
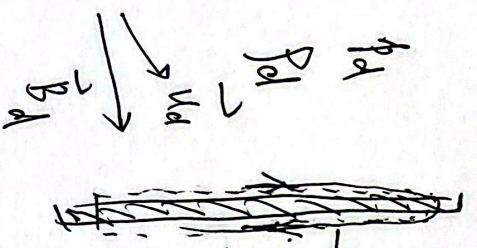
$$\left(\frac{\rho}{\gamma - 1} + \frac{\rho v^2}{2} + \frac{B^2}{2\mu_0} \right) + \nabla \cdot \left[\left(\frac{\rho \mathbf{v}}{\gamma - 1} + \frac{\rho v^2}{2} \right) \mathbf{v} + \frac{\mathbf{E} \times \mathbf{B}}{\mu_0} \right] = 0$$

$$\nabla \cdot (\mathbf{E} + \mathbf{v} \times \mathbf{B}) = 0, \quad \frac{\partial B}{\partial t} = \nabla \times (\mathbf{v} \times \mathbf{B}), \quad \nabla \cdot \mathbf{B} = 0$$

平面波 ($\mathbf{v}, \mathbf{B}, \mathbf{n}$)

$$\mathbf{v} = v_x \mathbf{e}_x + v_y \mathbf{e}_y$$

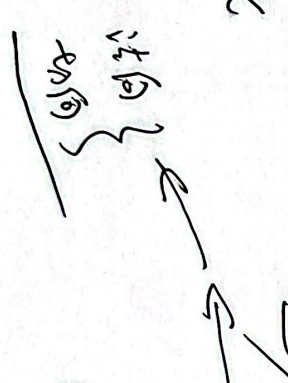
$$\mathbf{B} = B_x \mathbf{e}_x + B_y \mathbf{e}_y$$



$$\textcircled{1} \rho v_n |_{x=0} = 0$$

$$= v_n \mathbf{n} + v_z \mathbf{z}$$

$$= B_n \mathbf{n} + B_z \mathbf{z}$$



$$\textcircled{2} \rho \mathbf{v} \cdot \mathbf{n} + \rho + \frac{B^2}{2\mu_0} - \frac{\rho B_n}{\mu_0} \Big|_{x=0} = 0$$

$$\left(\frac{\rho \rho}{\gamma - 1} + \frac{\rho v^2}{2} \right) v_n + \frac{\mathbf{E} \times \mathbf{B}}{\mu_0} \Big|_{x=0} = 0$$

$$\begin{aligned} &= \mathbf{B} \times (\mathbf{v} \times \mathbf{B}) \\ &= \mathbf{B} \cdot \mathbf{B} \mathbf{v} - \mathbf{B} \cdot \mathbf{v} \mathbf{B} \\ &= B^2 \mathbf{v} - \mathbf{v} \cdot \mathbf{B} \mathbf{B} \end{aligned}$$

切向磁场的连续, $\mathbf{v} \times \mathbf{B} \Big|_{x=0} = 0$ $\textcircled{14}$

$$+ B^2 v_n - \mathbf{v} \cdot \mathbf{B} B_n \Big|_{x=0} = 0$$

法向磁场的连续, $B_n |_{x=0} = 0$ $\textcircled{15}$

$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{v}) = 0$ 分别对上、下分子写出守恒定律在控制体上:

$$\frac{\partial (\rho \vec{v})}{\partial t} + \nabla \cdot (\rho \vec{v} \vec{v}) + \rho \vec{I} + \frac{B^2}{2\mu_0} \vec{I} - \frac{\vec{B} \times \vec{B}}{\mu_0} = 0$$

$$\frac{\partial}{\partial t} \left(\frac{\rho}{\gamma - 1} + \frac{\rho v^2}{2} + \frac{B^2}{2\mu_0} \right) + \nabla \cdot \left[\left(\frac{\rho \vec{v}}{\gamma - 1} + \frac{\rho \vec{v} v^2}{2} \right) + \frac{\vec{E} \times \vec{B}}{\mu_0} \right] = 0$$

$$\frac{\partial \vec{B}}{\partial t} = \nabla \times (\vec{v} \times \vec{B}) = 0 \quad \nabla \cdot \vec{B} = 0$$

体积分 \rightarrow 面积分 $(\cdot \vec{n})$

$$\Rightarrow \textcircled{1} \int_{u-d} [\rho v_n] = 0 \quad \rho_1 v_1 = \rho_2 v_2$$

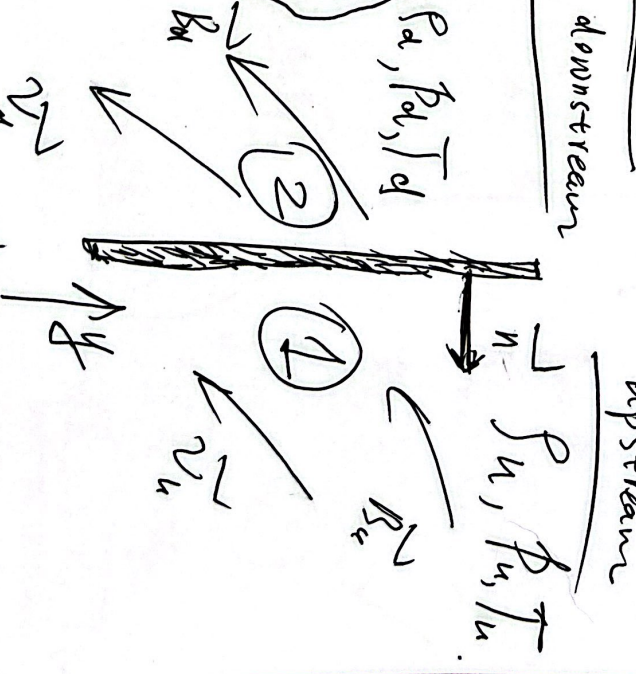
$$\Rightarrow \textcircled{2} \int_{u-d} \rho v_n + p \vec{n} + \frac{B^2}{2\mu_0} \vec{n} - \frac{B_x B_n}{\mu_0} = 0$$

$$\Rightarrow \int_{u-d} \rho (v_x \vec{e}_x + v_y \vec{e}_y) v_x + p \vec{e}_x + \frac{B^2}{2\mu_0} \vec{e}_x - \frac{(B_x \vec{e}_x + B_y \vec{e}_y) v_x}{\mu_0} = 0$$

$$\left\{ \begin{array}{l} \rho v_x^2 + p + \frac{B^2}{2\mu_0} - \frac{B_x^2}{\mu_0} \\ \rho v_x v_y - \frac{B_x B_y}{\mu_0} \end{array} \right\}_{u-d} = 0$$

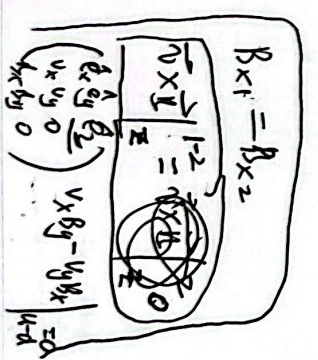
$$\left\{ \begin{array}{l} B_{x1} = B_{x2} \\ \vec{v} \times \vec{B} = 0 \end{array} \right\}_{u-d} = 0$$

$$\left\{ \begin{array}{l} \rho v_x^2 + \frac{B^2}{2\mu_0} v_x + \frac{B_x^2}{2\mu_0} v_x - (v_x B_x + v_y B_y) v_x \\ \rho v_x v_y - \frac{B_x B_y}{\mu_0} \end{array} \right\}_{u-d} = 0$$



Shock frame

$$\vec{v} = v_x \vec{e}_x + v_y \vec{e}_y$$

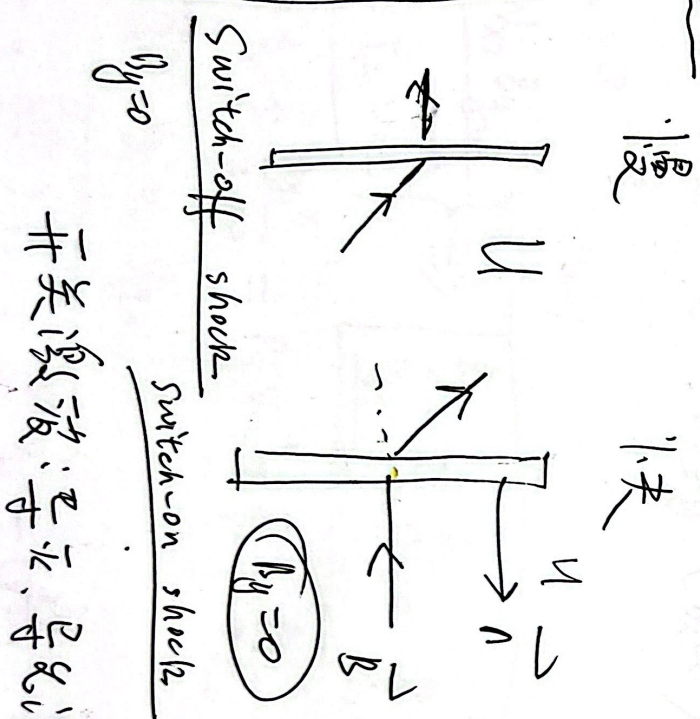
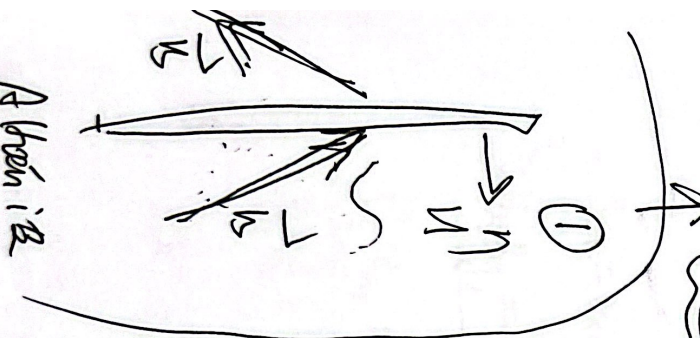
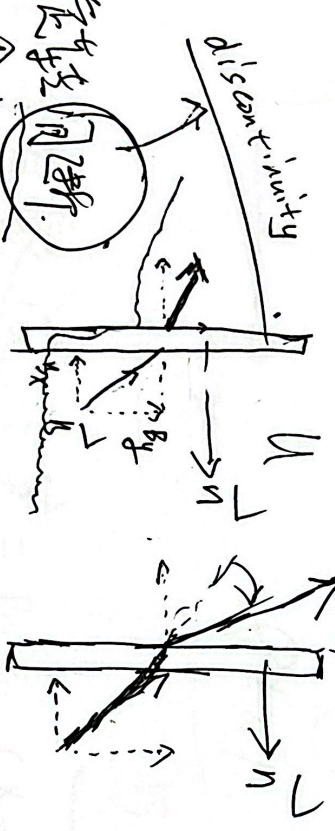
$$\vec{B} = B_x \vec{e}_x + B_y \vec{e}_y$$


① HD 波与 MH 波的区别: 磁场, 粒子加速, 波速不同, ~~耗散机制~~ → 无碰撞激波

② 三组件: 快激波, 慢激波, 中间激波 (大振幅 Alfvén 波 — 不可压)



$$B^2 = B_x^2 + B_y^2$$



$$\Rightarrow P' = P'' = 0$$

$$P^{u=1} = 0, P_u = P_d$$

$$\frac{\rho}{2} (v_y^2) v_x \phi - \frac{(\mu_0 B_x + \mu_0 B_y)}{\mu_0} B_x$$

$$\frac{\rho v_x v_y^2}{2} - \frac{\mu_0 B_x B_y}{\mu_0}$$

$$= \frac{\rho_2 v_{x2} v_{y2}^2}{2} - \frac{\mu_0 v_{x2} v_{y2} B_{y2}}{\mu_0}$$

$$\frac{\rho_1 v_{x1} (v_{y1}^2 - v_{y2}^2)}{2} = \frac{B_{x1} B_{y1} (\mu_0 v_{x1} + \mu_0 v_{x2})}{\mu_0}$$

$$\textcircled{1} v_{y1} + v_{y2} = 0$$

$$\textcircled{2} \frac{\rho_1 v_{x1}}{2} (v_{y1} - v_{y2}) = \frac{B_{x1} B_{y1}}{\mu_0}$$

$$\Rightarrow v_{y1} + v_{y2} = v_{y1} + v_{y2}$$

$$P_u = P_d, v_{x1} = v_{x2}, B_{x1} = B_{x2}$$

$$B_{y1}^2 = B_{y2}^2$$

$$\Rightarrow B_{y1} = \pm B_{y2}$$

$$\Rightarrow B_{y1} = -B_{y2}$$

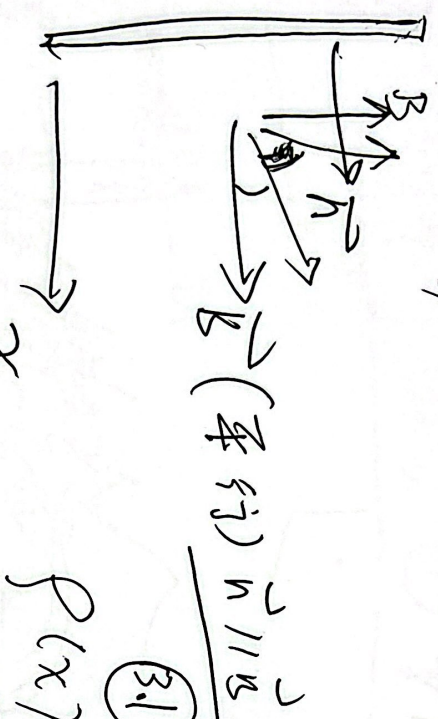
$$v_{x1} v_{y1} - v_{y1} v_{x1}$$

$$= v_{x2} B_{y2} - v_{y2} B_{x2}$$

$$= -v_{x1} B_{y1} - v_{y2} B_{x1}$$

$$\Rightarrow 2 v_{x1} v_{y1} = \mu_0 v_{x1} (v_{y1} - v_{y2})$$

③ 平行激波、垂直激波、倾斜激波、Oblique (斜) (准)



3.1 平行激波
 $P(x), \rho(x), \vec{v}(x), B(x)$
 $B_{x1} = B_{x2}$

与HD激波关系一致

3.2 垂直激波: $\vec{B} = B_y \hat{e}_y$ ($B_x = 0$)

$B_{x1} = B_{x2} = 0$

$v_{x1} B_{y1} = v_{x2} B_{y2}$

$\rho_1 v_{x1} = \rho_2 v_{x2}$

$\frac{B_{y2}}{B_{y1}} = \frac{\rho_2}{\rho_1} = \frac{v_{x1}}{v_{x2}}$

$\rho_1 v_{x1}^2 + p_1 + \frac{B_{y1}^2}{2\mu_0} = \rho_2 v_{x2}^2 + p_2 + \frac{B_{y2}^2}{2\mu_0}$

$v_{y1} = v_{y2}$

$(\frac{\gamma p_1}{\rho_1} + \frac{\rho_1 v_1^2}{2}) v_{x1} + \frac{B_{y1}^2}{\mu_0} v_{x1} = (\frac{\gamma p_2}{\rho_2} + \frac{\rho_2 v_2^2}{2}) v_{x2} + \frac{B_{y2}^2}{\mu_0} v_{x2}$

$X \leq \frac{\gamma+1}{\gamma-1}$

$\frac{\rho_2}{\rho_1} \leq \frac{\gamma+1}{\gamma-1}$

$2(2-\gamma)X^2 + [2\beta + 2 + (8\gamma)]M_1^2 \beta_1] \gamma X - \gamma(\gamma+1)M_1^2 \beta_1 = 0$

$M_1 = \frac{v_1}{c_{s1}}, \beta_1 = \frac{\rho_1}{\rho_1} \frac{v_1^2}{2\mu_0}, c_{s1}^2 = \frac{\gamma p_1}{\rho_1}$

$\frac{1}{2c_{s1}^2} = \frac{1}{\gamma p_1} \frac{\rho_1 v_1^2}{\rho_1 v_1^2} = \frac{1}{\gamma M_1^2}$

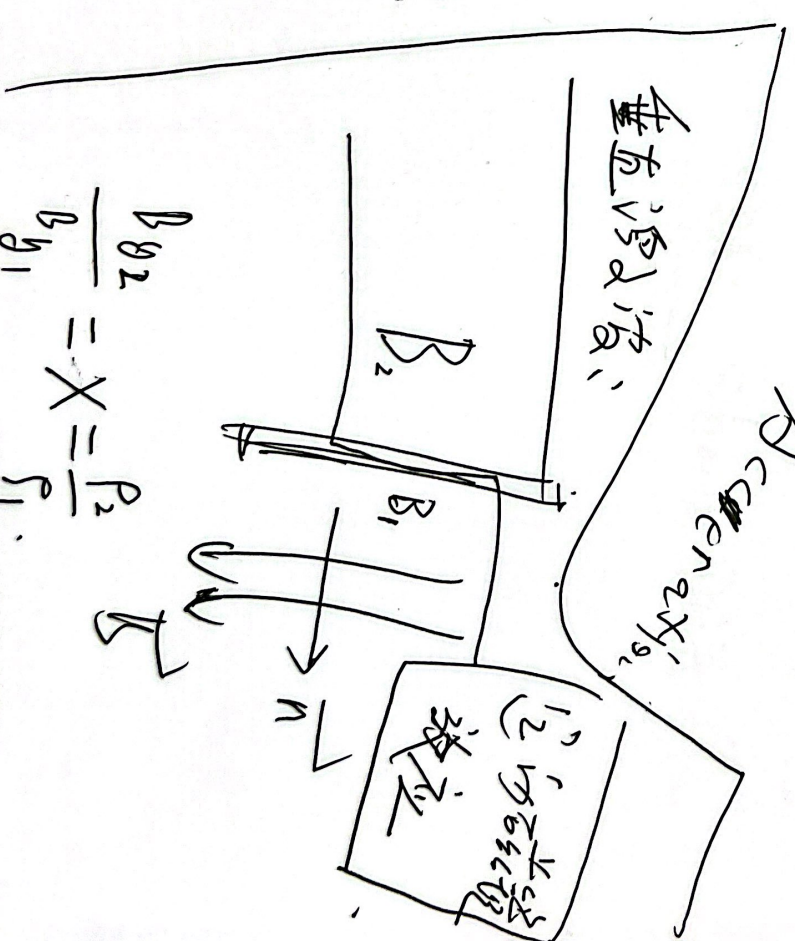
④ 激波粒子加速 (电场):

- ① 平行激波
- ② 垂直激波

上下粒子强湍流; = 所 Fermi 加速



Diffusive Shock Acceleration



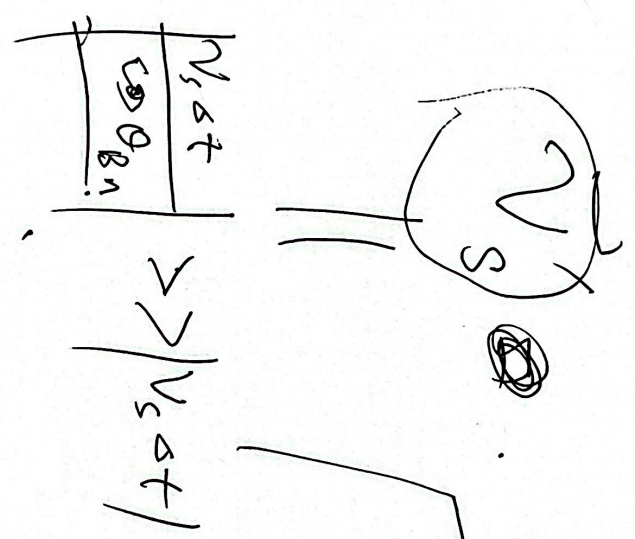
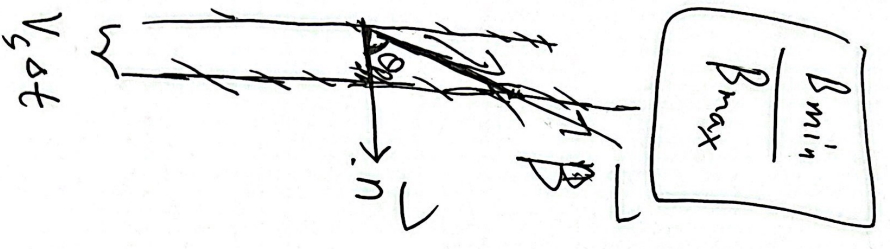
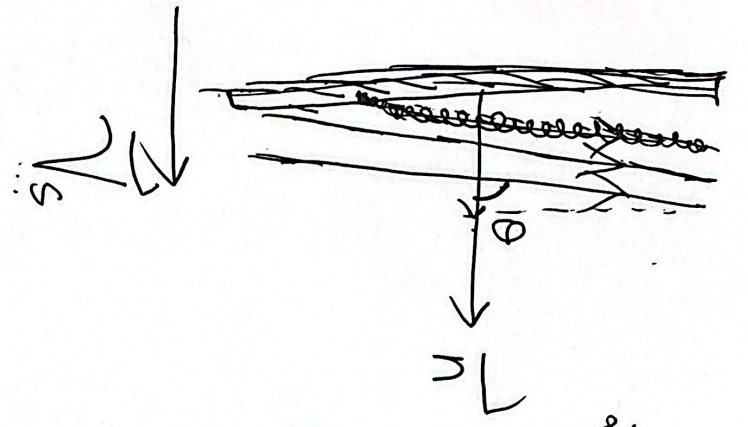
$$\frac{B_{02}}{B_{01}} = X = \frac{P_2}{P_1}$$

对沿 \vec{v} 方向的电子而言, shock 速度?

Fermi 加速

$$\Delta E = 2\gamma v^2$$

$$\left[\frac{v_m}{v} + \left(\frac{v_m}{v} \right)^2 \right]$$



快 Fermi 加速

吴京生

源区漂移加速

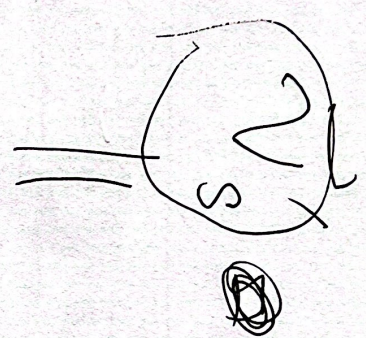
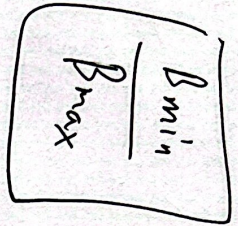
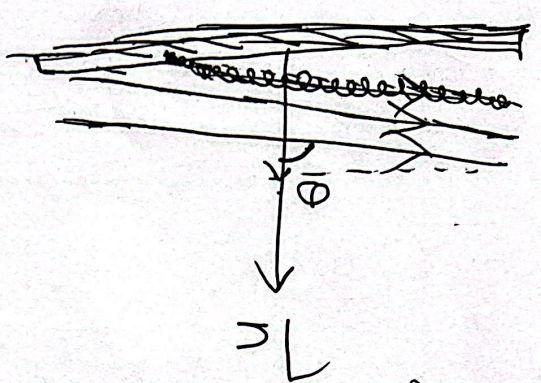
SDA: Shock Drift Acc.

对沿 \vec{v} 运动的电子而言, shock 速度?

Fermi 加速

$$\Delta E = 2\mu v^2$$

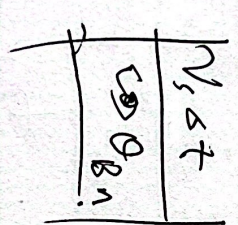
$$\left[\frac{1}{2} \left(\frac{v_m}{c} \right)^2 + \left(\frac{v_m}{c} \right)^2 \right]^2$$



快 Fermi 加速

吴京生

源波漂移加速



SDA: Shock Drift Acc.

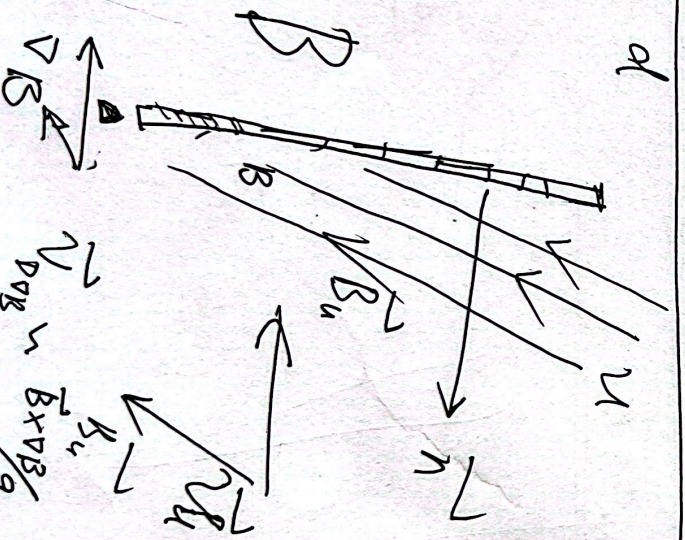
主要是电子加速

对流电场

$$\vec{E}_u = -\vec{v}_u \times \vec{B}_u$$

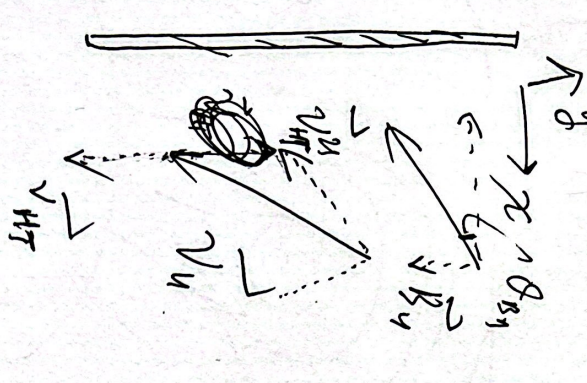
PHS 方向

电子: 向外, $e\vec{E}_u$ 向外



⑤ De Hoffmann-Teller (HT) 参考系 (请在上游电场, 简化推子)

$$\vec{E}_{HT} = -(\vec{v}_{HT} \times \vec{B}_u = 0 \quad (\vec{v}_{HT} \parallel \vec{B}_u)) \quad \vec{v}_{HT}$$



$$(\vec{v}_u - \vec{v}_{HT}) \times \vec{B}_u = 0$$

$$\vec{A} \times (\vec{B} \times \vec{c}) = \vec{A} \cdot \vec{c} \vec{B} - \vec{A} \cdot \vec{B} \vec{c}$$

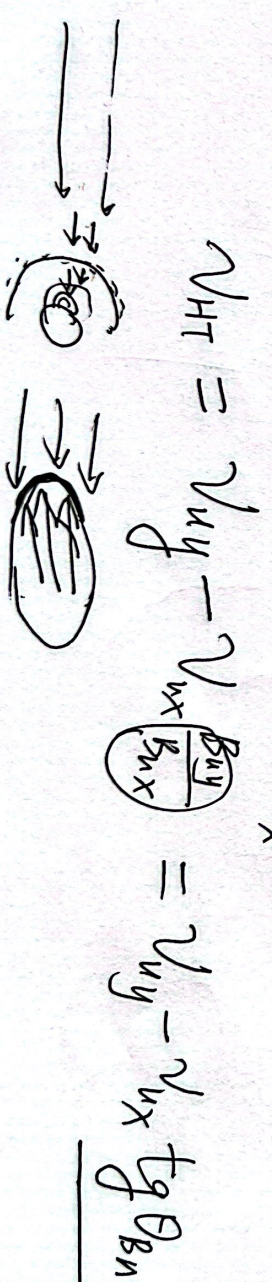
$$(\vec{v}_u \times \vec{B}_u) \times \vec{n} = \vec{n} \cdot \vec{v}_u \vec{B}_u - \vec{n} \cdot \vec{B}_u \vec{v}_u$$

$$\vec{v}_{HT} = \frac{\vec{n} \times (\vec{v}_u \times \vec{B}_u)}{\vec{n} \cdot \vec{B}_u} = \frac{\vec{n} \cdot \vec{B}_u \vec{v}_u - \vec{n} \cdot \vec{v}_u \vec{B}_u}{\vec{n} \cdot \vec{B}_u}$$

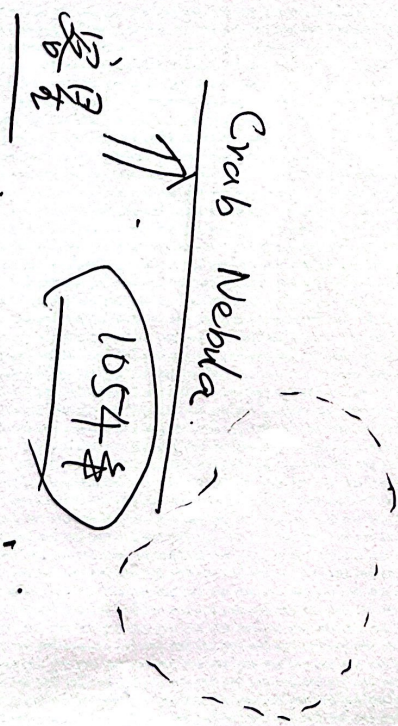
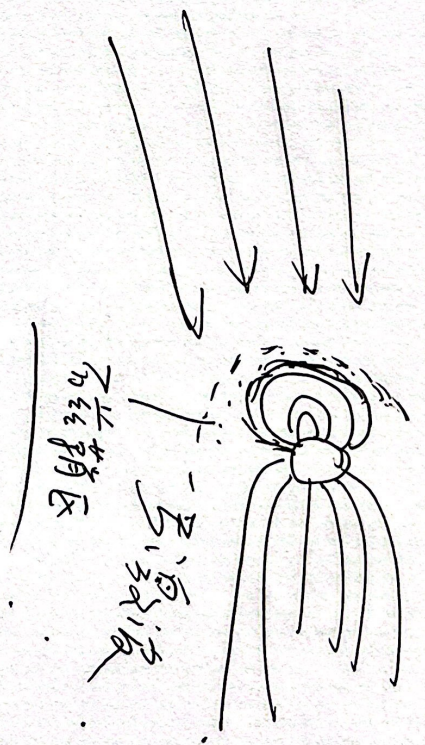
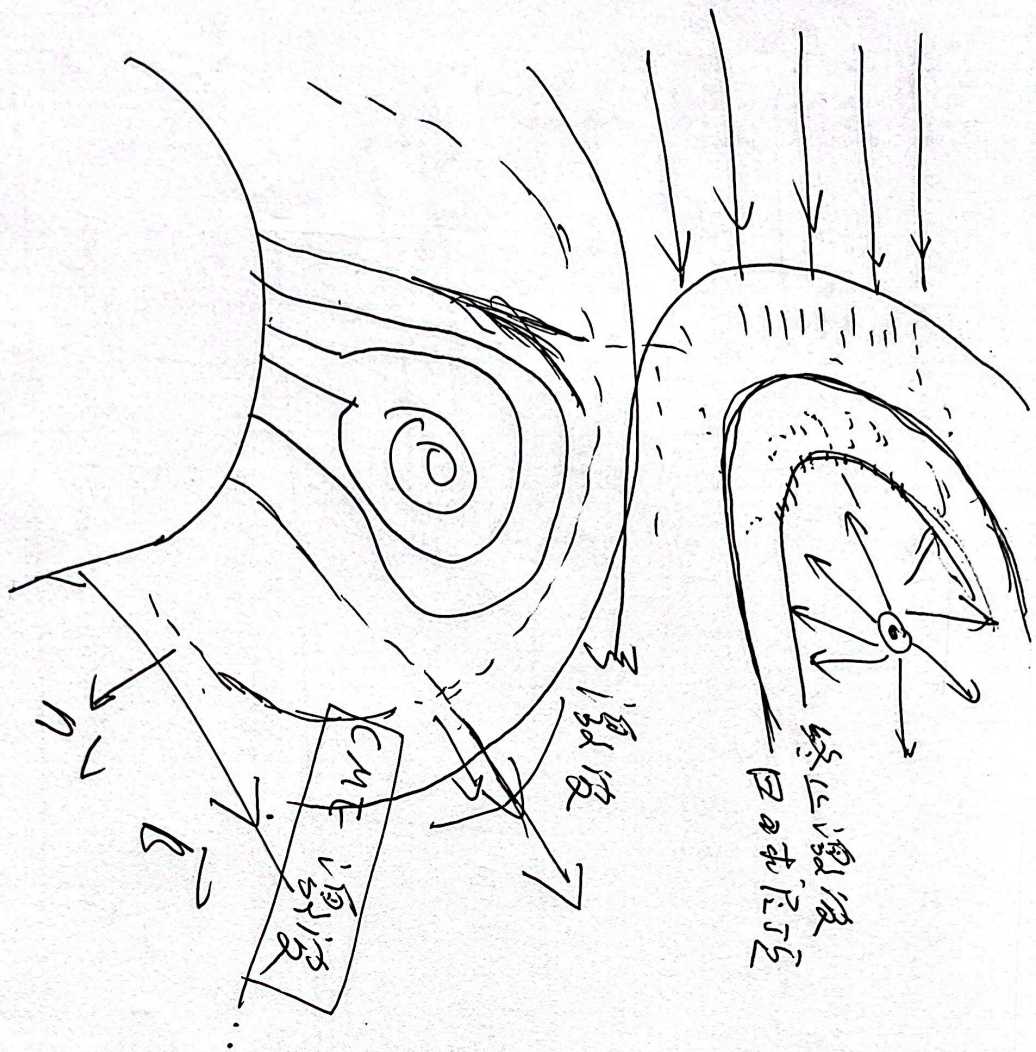
$$\vec{v}_{HT} = \frac{B_{ux} \vec{v}_u - v_{ux} \vec{B}_u}{B_{ux}} = \frac{B_{ux} v_{uy} \hat{e}_y - v_{ux} B_{ux} \hat{e}_x - v_{ux} B_{uy} \hat{e}_y}{B_{ux}}$$

$$= \frac{v_{uy} - v_{ux} \frac{B_{uy}}{B_{ux}}}{B_{ux}}$$

E. R. Priest
Solar MHD
MHD of the Sun



$$v_{HT} = v_{uy} - v_{ux} \frac{B_{uy}}{B_{ux}} = v_{uy} - v_{ux} \tan \theta_{Bn}$$



$$\frac{\partial n_e}{\partial t} + \nabla \cdot (n_e \vec{v}_e) = 0 \quad \frac{\partial n_i}{\partial t} + \nabla \cdot (n_i \vec{v}_i) = 0$$

$$\rho_e \left(\frac{\partial \vec{v}_e}{\partial t} + \vec{v}_e \cdot \nabla \vec{v}_e \right) = \rho_e \frac{d\vec{v}_e}{dt} = -\nabla p_e - e n_e (\vec{E} + \vec{v}_e \times \vec{B})$$

$$\rho_i \frac{d\vec{v}_i}{dt} = -\nabla p_i + e n_i (\vec{E} + \vec{v}_i \times \vec{B})$$

$$p_e = c_e \rho_e, \quad p_i = c_i \rho_i$$

$$\frac{\partial \vec{B}}{\partial t} = \nabla \times \vec{E}, \quad \frac{\partial \vec{E}}{\partial t} = -\nabla \times \vec{B}$$

$$\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}, \quad \nabla \cdot \vec{B} = 0$$

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}, \quad \nabla \times \vec{B} = \mu_0 \vec{j} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

$-\nabla p_e$	$-e n_e \vec{E}$	$-e \vec{v}_e \times \vec{B}$	$-\nabla p_i$	$e n_i \vec{E}$	$e n_i \vec{v}_i \times \vec{B}$	$\frac{\partial \vec{B}}{\partial t}$	$\frac{\partial \vec{E}}{\partial t}$
$k^2 c_e^2$	ω_{pe}^2	ω_{ce}	ω_{pi}^2	ω_{ci}^2	ω_{ci}^2	ω_{pe}^2	ω_{pi}^2

(各等号均非)

Langmuir 波 \rightarrow 等离子体振荡 $\omega^2 = \omega_{pe}^2$

$$\sum_{\alpha} n_{\alpha 0} q_{\alpha} = 0$$

$$\frac{\partial n_{\alpha}'}{\partial t} + n_{\alpha 0} \nabla \cdot (\vec{v}_{\alpha}') = 0, \quad \rho_{\alpha 0} \frac{\partial \vec{v}_{\alpha}'}{\partial t} = q_{\alpha} n_{\alpha 0} \vec{E}$$

$$\vec{j} = \sum_{\alpha} n_{\alpha} q_{\alpha} \vec{v}_{\alpha}$$

$$\rho = \sum_{\alpha} n_{\alpha} q_{\alpha}$$

$$\frac{\partial (\nabla \cdot \vec{v}_{\alpha}')}{\partial t} = \frac{q_{\alpha}}{m_{\alpha}} \nabla \cdot \vec{E} = -\frac{\partial^2 n_{\alpha}'}{\partial t^2} / n_{\alpha 0}$$

$$i\vec{k} \cdot \vec{E} = \sum_{\alpha} \frac{N_{\alpha} q_{\alpha}}{\epsilon_0} \quad \frac{N_{\alpha} q_{\alpha}}{\omega^2 \epsilon_0} \quad i\vec{k} \cdot \vec{E} = \sum_{\alpha} \frac{N_{\alpha} q_{\alpha}^2}{\epsilon_0} \frac{i\vec{k} \cdot \vec{E}}{\omega^2}$$

$$\Rightarrow \left[\omega^2 = \sum_{\alpha} \frac{N_{\alpha} q_{\alpha}^2}{\epsilon_0} \right] \left[\frac{\omega_{p\alpha}^2}{\omega^2} \right] \quad \omega_{p_i}^2 < \omega_{pe}^2$$

4.2.1 (电介质) 冷等离子体 色散关系的一般形式

$$\frac{\partial \vec{B}}{\partial t} = -\nabla \times \vec{E}, \quad \nabla \times \vec{B} = \mu_0 \vec{j} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

$$-i\omega \vec{B} = -i\vec{k} \times \vec{E}, \quad i\vec{k} \times \vec{B} = \mu_0 \vec{j} - i\mu_0 \epsilon_0 \omega \vec{E} = \left(\mu_0 \frac{\partial \vec{j}}{\partial t} - i\mu_0 \epsilon_0 \omega \vec{I} \right) \cdot \vec{E}$$

$$\vec{j} = \vec{I} + \frac{N_{\alpha} q_{\alpha}^2}{-i\mu_0 \epsilon_0 \omega} = \vec{I} + \frac{i\omega}{\omega_{p\alpha}^2} \vec{j}$$

$\omega_{p\alpha}^2 = -i\mu_0 \epsilon_0 \omega \sum_{\alpha} \vec{j} \cdot \vec{E}$
= 介电张量

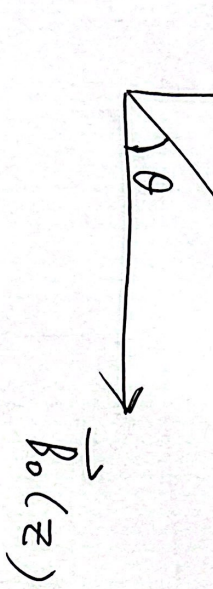
$$\left\{ \begin{aligned} \omega \vec{B} = \vec{k} \times \vec{E} &\Rightarrow \vec{k} \times (\vec{k} \times \vec{E}) = \omega \vec{k} \times \vec{B} = -\mu_0 \epsilon_0 \omega^2 \sum_{\alpha} \vec{j} \cdot \vec{E} = -\frac{\omega^2}{c^2} \sum_{\alpha} \vec{E} \\ \vec{k} \times \vec{B} = -\mu_0 \epsilon_0 \omega \sum_{\alpha} \vec{j} \cdot \vec{E} &\Rightarrow (\vec{k} \cdot \vec{E}) \vec{k} - k^2 \vec{E} + \frac{\omega^2}{c^2} \sum_{\alpha} \vec{j} \cdot \vec{E} = 0 \end{aligned} \right.$$

$$\left(k^2 \vec{I} - k^2 \frac{\vec{r}\vec{r}}{r^2} + \frac{\omega^2}{c^2} \sum_{\alpha} \vec{j} \cdot \vec{E} \right) \cdot \vec{E} = 0$$

关于 E_x, E_y, E_z 的二次代数方程。

$$\vec{r}_k = \begin{pmatrix} r_x \\ 0 \\ r_z \end{pmatrix} \quad (r_x, 0, r_z) = \begin{pmatrix} r_x^2, 0, r_x r_z \\ 0, 0, 0 \\ r_z r_x, 0, r_z^2 \end{pmatrix}$$

$$\vec{r}_k = r_x \hat{e}_x + r_z \hat{e}_z = r \sin \theta \hat{e}_x + r \cos \theta \hat{e}_z$$



有非零解的条件: $\det \begin{vmatrix} \vec{r}_k - k^2 \vec{I} + \frac{\omega^2}{c^2} \vec{z} \vec{z} \end{vmatrix} = 0$

$$\begin{pmatrix} k^2 & 0 & 0 \\ 0 & k^2 & 0 \\ 0 & 0 & k^2 \end{pmatrix} \quad \frac{1}{c^2} \begin{pmatrix} \omega^2 \\ 0 \\ 0 \end{pmatrix}$$

$$\sum_{\alpha} n_{\alpha} q_{\alpha} \vec{v}_{\alpha} = \frac{1}{\sigma} \cdot \vec{E}$$

$$n_{\alpha 0} m_{\alpha} \frac{d\vec{v}_{\alpha}}{dt} = + q_{\alpha} n_{\alpha} (\vec{E} + \vec{v}_{\alpha} \times \vec{B}_0)$$

FT

$$n_{\alpha 0} m_{\alpha} (-i\omega \vec{v}_{\alpha}) = q_{\alpha} n_{\alpha} (\vec{E} + \vec{v}_{\alpha} \times \vec{B}_0)$$

$$\begin{pmatrix} q_{\alpha} n_{\alpha} & 0 & 0 \\ 0 & q_{\alpha} n_{\alpha} & 0 \\ 0 & 0 & q_{\alpha} n_{\alpha} \end{pmatrix} =$$

$$-i\omega n_{\alpha 0} m_{\alpha} v_{\alpha x} = q_{\alpha} n_{\alpha} E_x + q_{\alpha} n_{\alpha} v_{\alpha y} B_0$$

$$-i\omega n_{\alpha 0} m_{\alpha} v_{\alpha y} = q_{\alpha} n_{\alpha} E_y - q_{\alpha} n_{\alpha} v_{\alpha x} B_0$$

$$-i\omega n_{\alpha 0} m_{\alpha} v_{\alpha z} = q_{\alpha} n_{\alpha} E_z$$



$$\begin{pmatrix} v_{\alpha x} \\ v_{\alpha y} \\ v_{\alpha z} \end{pmatrix} = \begin{pmatrix} E_x \\ E_y \\ E_z \end{pmatrix}$$

$$\vec{v}_d = \vec{A}_d^{-1} \cdot \vec{E} \Rightarrow \sum \eta_d \eta_d \vec{A}_d^{-1} \cdot \vec{E} = \delta \cdot \vec{E}$$

$$\begin{pmatrix} \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot & \cdot & \cdot \end{pmatrix}$$

$$\Rightarrow \vec{0} = \sum \eta_d \eta_d \vec{A}_d^{-1}$$

$$\vec{0} = \vec{I} + \frac{N^2}{\omega^2 \epsilon_0}$$

$$N^2 = \frac{B \pm \sqrt{B^2 - 4AC}}{2A} = \frac{k c^2}{\omega^2}$$

推导 §4.2 节

$$C = PRL$$

$$P = 1 - \sum \frac{\omega_{pa}^2}{\omega^2}$$

$$S = 1 - \sum \frac{\omega_{pa}^2}{\omega^2 - \omega_{ca}^2}$$

$$D = \sum \frac{\omega_{pa}^2 \omega_{ca}^2}{\omega(\omega^2 - \omega_{ca}^2)}$$

$$R = S + D, L = S - D$$

$$\det | k \vec{k} - k^2 \vec{I} + \frac{\omega^2}{c^2} \vec{\Sigma} | = 0$$

$$n = \frac{kc}{\omega}, \vec{n} = \frac{k\vec{c}}{\omega}$$

$\frac{c}{\omega}$ 折射率是

$$\det | \vec{n} \vec{n} - n^2 \vec{I} + \vec{\Sigma} | = 0$$

$$\vec{n} = n \sin \alpha \vec{e}_1 + n \cos \alpha \vec{e}_2$$

$$\Rightarrow A n^4 - B n^2 + C = 0$$

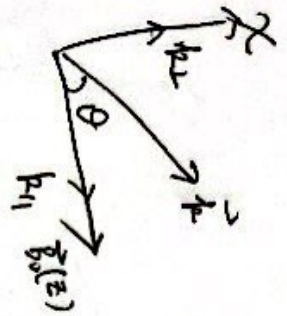
$$\left\{ \begin{aligned} \frac{\partial n_e}{\partial t} + \nabla \cdot (n_e \vec{v}_e) &= 0, & \frac{\partial n_i}{\partial t} + \nabla \cdot (n_i \vec{v}_i) &= 0, \\ \rho_e \frac{d\vec{v}_e}{dt} &= -\nabla p_e + (-e) n_e (\vec{E} + \vec{v}_e \times \vec{B}) \\ \rho_i \frac{d\vec{v}_i}{dt} &= -\nabla p_i + e n_i (\vec{E} + \vec{v}_i \times \vec{B}) \\ p_e &= \omega \rho_e v_e, & p_i &= \omega \rho_i v_i \end{aligned} \right.$$

$$\left. \begin{aligned} \nabla \times \vec{E} &= -\frac{\partial \vec{B}}{\partial t} \\ \nabla \times \vec{B} &= \mu_0 \vec{j} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} = \mu_0 \frac{\partial}{\partial t} (\vec{E} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}) \\ \nabla \cdot \vec{E} &= \frac{\rho}{\epsilon_0} \\ \nabla \cdot \vec{B} &= 0 \\ \vec{j} &= \sum n_a q_a \vec{v}_a, & \rho &= \sum n_a q_a \end{aligned} \right\}$$

4.2 一般形式: $\vec{j} = \frac{\partial}{\partial t} \cdot \vec{E}$, $\frac{\partial}{\partial t}$ 电导率张量

$$\vec{k} \times \vec{E} = \omega \vec{B}, \quad \vec{k} \times \vec{B} = \frac{k}{\omega} \times (k \times \vec{E}) = -\omega \mu_0 \epsilon_0 \vec{E} \cdot \vec{E}, \quad \vec{E} = \vec{I} + \frac{\omega^2}{\omega \epsilon_0} \vec{E}$$

$\Rightarrow \left(\frac{\omega^2}{c^2} \vec{E} + k^2 \vec{E} - k^2 \vec{I} \right) \cdot \vec{E} = 0$. ----- 电场 \vec{E} 的三分量方程



非零解条件 $\det | \vec{k} | = \det \left| \frac{\omega^2}{c^2} \vec{E} + k^2 \vec{E} - k^2 \vec{I} \right| = 0$,

令 $\vec{n} = \frac{k}{\omega}$, 得 $\det \left| \vec{E} + \vec{n} \vec{n} - n^2 \vec{I} \right| = 0$. $n = \frac{k}{\omega} = \frac{c}{v_p}$.

$$\vec{n} \vec{n} - n^2 \vec{I} =$$

$$\begin{pmatrix} -n^2 \sin^2 \theta & 0 & n^2 \sin \theta \cos \theta \\ 0 & -n^2 & 0 \\ n^2 \sin \theta \cos \theta & 0 & -n^2 \cos^2 \theta \end{pmatrix}$$

$$\vec{k}_e = (k \cos \theta, k \sin \theta)$$

$$\vec{n} = (n \cos \theta, n \sin \theta)$$

$$\vec{E} = \vec{I} + \frac{\omega^2}{\omega \epsilon_0} \vec{E}, \quad \vec{j} = \sum n_a q_a \vec{v}_a = \frac{\partial}{\partial t} \cdot \vec{E}$$

令等号条件

$$\rho_a \frac{d\vec{v}_a}{dt} = q_a N (\vec{E} + \vec{v}_a \times \vec{B}) \quad \vec{v} = -i N a_0 m_a w \vec{v}_a = q_a N a_0 (c \vec{E} + \vec{v}_a \times \vec{B}_0) \Rightarrow \vec{A}_a \cdot \vec{v}_a = \frac{q_a}{m_a w} E$$

$$\Rightarrow \vec{A}_a^{-1} \vec{A}_a \cdot \vec{v}_a = \frac{q_a}{m_a w} \vec{A}_a^{-1} \cdot \vec{E} \Rightarrow \vec{v}_a = \frac{q_a}{m_a w} \vec{A}_a^{-1} \cdot \vec{E}, \quad \vec{A}_a^{-1} = \begin{pmatrix} 1 & i \frac{w p_a}{w} & 0 \\ -i \frac{w p_a}{w} & 1 & 0 \\ 0 & 0 & 1 - \frac{w p_a^2}{w^2} \end{pmatrix}$$

$$\vec{B} = \frac{q_a}{m_a w} \vec{B}_a, \quad \vec{B}_a = \frac{i N a_0 q_a^2}{m_a w} \vec{A}_a^{-1}$$

$$\frac{1}{w \xi_0} = \frac{i w p_a^2}{\cancel{w^2 - w p_a^2}} \begin{pmatrix} 1 & i \frac{w p_a}{w} & 0 \\ -i \frac{w p_a}{w} & 1 & 0 \\ 0 & 0 & 1 - \frac{w p_a^2}{w^2} \end{pmatrix} = \begin{pmatrix} S & -iD & 0 \\ iD & S & 0 \\ 0 & 0 & P \end{pmatrix}$$

$$\text{由 } \det \left| \frac{1}{n} \vec{n} - n^2 \vec{I} + \vec{E} \right| = 0, \text{ 得}$$

$$\det \begin{pmatrix} S - n^2 \cos^2 \theta & -iD & n^2 \sin^2 \theta \\ iD & S - n^2 & 0 \\ n^2 \sin^2 \theta & 0 & P - n^2 \sin^2 \theta \end{pmatrix} = 0 \Rightarrow A n^4 - B n^2 + C = 0$$

$$S = 1 - \frac{\sum w p_a^2}{\omega^2 - w p_a^2}$$

$$D = \frac{\sum w p_a^2 w p_a}{\omega (\omega^2 - w p_a^2)}$$

$$P = 1 - \frac{\sum w p_a^2}{\omega^2}$$

$$\begin{cases} A = P \cos^2 \theta + S \sin^2 \theta \\ B = S P (1 + \cos^2 \theta) + (S^2 - D^2) \sin^2 \theta \\ C = P (S^2 - D^2) = P (S+D)(S-D) = P R L \end{cases}$$

$$\begin{cases} R = S+D \\ L = S-D \end{cases}$$

$$\text{可证 } B^2 - 4AC > 0, \quad \tan^2 \theta = - \frac{P(C n^2 - R)(C n^2 - L)}{(n^2 - P)(S n^2 - P L)} \quad (\text{Alice 探针})$$

1° 截止 (cut-off) 频率与共振 (resonance) 频率 ($n^2 = 0$, $n^2 \rightarrow \infty$) ③

由 $n^2 = 0$, 得 $C=0 \Rightarrow P=0, R=0, L=0$. 分别求得 $\omega = \omega_R, \omega = \omega_L$.

又对应于 0 模截止频率、右旋截止频率、左旋...

共振频率 $n^2 \rightarrow \infty \Rightarrow A=0 \Rightarrow P \cos^2 \theta + S \sin^2 \theta = 0$

忽略各因子效应: $(1 - \frac{\omega_{pe}^2}{\omega^2}) \cos^2 \theta + (1 - \frac{\omega_{pe}^2}{\omega^2 - \omega_c^2}) \sin^2 \theta = 0$

$\theta = 0^\circ$ 时. $\omega = \omega_{pe}$. 一般情况 $\omega_L (\omega_L^2, \omega_H)$

$\theta = 90^\circ$ 时. $\omega \sim \omega_{pe}^2 + \omega_c^2 = \omega_{UH}^2$, 高电子波 (自行求解 绘图)

2° 平行传播 $\theta = 0^\circ$. $P=0, n^2 = R, n^2 = L$.

(三种模式) $\omega^2 = \omega_{pe}^2, \frac{k^2 c^2}{\omega^2} = 1 - \frac{\omega_{pe}^2}{(\omega^2 - \omega_c^2) \omega^2}$
 $\frac{k^2 c^2}{\omega^2} = 1 - \frac{\omega_{pe}^2}{(\omega - \omega_c) \omega}$

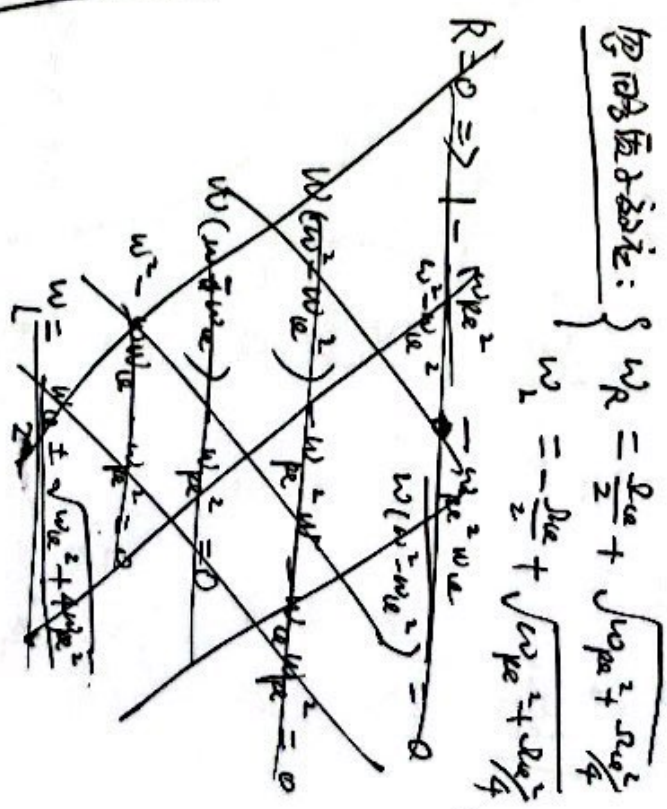
垂直传播 $\theta = 90^\circ$.

$n^2 = P, n^2 = R/L/S$.

0 模 $\frac{k^2 c^2}{\omega^2} = 1 - \frac{\omega_{pe}^2}{\omega^2} \Rightarrow \omega^2 = \omega_{pe}^2 + k^2 c^2$

X 模 $\frac{k^2 c^2}{\omega^2} = R/L/S$ 一般情况: $n^2 = \frac{1}{2A} (B \pm \sqrt{B^2 - 4AC})$

忽略各因子效应: $\omega_R = \frac{\omega_c}{2} + \sqrt{\frac{\omega_{pe}^2 + \omega_c^2}{4}}$
 $\omega_L = -\frac{\omega_c}{2} + \sqrt{\frac{\omega_{pe}^2 + \omega_c^2}{4}}$



$R = S + D = 1 - \frac{\omega_{pe}^2}{\omega^2 - \omega_c^2} + \frac{\omega_{pe}^2 \omega_c^2}{\omega(\omega^2 - \omega_c^2)}$

$= 1 - \frac{\omega_{pe}^2 - \omega_{pe}^2 \omega_c^2}{\omega(\omega^2 - \omega_c^2)} = 1 - \frac{\omega_{pe}^2}{\omega(\omega + \omega_c)}$

$R=0 \Rightarrow 1 - \frac{\omega_{pe}^2}{\omega(\omega - \omega_c)} = 0$

$\omega^2 - \omega \omega_c - \omega_{pe}^2 = 0$

$\omega = \frac{\omega_c \pm \sqrt{\omega_c^2 + 4\omega_{pe}^2}}{2}$ (两种取值)

$L = S - D = \dots$

冷等离子体磁流体论 (Magnetoionic theory of waves in cold plasmas) : X, O, Z, W

1° 冷等离子体假设. 2° 离子静止不动. — 考虑 $w \gg v_{pi}, v_{pe}$ (高频模式) \Rightarrow Appleton-Hartree (A-H) 形式

$$n^2 = \frac{1}{2A} (B \pm \sqrt{B^2 - 4AC})$$

$$A n^2 + A 0^4 - B n^2 + C = A n^2 \Rightarrow n^2 = \frac{A n^2 - C}{A n^2 - B + A}$$

代入得: $W^2 = 1 - \frac{X}{Q}$, $X = \frac{\omega_{pe}^2}{\omega^2}$, $Y = \frac{\Omega_{ce}}{\omega}$, $Q = 1 - \frac{Y^2 \sin^2 \theta}{2(1-X)} \pm \frac{X-1}{|X-1|} \left[\frac{Y^4 \sin^2 \theta}{4(1-X)^2} + Y^2 \cos^2 \theta \right]^{1/2}$

则可解出 n^2 , 有两组解, 对应于“+”、“-”.

X, O 模 — 右. 左旋电磁波 (左波).
 “+” = X, Z
 “-” = O, W. { — 快-慢 (— 高频-低频) 相速度 (同-快: O)

— 可逃逸模式. (有截止频率: ω_{pe}, ω_{RH}) (escaping modes)

Z, W 模 — Z 模与 Langmuir 波. 高频波 (UH/HH) 同支色散关系.

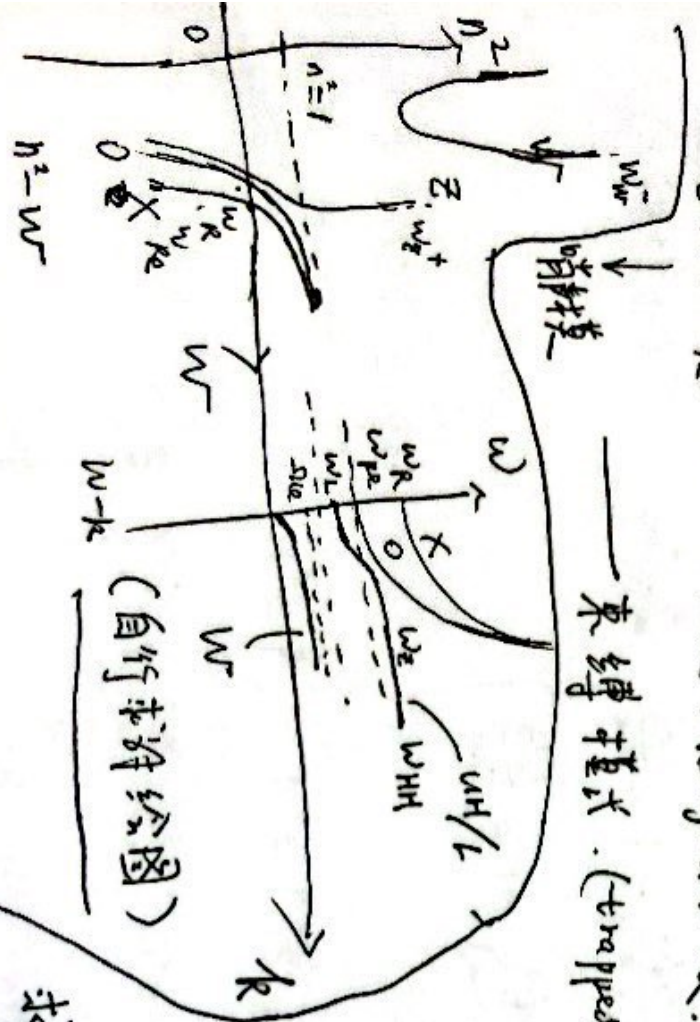
— 束缚模式. (trapped modes), 有截止, 有共振: { Z: $\omega_L, \omega_Z, (\omega+)$ W: 0, $\omega_W(\omega-)$

比较几个特征频率间的大小关系:

一般情况下的磁流体色散关系曲线

X O Z W

- ① $\omega - k$ 曲线
- ② $n^2 - \omega$ 曲线



求得色散关系后, 可根据 $\nabla \cdot \vec{E} = 0$ 得出各模式的场分量间大小及相位关系!

- $n^2 > 0$: 传播区 (高频, 低频)
- $n^2 = 0$: 截止区
- $n^2 < 0$: 截止区 (不传播区)

4.3 非磁化等离子体波动模式

($\mu_0 = \epsilon_0$), $\vec{B}_0 = 0$, 可取 $\theta = 0$ ($\vec{k} = k\hat{e}_z$), 得:

$$S = P = R = L = 1 - \frac{\omega_{pe}^2}{\omega^2}, D = 0.$$

$$\vec{N} \cdot \vec{E} = \begin{pmatrix} S - n^2 & 0 & 0 \\ 0 & S - n^2 & 0 \\ 0 & 0 & P \end{pmatrix} \begin{pmatrix} E_x \\ E_y \\ E_z \end{pmatrix} = 0 \Rightarrow \begin{cases} (S - n^2) E_x = 0 \\ (S - n^2) E_y = 0 \\ P E_z = 0 \end{cases}$$

$\Rightarrow n^2 = 1 - \frac{\omega_{pe}^2}{\omega^2} \Rightarrow \omega^2 = k^2 c^2 + \omega_{pe}^2$ ($E_x, E_y \neq 0$). 横波模式 ($\vec{k} \perp \vec{E}$), 电磁横波. $\omega > \omega_{pe}$
 $\left. \begin{matrix} P = 0 \Rightarrow \omega = \omega_{pe} \text{ (} E_z \neq 0 \text{)}, \text{ 纵波模式 (} \vec{k} \parallel \vec{E} \text{)}, \text{ 静电波. } \\ \text{Langmuir 波} \end{matrix} \right\}$

考虑热效应后: $\omega^2 = \omega_{pe}^2 + k^2 c_s^2$

4.3.1 由公式导出考虑热效应时的静电 Langmuir 波

$$\frac{\partial n e}{\partial t} + \nabla \cdot (n e \vec{v}_e) = 0$$

$$P e \frac{d \vec{v}_e}{d t} = - \nabla p_e - e n e \vec{E}$$

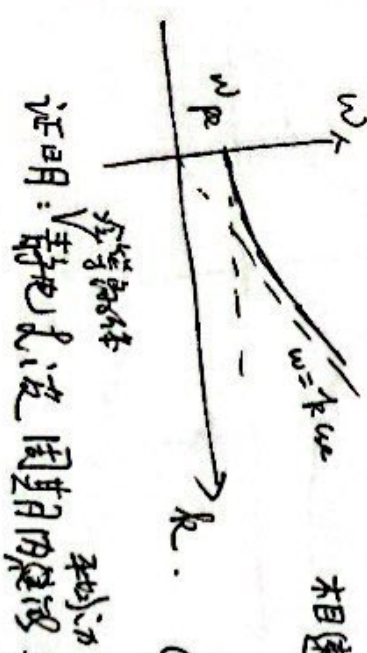
$$\nabla \cdot \vec{j} = \frac{e(N_0 - n_0)}{\epsilon_0} = - \frac{e n e'}{\epsilon_0}$$

$$\vec{E} = \frac{n e'}{N_0 \epsilon_0} = \frac{\vec{k} \cdot \vec{v}_e}{\omega}$$

$$i \omega p_e \vec{v}_e = i \vec{k} c_s^2 m_e n e' + e N_0 \vec{E} \Rightarrow i \omega p_e \vec{k} \cdot \vec{v}_e = i k^2 c_s^2 m_e n e' + e N_0 \vec{k} \cdot \vec{v}_e$$

$$i \vec{k} \cdot \vec{v}_e = - e n e' / \epsilon_0$$

纵波, $\vec{k} \parallel \vec{v}_e$, 回复力: 热压力, 电场力 (静电, 电荷分离), 不满足准中性 ($N_0 - n_0 = N_0 n_1' = 0$).



相速度 $\frac{\omega}{k}$, 若 $k^2 c_s^2 \ll \omega_{pe}^2$, 则 $\frac{\omega^2}{\omega_{pe}^2} = 1 + \frac{k^2 c_s^2}{\omega_{pe}^2} \Rightarrow \frac{\omega}{\omega_{pe}} = 1 + \frac{k^2 c_s^2}{2 \omega_{pe}^2}$. $\omega_y = \omega_{pe} + \frac{k^2 c_s^2}{2 \omega_{pe}}$
 $f_{pe} = \frac{N_0 k_0 T_e}{N_0 m_e} = v_{th}^2 \Rightarrow \omega_{pe} = \omega_{pe} + \frac{3 k^2 c_s^2}{2 \omega_{pe}}$

$\vec{v}_e = \frac{\rho_{e0} v_e}{2} e^{i(kz - \omega t)}$, 由 $\vec{v}_e \propto \vec{v}_e \exp(i\vec{k} \cdot \vec{r} - i\omega t) = \vec{v}_e \exp(i(kz - \omega t)) = \vec{v}_e [\cos(kz - \omega t) + i \sin(kz - \omega t)]$ ①

只取实部, 得动能密度为 $\frac{\rho_{e0} v_e^2 \omega^2}{2} \cos^2(kz - \omega t)$, 电场能量密度?

由 $i \omega \rho_{e0} \vec{v}_e = e n_{e0} \vec{E} \Rightarrow \vec{E} = \frac{i \omega \rho_{e0} m_e}{e} \vec{v}_e = \frac{i \omega m_e \rho_{e0}}{e} \cos(kz - \omega t) + i \sin(kz - \omega t)$, 取实部得 $\vec{E} = \frac{-i \omega m_e \rho_{e0}}{e} \sin(kz - \omega t)$

得 $\frac{\epsilon_0 E^2}{2} = \frac{\epsilon_0 \omega^2 m_e^2}{2 e^2} v_e^2 \sin^2(kz - \omega t)$, 二者之和为: $\frac{\rho_{e0} v_e^2 \omega^2}{2} \cos^2(kz - \omega t) - \frac{\epsilon_0 \omega^2 m_e^2}{2 e^2} v_e^2 \cos^2(kz - \omega t) + \frac{\omega^2 m_e^2 \rho_{e0}^2}{2 e^2 v_e^2}$

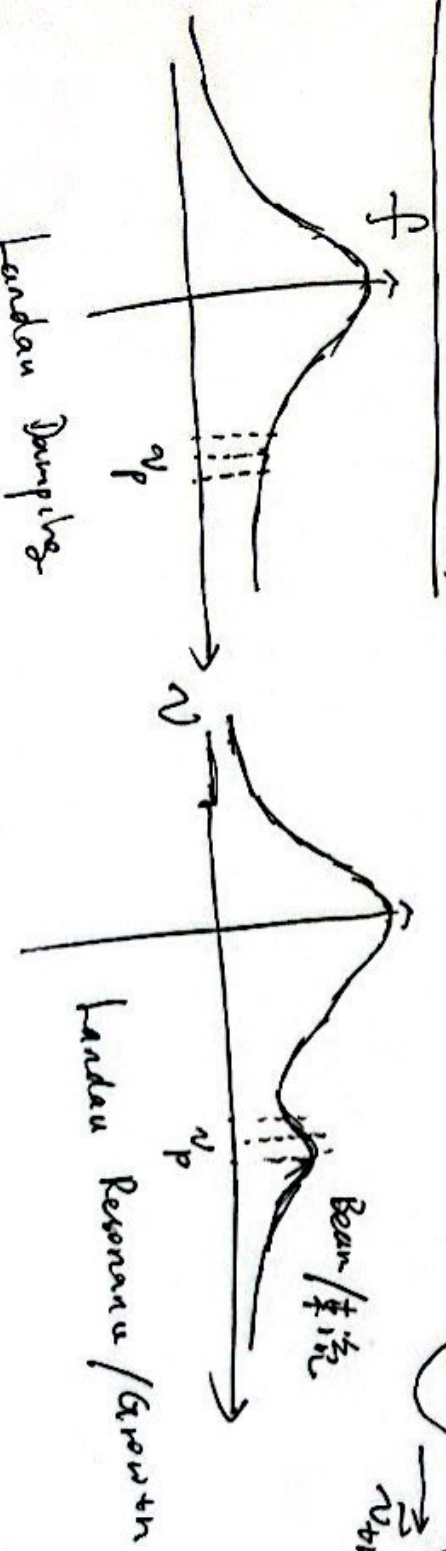
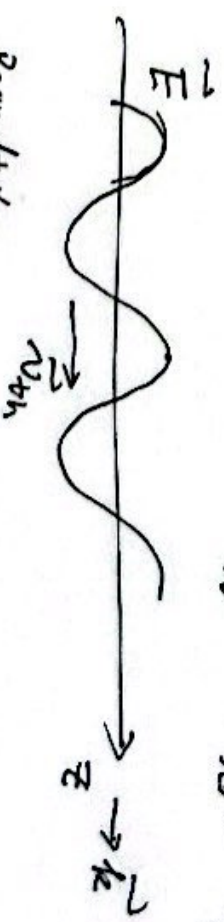
由 $\frac{\rho_{e0} v_e^2}{2} = W_0 \omega^2 (kz - \omega t)$ $\frac{\epsilon_0 \omega^2 m_e^2}{2 e^2} v_e^2 = \frac{\rho_{e0} v_e^2}{2} \cdot \omega^2 \frac{m_e \epsilon_0}{n_{e0} e^2} = \frac{\rho_{e0} v_e^2 \omega^2}{2} \frac{\omega^2}{\omega_{pe}^2} = \frac{\rho_{e0} v_e^2}{2} = W_0$

$\frac{\rho_{e0} v_e^2}{2} = W_0 \sin^2(kz - \omega t)$, $\frac{\rho_{e0} v_e^2}{2} + \frac{\epsilon_0 E^2}{2} = W_0$

证明: 考虑热致效应后, \vec{v}_e 有 \vec{v}_e 的能量交换于电子运动能量密度。 ($\frac{\epsilon_0 E^2}{2} / \frac{\rho_{e0} v_e^2}{2} = \frac{\omega_{pe}^2}{\omega^2} < 1$)

提示: $e n_{e0} \vec{E} = i \omega \rho_{e0} \vec{v}_e - i \vec{k} \epsilon_0 m_e n_e \vec{v}_e' = i \omega \rho_{e0} \vec{v}_e - i \epsilon_0^2 m_e n_{e0} k (\vec{k} \cdot \vec{v}_e) = i \omega \rho_{e0} \vec{v}_e - \frac{i \epsilon_0^2 m_e n_{e0}}{\omega}$

朗道阻尼 (Landau Damping) : $v_{th} \sim v_p = \omega/k$



无碰撞阻尼
波粒共振
波的耗散与增长
尾效应 (Bump-on-tail Instability)

4.3.2 非磁化等离子体电磁模式

$$\omega^2 = \omega_{pe}^2 + kc^2 \quad (n^2 = S)$$

$$\vec{k} \times (\vec{k} \times \vec{E}) = \omega^2 \vec{E} - kc^2 \vec{E}$$

$$\frac{\partial \vec{B}}{\partial t} + \nabla \times \vec{E} = 0$$

$$\nabla \times \vec{B} = \mu_0 \vec{j} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}, \quad \vec{j} = -en_0 v_e$$

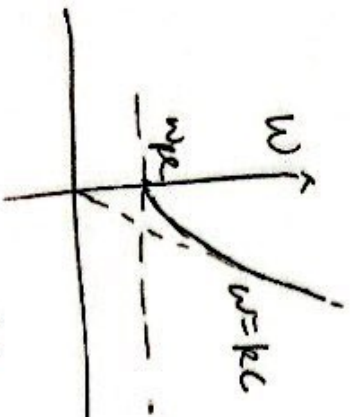
$$\rho_e \frac{dv_e}{dt} = -\nabla \cdot p_0 - en_0 \vec{E}$$

$$\left. \begin{aligned} \vec{k} \times \vec{E} &= \omega \vec{B} \\ i\vec{k} \times \vec{B} &= -en_0 \mu_0 v_e - i\mu_0 \epsilon_0 \omega \vec{E} = i\vec{k} \times (\vec{k} \times \vec{E}) / \omega \\ -i\omega n_0 m_e v_e &= -i\vec{k} \cdot \rho_e \frac{c^2}{\omega^2} - en_0 \vec{E} \Rightarrow v_e = \frac{-ien_0 \vec{E}}{\omega n_0 m_e} \end{aligned} \right\} \Rightarrow$$

考虑由磁扰动可忽略去压梯度的作用(对称); 得:

$$\frac{+ien_0 \mu_0}{\omega m_e} \vec{E} - i\frac{\omega}{c^2} \vec{E} = -i\vec{k} \times \frac{\vec{E}}{\omega}$$

$$\text{得: } \frac{\omega_{pe}^2}{c^2} - \frac{\omega^2}{c^2} + k^2 = 0 \Rightarrow \omega^2 = kc^2 + \omega_{pe}^2$$

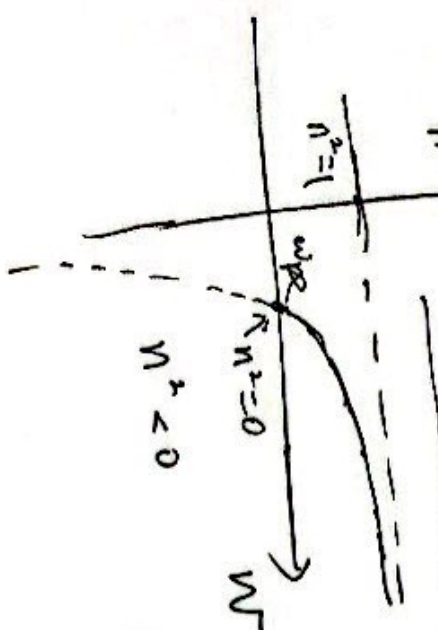


一截止频率 (ω 低于 ω_{pe} 时, 无传播)

$$(n^2 = \frac{kc^2}{\omega^2} = 1 - \frac{\omega_{pe}^2}{\omega^2} < 1, \text{ 折射率 } n^2 < 0)$$

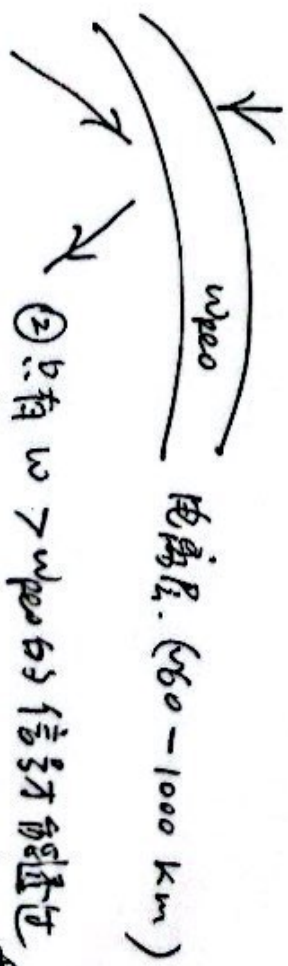
等离子体对电磁波的作用 (折射率小于 1 的介质)

ω > ω_{pe} 时, ω → kc (n² > 1) 逼近真空极限



n² > 0 传播区

① 无线电波的跨洋传播——电离层在的反射



② 只有 ω > ω_{pe0} 的信号才能通过

电离层传向地面, ③ 电离层探测

$$\left\{ \begin{aligned} \text{电场能量密度 } \frac{\epsilon_0 E^2}{2}, \quad \frac{u}{2\mu_0}, \quad \vec{k} \perp \vec{E} \Rightarrow \frac{E}{B} = \frac{\omega}{k} \Rightarrow \frac{\epsilon_0 E^2}{2} / \frac{B^2}{2\mu_0} = \frac{\omega^2}{k^2 c^2} \Rightarrow \text{若 } \omega^2 > k^2 c^2, \text{ 则 } \frac{\epsilon_0 E^2}{2} > \frac{B^2}{2\mu_0} \\ \frac{\epsilon_0 E^2}{2} / \frac{\rho_0 m_e v_e^2}{2} = \frac{\epsilon_0 E^2}{\rho_0 m_e v_e^2} = \frac{\epsilon_0 E^2 \omega^2 \mu_0^2 m_e^2}{\rho_0 m_e v_e^2} = \frac{\omega^2}{v_p^2} \end{aligned} \right.$$

若 $\omega^2 > \omega_p^2$, 则 $\frac{\epsilon_0 E^2}{2} > \frac{\rho_0 m_e v_e^2}{2}$

4.4 磁化等离子体静电模式 ($\omega_0 \neq 0, \vec{B}' = 0$)

$$\vec{k} \times \vec{E} = \omega \vec{B}' = 0, \quad \vec{B}' = 0, \quad k_{\parallel} \vec{E} \cdot \vec{E} = (k_{\parallel} E_{\parallel}) \cdot \vec{E} = k_{\parallel} E_{\parallel} \vec{e}_z + k_{\perp} E_{\perp} \vec{e}_z, \quad \frac{k_{\parallel} E_{\parallel}}{E_{\parallel}} = \frac{k_{\parallel} E_{\parallel}}{E_{\parallel}}$$

$$\omega \vec{k} \times \vec{B} = k \times (k \times \vec{E}) = (k_{\parallel} \vec{k} - k^2 \vec{I}) \cdot \vec{E} = -\frac{\omega^2}{c^2} \vec{E} \cdot \vec{E} = 0 \quad (\text{一般形式, 引入了更严格的限制})$$

再用一个方程便可描述电场. $\vec{\epsilon} \cdot \vec{E} = 0$ (相对于将所写方程投影在 \vec{e}_z 方向).

$$\vec{\epsilon} \cdot \vec{E} = \begin{pmatrix} \epsilon - \text{id} & 0 & 0 \\ 0 & \epsilon & 0 \\ 0 & 0 & \epsilon \end{pmatrix} \cdot \begin{pmatrix} E_x \\ 0 \\ E_z \end{pmatrix} = 0 \Rightarrow \begin{cases} \epsilon E_x = 0 \\ \text{id} E_x = 0 \\ \epsilon E_z = 0 \end{cases}$$

由 $\vec{\epsilon} \cdot \vec{E} \cdot \vec{k} = 0 \Rightarrow \epsilon E_x k_x + \epsilon E_z k_z = 0$

也可由方程组导出:

一般形式

$$\frac{\partial m_e'}{\partial t} + n_0 \nabla \cdot \vec{v}_e = 0$$

$$n_0 m_e \frac{\partial \vec{v}_e}{\partial t} = -e n_0 (\vec{E} + \vec{v}_e \times \vec{B}_0)$$

$$\nabla \times \vec{E} = 0 \quad (k_{\parallel} \vec{E})$$

$$\nabla_{\parallel} j + \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t} = 0, \quad \vec{j} = -e n_0 \vec{v}_e \quad (\nabla_{\parallel} \vec{E})$$

$$\nabla \cdot \vec{E} = -\frac{e n_e'}{\epsilon_0}$$

快速采用 E_x 表示:

$$-i \omega n_0 m_e v_{ex} = -e n_0 (E_x + v_{ey} B_0) = -e n_0 (E_x + \frac{i \omega v_{ex}}{\omega_c})$$

$$v_{ey} = \frac{i e v_{ex} B_0}{\omega m_e} = i \frac{\omega_c}{\omega} v_{ex}$$

$$-i \omega n_0 m_e v_{ez} = -e n_0 E_z = -e n_0 \frac{k_z}{k_x} E_x$$

$$\Rightarrow \begin{cases} v_{ex} = -\frac{e E_x}{m_e (-i \omega + i \omega_c)} \\ v_{ez} = \frac{e}{i \omega m_e} \frac{k_z}{k_x} E_x \end{cases}$$

再由安培定律或泊松方程 $i(k_x E_x + k_z E_z) = -\frac{e n e'}{\epsilon_0} = -\frac{e n_0}{\omega \epsilon_0} (k_x v_{ex} + k_z v_{ez})$, 代入可得 $\begin{cases} 1 - \frac{\omega p_e^2}{\omega^2} = -\left(1 - \frac{\omega p_e^2}{\omega^2}\right) \\ \tan^2 \theta = \frac{k_x^2}{k_z^2} \end{cases}$

$\theta = 0^\circ, \rho = 0, \text{Langmuir 波 } (E_z \neq 0, E_x = 0)$

$\theta = 90^\circ, S = 0. (E_x \neq 0, E_z = 0)$

$\omega^2 = \omega p_e^2 + \omega e^2$. 高频频率.

当 $\omega^2 \gg \omega p_e^2$ 时, 可化简一般情况色散关系: $\omega^2 = \omega p_e^2 + \omega e^2 \sin^2 \theta$, θ 为 k, \vec{B}_0 夹角.

4.5 磁化等离子体电磁模式. $(\tan^2 \theta = \frac{\rho(n^2 - R)(n^2 - L)}{\cos^2 \theta (S n^2 - RL)} : \text{Aliev 形式})$.

平行 ($\vec{k} \parallel \vec{B}_0$): $n^2 = R, n^2 = L$; 垂直 ($\vec{k} \perp \vec{B}_0$): $n^2 = \rho, n^2 = R/L$

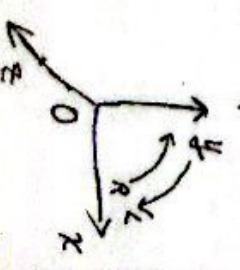
由电场方程: $\nabla \cdot \vec{E} =$

$$\begin{pmatrix} S - n^2 \cos^2 \theta & -iD & n^2 \sin \theta \cos \theta \\ iD & S - n^2 & 0 \\ n^2 \sin \theta \cos \theta & 0 & \rho - n^2 \sin^2 \theta \end{pmatrix} \begin{pmatrix} E_x \\ E_y \\ E_z \end{pmatrix} \Big|_{\theta=0} = \begin{pmatrix} S - n^2 & -iD & 0 \\ iD & S - n^2 & 0 \\ 0 & 0 & \rho \end{pmatrix} \begin{pmatrix} E_x \\ E_y \\ E_z \end{pmatrix}$$

$\theta = 0 \Rightarrow \begin{cases} (S - n^2) E_x - iD E_y = 0 \Rightarrow E_x = \frac{iD}{S - n^2} E_y \\ iD E_x + (S - n^2) E_y = 0 \Rightarrow E_x = -\frac{iD}{S - n^2} E_y \end{cases} \Rightarrow (S - n^2)^2 D^2 \Rightarrow \text{① } S - n^2 = iD \Rightarrow \begin{cases} n^2 = R \\ n^2 = L \end{cases}$

$\rho E_z = 0 \Rightarrow \rho = 0 (E_z \neq 0)$. 静电 Langmuir 波, 不再讨论.

$|\vec{E}| = 1 \Rightarrow$ 圆偏振, $E_x = i E_y$ 对应于 $\underline{\text{左旋}}$, $E_x = -i E_y$ 对应于 $\underline{\text{右旋}}$.



左右旋简率判定: $\vec{E} = \vec{E}_x e^{i(\vec{k}\cdot\vec{r}-\omega t)} = \vec{E}_x \omega (\vec{k}\cdot\vec{r} - \omega t) + i \vec{E}_x \sin(\vec{k}\cdot\vec{r} - \omega t) = \vec{E}_x \omega \varphi + i \sin \varphi$ ⑩

$E_y = -i \vec{E}_x (\vec{E}_x = i \vec{E}_y)$ 时, $E_y = \vec{E}_x (-i \omega \varphi + \sin \varphi)$

t_1 时刻($\varphi = 0$)时, $\varphi = 0$, $E_y = \vec{E}_x \omega$, t_2 ($> t_1$)时刻, ($\varphi = -\frac{\pi}{2}$)时, $E_x \sim 0$, $E_y \sim -\vec{E}_x$

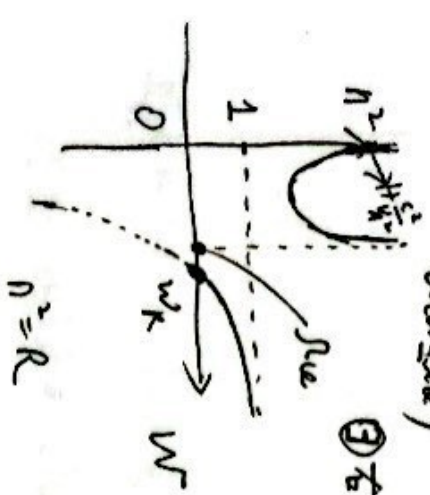


右旋: $n^2 = R = 1 - \frac{\omega_{pe}^2}{\omega(\omega + \omega_c)}$ ①由 $n^2 = 0$, $\omega = \omega_c$

$\omega_R = \frac{\omega_c}{2} + \sqrt{\omega_{pe}^2 + \frac{\omega_c^2}{4}}$, 右旋截止频率

②由 $n^2 \rightarrow \infty$ 得 $\omega \sim \omega_c$, 对应于(右旋)电子回旋共振

③右旋波低频率极限 $\omega \rightarrow 0$ 时, 需考虑离子效应, $n^2 = 1 - \sum \frac{\omega_{pi}^2}{\omega(\omega + \omega_{ci})}$



(低频)右旋剪切 Alfvén 波

④ 高频极限: $n^2 = 1$ ($\omega = kc^2$)

存在两组射线: $\omega > \omega_R$ 时, 右旋高频电磁波

$\omega < \omega_c$ 时, 电子回旋波 (Whistler mode)

$\omega_c < \omega < \omega_R$ 时, 无波 (截止区), $n^2 < 0$

无背景场时, $B_0 = 0$ 时: $n^2 = 1 - \frac{\omega_{pe}^2}{\omega^2}$

分析: 为 $\omega > \omega_R$ 在 $\omega < \omega_c$ 区间出现 $n^2 < 0$ 与 $n^2 > 1$ 的波? 分析: $n^2 > 1$ (ω_{upper})

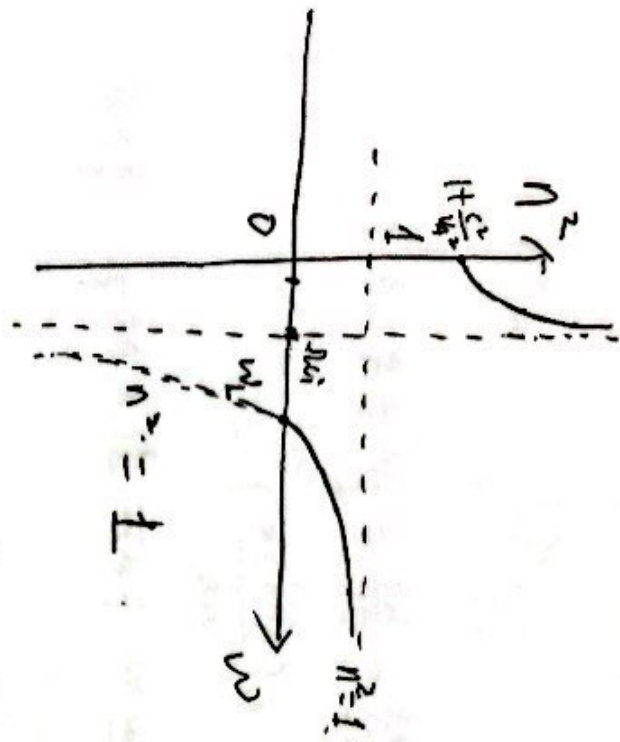
并不合适, 忽略得太彻底了!

$n^2 \approx 1 + \frac{\omega_{pe}^2}{\omega \Omega_{ci}} (1 + \frac{\omega}{\Omega_{ci}}) - \frac{\omega_{pi}^2}{\omega \Omega_{ci}} (1 - \frac{\omega}{\Omega_{ci}})$

$= 1 + \frac{\omega_{pe}^2}{\omega \Omega_{ci}} + \frac{\omega_{pi}^2}{\omega \Omega_{ci}^2} = 1 + \frac{c^2}{\omega \Omega_{ci}^2} (\frac{\omega_{pe}^2}{\omega} + \frac{\omega_{pi}^2}{\omega^2})$

$= 1 + \frac{c^2}{\omega^2} \frac{\omega_{pe}^2}{\Omega_{ci}^2}$

左旋: $n^2 = L = 1 - \frac{\omega_{pe}^2}{\omega(\omega + \Omega_{ce})}$, ① 由 $n^2 = 0$, 得 $\omega_L = -\frac{\Omega_{ce}}{2} + \sqrt{\frac{\Omega_{ce}^2}{4} + \omega_{pe}^2}$, 左旋截止频率



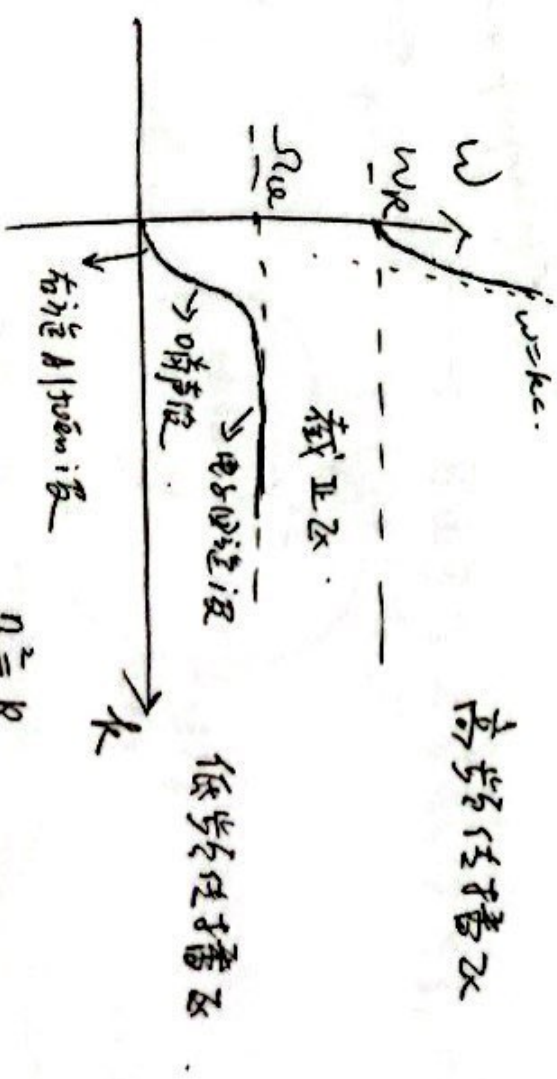
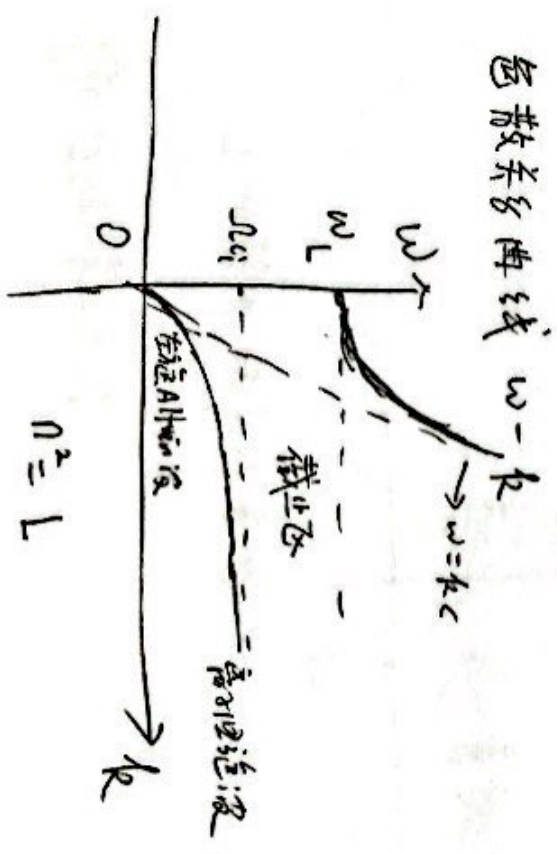
② 由 $n^2 \rightarrow \infty$, 得 ω_{ci} , 需考虑离子回旋共振 $\omega \rightarrow \Omega_{ci}$, 离子回旋共振 (左旋离子回旋波)

③ 低频率极限 $\omega \rightarrow k^2 v_A^2$, (低频率左旋剪切 Alfvén 波)

④ 无磁切. 真空极限. Okay.

$\Omega_{ci} < \omega_L < \omega_{UH}$: 左旋波截止区.

作图: 比较 $\omega_{pe}, \omega_{UH}, \omega_{UH}, \omega_L, \omega_R, \omega_{pe}$ 大小关系.



高频传播区

低频率传播区

① 电子回旋共振、离子回旋共振 \rightarrow 波粒共振相互作用, (12)

② 哨声波: ω 略低于 Ω_e , why whistler? $\frac{n^2 - \omega^2}{\omega^2}$ 非常小...

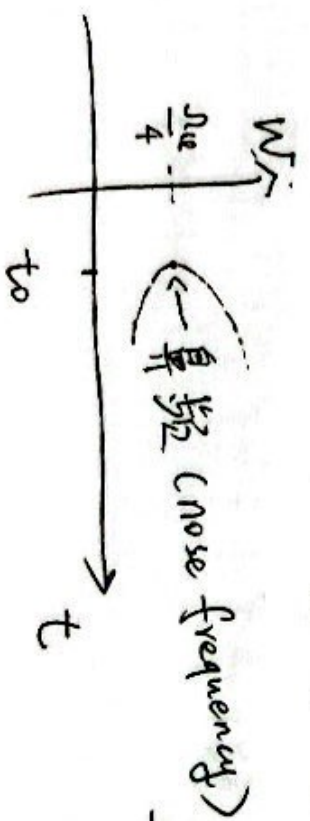
$$n^2 = 1 - \frac{\omega_{pe}^2}{\omega(\omega - \Omega_e)}, \quad \text{if } \frac{\omega_{pe} \omega}{\omega - \Omega_e} \ll c, \quad \text{得 } n \sim \frac{\omega_{pe}}{[\Omega_e(\omega - \Omega_e)]^{1/2}}, \quad \frac{v_p}{c} \sim \frac{[\Omega_e(\omega - \Omega_e)]^{1/2}}{\omega_{pe}}$$

得群速度 $v_g = \frac{d\omega}{dk} = \left(\frac{dk}{d\omega}\right)^{-1}$

$$= \left(\frac{d(n\omega/c)}{d\omega}\right)^{-1} = \frac{c}{\omega \frac{dn}{d\omega} + n} \approx \frac{2c}{\omega_{pe} \Omega_e} \omega^{1/2} (\Omega_e - \omega)^{3/2} \quad \text{[自行推导、验证]}$$

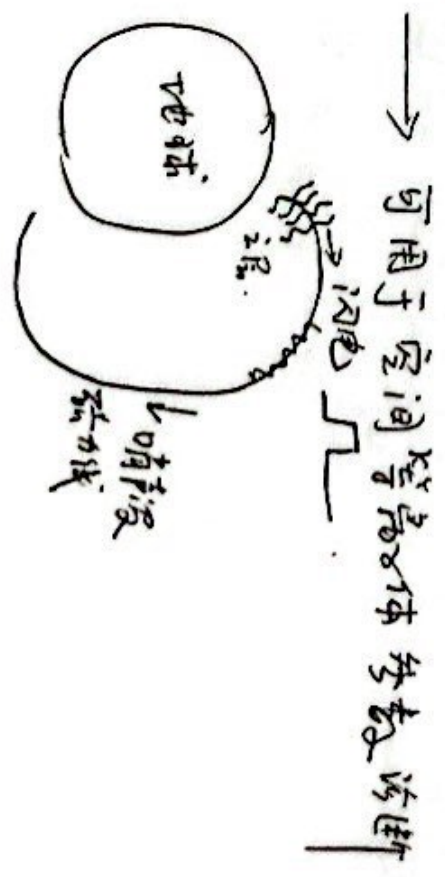
可得 v_g 极大值对应于 $\omega = \Omega_e/4$, 即 $\omega \leq \Omega_e/4$ 时, $v_g(\omega)$ 随 ω 而 \uparrow , $\omega > \Omega_e/4$ 时, $v_g(\omega)$ 随 ω 而 \downarrow .

某处台站, 接收空间电磁信号. ($\Omega_e + kH$) 直接转为音频 \rightarrow 哨声 ($\omega = \Omega_e/4$, 高频共振达)



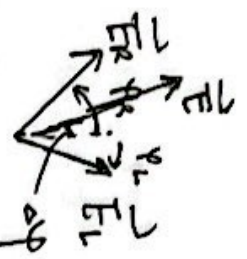
上网聆听哨声波音频.

③ 法拉第旋转



线偏振 \leftrightarrow 左、右旋圆偏振 (同 ω), 在传播方向, $n_R \neq n_L$, \vec{E} 发生旋转。

$$\vec{E} = \vec{E}_L + \vec{E}_R$$



$$\Delta\varphi = \frac{\varphi_R - \varphi_L}{2} = \varphi_R - \frac{\varphi_R + \varphi_L}{2}$$

$$\left. \begin{aligned} \vec{E}_L &= E_0/\sqrt{2} (\hat{x} - i\hat{y}) \exp(i(\vec{k}_L \cdot \vec{r} - \omega t)) \\ \vec{E}_R &= E_0/\sqrt{2} (\hat{x} + i\hat{y}) \exp(i(\vec{k}_R \cdot \vec{r} - \omega t)) \end{aligned} \right\}$$

$$\Delta\varphi = \left[\frac{\varphi_R - \varphi_L}{2} \right] = \frac{(k_R - k_L)z}{2}, \quad \text{得: } n_R = \frac{k_R c}{\omega} \sim \sqrt{1 - \frac{\omega_{pe}^2}{\omega(\omega - \Omega_e)}}$$

$$\therefore \Delta\varphi = \frac{\omega_{pe}^2}{c^2} \left(\frac{\omega_{pe}^2}{2\omega(\omega + \Omega_e)} - \frac{\omega_{pe}^2}{2\omega(\omega - \Omega_e)} \right)$$

$$|\Delta\varphi| = \frac{\omega_{pe}^2}{2c} \frac{\omega_{pe}^2 \Omega_e}{\omega^2 (\omega^2 - \Omega_e^2)} \sim \frac{z \omega_{pe}^2 \Omega_e}{2c \omega^2} \propto (n_D, z, B_0, \omega)$$

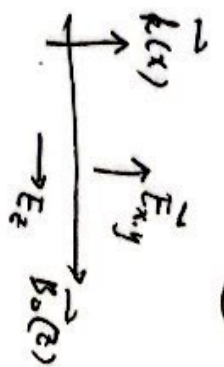
$$n_L = \frac{k_L c}{\omega} \sim \sqrt{1 - \frac{\omega_{pe}^2}{\omega(\omega + \Omega_e)}}$$

则可基于 $\Delta\varphi$ 测量, 推断等离子体参数性质。
 ① 天文射电源、行星际介质、相位变化
 ② 等离子体诊断

IPS

4.5.2 垂直传播: $n^2 = p$, $n^2 = R/L/S$.

$$\vec{\nabla} \cdot \vec{E} = \begin{pmatrix} S & -iD & 0 \\ iD & S-n^2 & 0 \\ 0 & 0 & p-n^2 \end{pmatrix} \cdot \begin{pmatrix} E_x \\ E_y \\ E_z \end{pmatrix} = 0 \Rightarrow \begin{cases} SE_x - iDE_y = 0 \\ iDE_x + (S-n^2)E_y = 0 \\ (p-n^2)E_z = 0 \end{cases}$$



1° $p=n^2 \Rightarrow \omega^2 = k^2 c^2 + \omega_{pe}^2$, $E_z \neq 0$. 此种 \vec{B}_0 的电磁波, \vec{E}_{xy} 与 \vec{B}_0 的情况相同. \rightarrow Ordinary Mode

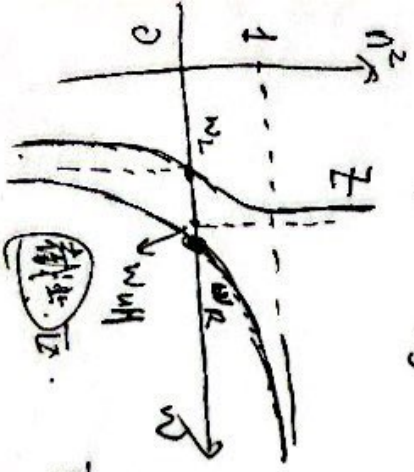
2° $n^2 = R/L/S$, $SE_x = iDE_y$, $(iD/S) + (S-n^2) = 0 \Rightarrow n^2 = R/L/S$, $E_x = \frac{iD}{S} E_y$, $\begin{cases} D/S > 0 \text{ 时, 左旋椭圆偏振} \\ D/S < 0 \text{ 时, 右} \dots \end{cases}$

$$\frac{D}{S} = \frac{\omega_{pe}^2 \omega_e}{\omega(\omega^2 - \omega_{UH}^2)} \sqrt{1 - \frac{\omega_{pe}^2}{n^2 - \omega_e^2}} = \frac{\omega_{pe}^2 \omega_e}{(\omega^2 - \omega_{UH}^2) \omega} \sqrt{1 - \frac{\omega_{pe}^2}{n^2 - \omega_e^2}} \left(1 - \frac{\omega_{pe}^2}{\omega(\omega^2 - \omega_{UH}^2)}\right) = 1 - \frac{\omega_{pe}^2}{\omega^2 - \omega_e^2}$$

$$\text{可化为 } \frac{D}{S} = \frac{\omega_{pe}^2 (\omega^2 - \omega_{UH}^2) (-\omega \omega_e)}{(\omega^2 - \omega_{UH}^2) \omega^2} = \frac{\omega_{pe}^2 \omega_e}{\omega^2 - \omega_{UH}^2}$$

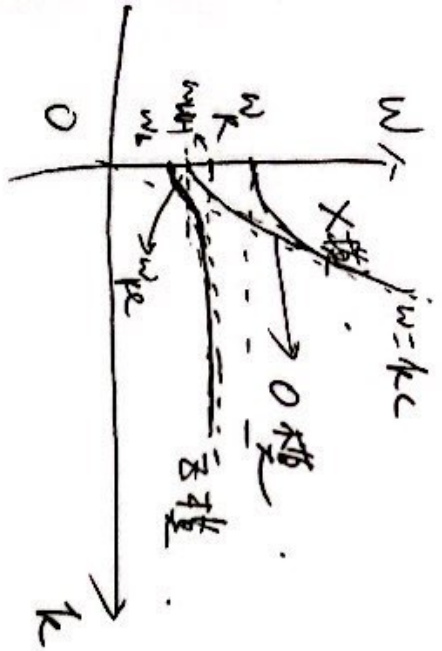
$$\frac{D}{S} = (n^2 - 1) \frac{\omega \omega_e}{\omega^2 - \omega_{UH}^2}, \text{ RP 当 } \begin{cases} \textcircled{1} (n^2 - 1) (\omega^2 - \omega_{pe}^2) > 0 \text{ 时, 为左旋} \\ \textcircled{2} (n^2 - 1) (\omega^2 - \omega_{UH}^2) < 0 \text{ 时, 为右旋} \end{cases}$$

$n^2 = R/L/S = 0$. 截止频率 $\begin{cases} R=0, \omega_R \rightarrow \text{高频传播的波的截止频率} \\ L=0, \omega_L \rightarrow \text{左旋的截止频率} \end{cases}$ (X模)



Z 模截止: $n^2 = \frac{R/L}{S} \rightarrow \infty$, $S=0 \Rightarrow 1 = \frac{\omega_{pe}^2}{\omega^2 - \omega_{UH}^2} \Rightarrow \omega^2 = \omega_e^2 + \omega_{UH}^2 = \omega_{UH}^2$ 高频左旋

$E_x = \frac{iD}{S} E_y$, 故左旋时有 $E_x \gg E_y \Rightarrow \vec{k} \parallel \vec{E} \Rightarrow$ 静电 (左旋时趋于静电场)



⑭ X 扰动与 Z 扰动的差异是由磁场的不均匀造成的， $\vec{B}_0 \perp \vec{v}$ 时， $\omega^2 = k^2 v_A^2 + \omega_{pe}^2$ 右旋 或 $n^2 = 1 - \frac{\omega_{pe}^2}{\omega^2}$

对于 Z 扰动， $n^2 = 1$ 时， $k_L = S$ ，有得：

$$\left(1 - \frac{\omega_{pe}^2}{\omega(\omega - \Omega_{ce})}\right) \left(1 - \frac{\omega_{pe}^2}{\omega(\omega + \Omega_{ce})}\right) = \frac{(\omega^2 - \omega_{pe}^2)(\omega^2 - \omega_{ce}^2)}{\omega^2(\omega^2 - \Omega_{ce}^2)} = 1 - \frac{\omega_{pe}^2}{\omega^2 - \omega_{ce}^2}$$

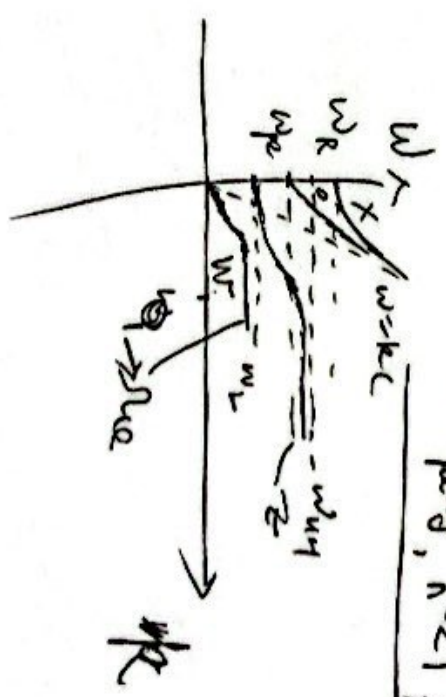
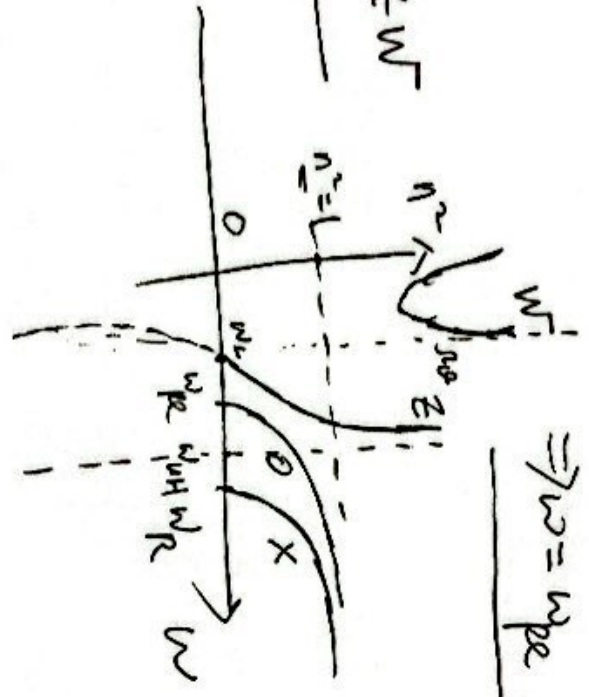
高频极限 $\omega = k_{ce}$

$\Rightarrow \omega = \omega_{pe}$. 则对于 Z 扰动： $\omega > \omega_{pe}$ 时， $n^2 > 1$ 左旋

$\omega < \omega_{pe}$ 时， $n^2 < 1$ 右旋

一般情况， $X \neq Z$

磁离子理论



4.6 低频近似 ~~静电波~~ ($\omega \ll \Omega_e, \omega_{pe}$, 设 $v_p \ll c_{se}$, 即相速远小于电子热速, 可略去电子惯性项) (15)

4.6.1 非磁化情况 ($B_0 = 0, B_1 = 0$): 离子声波与离子 ~~Langmuir~~ ~~Langmuir~~ ~~Langmuir~~ 波.

$$\left\{ \begin{aligned} \frac{\partial n_i'}{\partial t} + n_0 \nabla \cdot \vec{v}_i' &= 0, & \frac{\partial n_e'}{\partial t} + n_0 \nabla \cdot \vec{v}_e' &= 0 \Rightarrow \omega n_e' \sim n_0 k v_e < \cancel{\omega n_e'} \\ -\nabla \cdot \vec{p}_e' - e n_0 \vec{E} &= 0 & (v_p \ll c_{se}, \text{ 可略去 } n_0 m_e \frac{\partial \vec{v}_e'}{\partial t} \sim \omega n_0 m_e \vec{v}_e, & -\nabla p_e' \sim k n_0 m_e c_{se}^2, \left| \omega n_0 m_e \vec{v}_e \right| \ll \left| \frac{k^2 n_0 T_e}{\omega} \right| \\ n_0 m_i \frac{\partial \vec{v}_i'}{\partial t} &= -\nabla \phi_i' + e n_0 \vec{E} \\ \nabla \cdot \vec{E}' &= e (n_i' - n_e') / \epsilon_0 \end{aligned} \right.$$

$$\Rightarrow \left\{ \begin{aligned} \frac{n_i'}{n_0} &= \frac{k v_i'}{\omega} \\ n_e' &= \frac{i e n_0 \vec{E}}{k \gamma_e k T_e} = \frac{i e n_0 \vec{E}}{k c_{se}^2 m_e} \\ n_i' &= \frac{i e n_0 \vec{E}}{\omega^2 m_i / k - k c_{s_i}^2 m_i} \\ i k E &= \frac{e (n_i' - n_e')}{\epsilon_0} \end{aligned} \right. \Rightarrow | = \frac{\omega p_i^2}{\omega^2 - k^2 c_{s_i}^2} - \frac{\omega p_e^2}{k^2 c_{se}^2} \Rightarrow \omega^2 = k^2 \left[c_{s_i}^2 + \frac{c_{se}^2 \omega p_i^2}{\omega_{pe}^2 + k^2 c_{se}^2} \right]$$

且有 $\frac{n_e'}{n_i'} = \frac{\omega^2 - k^2 c_{s_i}^2}{k^2 c_{se}^2 \frac{m_e}{m_i}} = \frac{1}{1 + \gamma_e k^2 \lambda_{De}^2}$

V_s^2 (离子声速)

$\omega_{pe}^2 = \frac{\omega^2}{k^2} \ll c_{se}^2$

$\lambda_{De}^2 = \frac{v_{the}^2}{\omega_{pe}^2}$

1) 长波近似, $\lambda \gg \lambda_{De}$, 得 $k \lambda_{De} \ll 1$, $n_e' / n_i' = 1$, 准中性条件满足.

得 $\omega^2 = k^2 \left(c_{s_i}^2 + \gamma_e \frac{k T_e}{m_i} \right)$ 电子热压力通过电场传至离子上.

$V_s^2 = c_{s_i}^2 + c_{se}^2 \frac{m_e}{m_i}$ 离子声速 $T_e \sim 0$ 时, 仍有离子声速 (Ion Acoustic Mode)

2) 短波近似 ωk , $\lambda \ll \lambda_D$, 得 $\omega^2 = k^2 c_s^2 + \frac{v_e k_{Te} / m_i \omega_p^2}{v_e k_{Te} / m_e \omega_p^2} = k^2 c_s^2 + \omega_{pi}^2$. 离子 Langmuir 波.

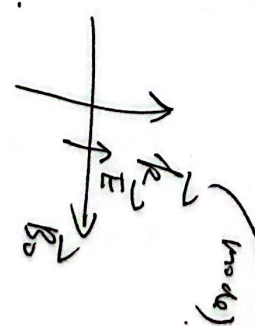
$\frac{n_e'}{n_e} \sim v_e |k_{Te}| \gg 1$, 此时 电子无法维持 (Why?), 电子不动, 离子静电振荡 (热压/静电均与背景)

离子声波的 Landau 阻尼: $v_s \sim v_{thi} = \sqrt{\frac{k_{Te}}{m_i}}$, 当 $T_e \sim T_i$ 时, 强阻尼; 当 $T_e \gg T_i$ 时, 阻尼较弱.

4.6.2 磁化情况 $C_{B_0} \neq 0$, $\vec{v}' = 0$: 低杂静电波与静电离子回旋波 (Electrostatic Ion Cyclotron)

只讨论长波情况, 无电荷分离 ($n_i' = n_e'$)

1) 平行传播 ($k \parallel B_0$) 时, 磁场所不起作用, 与非磁化情况相同.



2) 垂直传播或准垂直传播情况 ($k \perp B_0$) 时, $\vec{r} \perp \vec{B}_0$. $\vec{v} = k_x \hat{x}$, 则 $\vec{E} = E_x \hat{x}$. 可知 Lorentz 力影响波的振荡, 有关线性化. FT 后的方程组为:

$$\frac{n_e'}{n_0} = \frac{k_x v_x}{\omega}$$

$$-i \omega n_{meVex} = -i k_x c_e^2 m_e n_e' - e n_0 E_x - e n_0 B_0 v_y$$

$$-i \omega n_{omeVey} = e n_0 v_x B_0$$

$$\text{同样可得: } n_{ix} \left(1 - \frac{\omega_{ci}^2}{\omega^2} - \frac{k_x^2 c_s^2}{\omega^2} \right) = \frac{v_x e E_x}{m_i \omega}$$

$$\text{由 } n_i' = n_e' \text{ 得 } v_{ex} = v_{ix}, \text{ 得 } \omega^2 = \omega_{ce} \omega_{ci} + k_x^2 v_s^2, \omega_s^2 = c_s^2 + \frac{v_e k_{Te}}{m_i}$$

ω_{LH}^2 低杂频率, 如何理解这一个低杂频率的出现/意义?

低杂波率的物理意义: $\omega_{UH} \gg \Omega_{ci}$, $\omega_{UH} < \Omega_{ce}$. 故该静电振荡对于离子与电子“快”“慢”不同. (17)

对于离子, 快, 故离子在波中主要表现随 E 的快速振荡;
对于电子, 慢, 故电子在波中主要表现随 E 的慢速振荡.

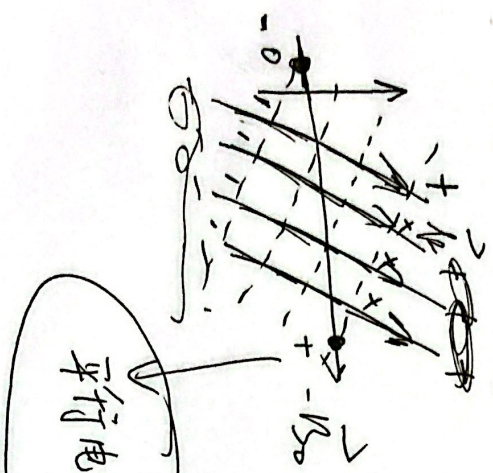
假设漂移运动:

$$\frac{dx_e}{dt} = \frac{m_e}{eB^2} \frac{dE}{dt} \sim \left| \omega \frac{m_e}{eB^2} E \right| = \left| \omega x_e \right|$$

准中性要求 $n_i = n_e$, 得: $\frac{m_e}{eB^2} = \frac{e}{m_i \omega^2} \Rightarrow \omega^2 = \Omega_{ce} \Omega_{ci} = \omega_{UH}^2$. 即电子在 x 方向的机械漂移. 要由

离子在电场 E 作用下的相同振荡

当 \vec{k} 与 \vec{v} 垂直时, 不需要如此中和方式:



$\vec{k} \parallel \vec{E}$, 则电场有平行于 \vec{k} 的分量 (E_{\parallel}), 在 E_{\parallel} 作用下

电子将做往返运动, 即可中和静电扰动. 此时仍使用 x 方向电子运动

便可忽略离子扰动. 运动方程:

$$C \text{ 设 } v_{the} \gg v_p \Rightarrow E_x = -\frac{ik_x c e^2 m_e n_e' - e n_i E_y}{e n_0}$$

$$n_i x \left(1 - \frac{\Omega_{ci}^2}{\omega^2} - \frac{k^2 c_s^2}{\omega^2} \right) = 0 \Rightarrow \frac{k_x c e^2 m_e n_e'}{m_i n_0 \omega} , \frac{n_i'}{n_0} = \frac{k_x v_{th}}{\omega}$$

$$\omega^2 = \Omega_{ci}^2 - k^2 c_s^2 = \frac{k_x^2 c_s^2 m_e}{m_i} \Rightarrow \omega^2 \approx \Omega_{ci}^2 + k^2 v_s^2$$

(长波)

静电离子回旋波与低杂波在维持电中性方面具有不同的物理: 垂直向下平行电场导致离子快速运动. 与垂直情况下的慢速电子漂移.

$n_i' = n_e'$

第5章 等离子体不稳定性简介

5.1 基本概念与研究方法简介

平衡 (Equilibrium) 与稳定性 (Stability):



不稳定性 (Instability): 受到扰动时, 扰的作用会使扰动幅度增大。—— 正反馈 (Feedback)

自由能 (Free energy) 宏观不稳定性 (MHD. 空间分布不均匀等)、微观不稳定性 (速度分布不均)

类型: 香肠 (sausage)、扭曲 (kink)、水龙带 (firehose)、气球模 (balloon)、磁静电、RT (Rayleigh-Taylor)、KH (Kelvin-Helmholtz)、Streaming Instability / Tearing-mode Instability.



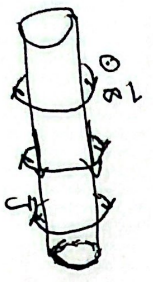
分析方法: 直观分析 (定性) 能量原理 (MHD系统)

色散关系: 扰动幅度随时间增长, 小扰动, 线性化 (仅适用于线性增长阶段)

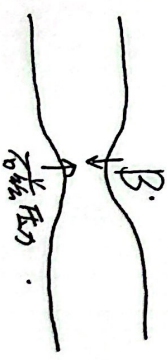
$$A(t) \exp(-i\omega t - \gamma \cdot \vec{r} \cdot \vec{r}), \quad A(t) = A_0 e^{i\omega t} = A_0 e^{-i \cdot \vec{r} \cdot \vec{r} \cdot \omega t}, \quad \text{得 } A(t) = A_0 e^{i(\vec{k} \cdot \vec{r} - \omega t)}$$

$$\text{令 } \omega = \omega_r + i\gamma, \quad A(t) = A_0 e^{\gamma t} e^{i(\vec{k} \cdot \vec{r} - \omega_r t)}, \quad \text{故傅里叶法仍可选用!}$$

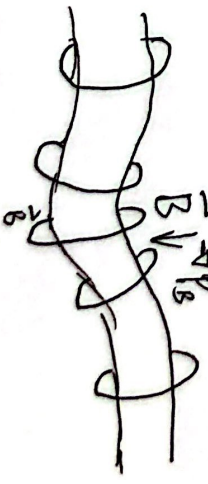
5.2 磁约束等离子体的箍缩与扭曲不稳定性



① 某处内缩, $B \uparrow$, 使内缩 ~~更~~ 继续, 如何致稳?



② 某处弯曲, 磁压力使之继续弯曲, 致稳.



5.3 Rayleigh-Taylor 和 Kelvin-Helmholtz 不稳定性 (头重脚轻 top-heavy 与速度剪切 Velocity shear)

查 < Bilibili 视频 >

5.3.1 RT 不稳定性: 从流体力学到磁流体力学
 双层流体, 分别均匀, 但在分界面有参数 (密度) 跃变, $\vec{g} = (0, 0, -g)$

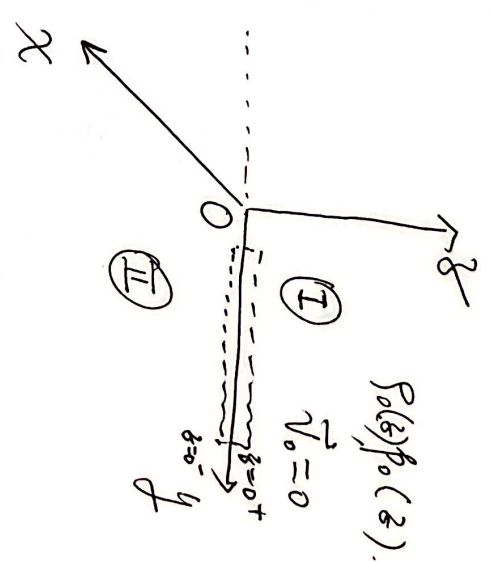
HD 方程组:

$$\begin{cases} \frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{v}) = 0 \\ \frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{v}) + (\gamma - 1) \rho \nabla \cdot \vec{v} = 0 \\ \rho \frac{d\vec{v}}{dt} = -\nabla p + \rho \vec{g} \end{cases}$$

小扰动线性 \Rightarrow "线性化"

$$\begin{cases} \frac{\partial \rho'}{\partial t} + \rho_0 \nabla \cdot \vec{v}' + \vec{v}' \cdot \nabla \rho_0 = 0 \\ \frac{\partial \rho'}{\partial t} + \rho_0 \nabla \cdot \vec{v}' + \vec{v}' \cdot \nabla \rho_0 + (\gamma - 1) \rho_0 \nabla \cdot \vec{v}' = 0 \\ \rho_0 \frac{\partial \vec{v}'}{\partial t} = -\nabla p' + \rho' \vec{g} \end{cases}$$

考虑界面在 $x=0$ 处, 考虑界面平衡项



Fourier Transform: 注意子方向 \vec{k} 是波数, 有 $\vec{k} = k_x \vec{e}_x + k_y \vec{e}_y$, 则 $\frac{\partial}{\partial t} \sim -i\omega$

扰动流场 $\vec{v}(\vec{r}, t) = v(z) \exp(i k_x x + i k_y y - i\omega t)$, $\vec{k} = k_x \vec{e}_x + k_y \vec{e}_y$, 可先保留
 考虑不可压情况 ($\nabla \cdot \vec{v} = 0$), 可简化: $\nabla \cdot \vec{v} = \frac{\partial v_z}{\partial z} = 0$

$$\begin{cases} -i\omega \rho' + i\rho_0 k \cdot \vec{v}' + \rho_0 \frac{\partial v_z}{\partial z} + \nu_z \frac{d\rho_0}{dz} = 0 \Rightarrow -i\omega \rho' + \nu_z \frac{d\rho_0}{dz} = 0 \Rightarrow \rho' = -\frac{i \nu_z \frac{d\rho_0}{dz}}{\omega} \quad (1) \\ -i\omega \rho' + \nu_z \frac{d\rho_0}{dz} = 0 \Rightarrow \rho' = -\frac{i \nu_z \frac{d\rho_0}{dz}}{\omega} \quad (2) \\ -i\omega \rho_0 \vec{v}' = -i k \rho' - \frac{d\rho_0}{dz} \vec{e}_z - \rho' g \vec{e}_z \Rightarrow \begin{cases} \omega \rho_0 \vec{v}' = k \rho' \\ i\omega \rho_0 \nu_z = \frac{\partial \rho'}{\partial z} + \rho' g \end{cases} \quad (3) \end{cases}$$

联合以上方程 (1)-(4), 可保留各项, 得:

由子方向运动方程 (4) $\Rightarrow \omega^2 \rho_0 \nu_z = \frac{\omega^2}{k^2} \rho_0 \left(\frac{d^2 \nu_z}{dz^2} + \frac{d\nu_z}{dz} \frac{d\rho_0}{dz} \right) - \nu_z g \frac{d\rho_0}{dz}$

在 I, II 区分别成立, $k^2 \nu_z = \frac{d^2 \nu_z}{dz^2} / \frac{d\rho_0}{dz}$

得 $\nu_z \sim \exp(\pm k z)$, $k z > 0$ 时, 取 "-", $k z < 0$ 时, 取 "+", 得 $\frac{d\nu_z}{dz} = \pm k \nu_z$, $\frac{d^2 \nu_z}{dz^2} = k^2 \nu_z$

扰动流场 \vec{v} 的密度, 仅依赖于 \vec{k} , 可设 $\rho_0 = 0$ 为扰动, $\nu_z \sim \exp(\pm k z)$

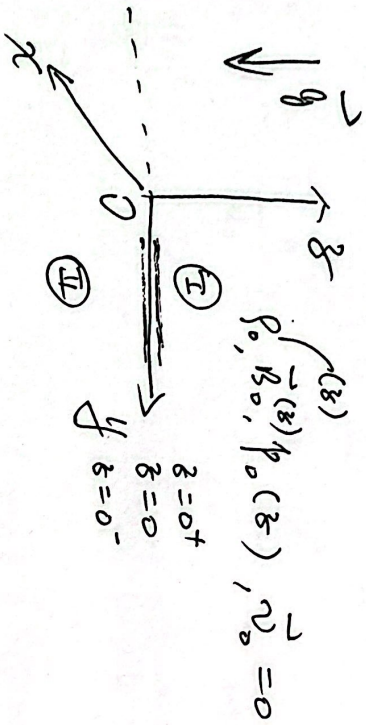
得 $\omega^2 \rho_0 = \frac{\omega^2}{k^2} \rho_0^2 \rho_0 \pm \frac{\omega^2}{k^2} \rho_0 \frac{d\rho_0}{dz} - g \frac{d\rho_0}{dz}$, 对 $z=0$ 上下薄层做线性扰动 (由 $z=0^-$ 和 $z=0^+$), 得

(3)

$$0 = -\frac{\omega^2}{k^2} \rho_0 \rho_{10} - \frac{\omega^2}{k^2} \rho_0 \rho_{20} - g(\rho_{10} - \rho_{20}) \Rightarrow \frac{\omega^2}{k^2} \rho_0 (\rho_{10} + \rho_{20}) = -g(\rho_{10} - \rho_{20}) \Rightarrow \omega^2 = -\frac{kg(\rho_{10} - \rho_{20})}{\rho_{10} + \rho_{20}} < 0$$

$\omega^2 < 0$, 绝对不稳定.

MHD RT:



$$\vec{g} = (0, 0, -g)$$

$$\vec{B}_0 = (B_x(z), B_y(z), 0)$$

z 方向是一个特殊的方向, 在该方向上背景

参数不均匀, $\frac{\partial \rho_0}{\partial z} = \frac{d\rho_0(z)}{dz} \neq 0$ 需保留 $\frac{d}{dz} \rho_0$

对 x, y 方向仍可用简谐振子表示, $e^{i(k_x x - \omega t)}$

$$\vec{r} = k_x \vec{e}_x + k_y \vec{e}_y$$

$$\nabla \sim i k_x + \frac{d}{dz} \vec{e}_z \quad \frac{\partial}{\partial t} \sim -i\omega$$

$$\nabla \rho_0 \sim \frac{d\rho_0}{dz} \vec{e}_z \quad (\text{作用于扰动量})$$

$$\frac{\partial p}{\partial t} + \vec{v} \cdot (\nabla p) + (\gamma - 1) \rho \nabla \cdot \vec{v} = 0$$

$$\rho \frac{d\vec{v}}{dt} = -\nabla p + \rho \vec{g} + \vec{j} \times \vec{B} = -\nabla(p + \frac{B^2}{2\mu_0}) + \frac{\vec{B} \cdot \nabla \vec{B}}{\mu_0} + \rho \vec{g}$$

$$\frac{\partial \vec{B}}{\partial t} = \nabla \times (\vec{v} \times \vec{B}) \quad (\vec{E} + \vec{v} \times \vec{B} = 0)$$

$$\nabla \cdot \vec{B} = 0$$

小扰动, 线性化, 得:

$$\frac{\partial p'}{\partial t} + \rho_0 \nabla \cdot \vec{v} + \vec{v} \cdot \nabla \rho_0 = 0$$

$$\frac{\partial p'}{\partial t} + \gamma \rho_0 \nabla \cdot \vec{v} + \vec{v} \cdot \nabla \rho_0 = 0$$

$$\frac{\partial \vec{B}'}{\partial t} = -\vec{B}_0 \cdot \nabla \vec{v} + \vec{B}_0 \cdot \nabla \vec{v} - \vec{v} \cdot \nabla \vec{B}_0$$

$$\nabla \cdot \vec{B}' = 0$$

$$\rho_0 \frac{\partial \vec{v}'}{\partial t} = -\nabla(p' + \frac{\vec{B}_0 \cdot \nabla \vec{B}'}{\mu_0}) + \frac{\vec{B}_0 \cdot \nabla \vec{B}' + \vec{B}' \cdot \nabla \vec{B}_0}{\mu_0} + \rho' \vec{g}$$

$$-\nabla p_0 + \rho_0 \vec{g} - \nabla \frac{B^2}{2\mu_0} + \frac{\vec{B}_0 \cdot \nabla \vec{B}_0}{\mu_0} = 0$$

$\vec{\tau} = 0$

假设波不可压, 即 $\nabla \cdot \vec{v} = 0$, 得 $\vec{k} \cdot \vec{v} = +i\omega \frac{dv_x}{dz}$, 又由 $\nabla \cdot \vec{B}' = 0$, 得 $\vec{k} \cdot \vec{B}' = i\omega \frac{dB_z}{dz}$... (1) (2) (4)

有: $i\omega \rho' = \nu_z \frac{d\rho_0}{dz}$ 或 $\rho' = -\frac{i\nu_z}{\omega} \frac{d\rho_0}{dz}$... (3) $i\omega \rho' = \nu_z \frac{d\rho_0}{dz}$, 或 $\rho' = -\frac{i\nu_z}{\omega} \frac{d\rho_0}{dz}$... (4)

$i\omega \vec{B}' = \nu_z \frac{d\vec{B}_0}{dz} - i\vec{k} \cdot \vec{B}_0 \vec{v} \Rightarrow \vec{B}' = -\frac{i\nu_z}{\omega} \frac{d\vec{B}_0}{dz} - \frac{\vec{k} \cdot \vec{B}_0}{\omega} \vec{v}$... (5) $\Rightarrow B_z' = -\frac{i\nu_z}{\omega} \nu_z$... (6)

$\rho \omega \rho_0 \vec{v} = \vec{k} (\rho' + \frac{B_0 \cdot \vec{B}'}{\mu_0}) - \frac{B_0 \cdot \vec{k}}{\mu_0} \vec{B}' + i\frac{d}{dz} (\rho' + \frac{B_0 \cdot \vec{B}'}{\mu_0}) \vec{e}_z - i\rho' g \vec{e}_z$

其中 $\vec{k} (\rho' + \frac{B_0 \cdot \vec{B}'}{\mu_0}) = -\frac{i\nu_z}{\omega} \frac{d\rho_0}{dz} \vec{k} - \frac{i\nu_z}{\omega \mu_0} \frac{d\vec{B}_0}{dz} \cdot \vec{B}_0 \vec{k} - \frac{(\vec{k} \cdot \vec{B}_0)(\vec{v} \cdot \vec{B}_0)}{\omega \mu_0} \vec{k}$, $-\frac{B_0 \cdot \vec{k}}{\mu_0} \vec{B}' = \frac{i\nu_z}{\omega} \frac{d\vec{B}_0}{dz} (\vec{B}_0 \cdot \vec{k}) + \frac{(\vec{k} \cdot \vec{B}_0)^2}{\omega \mu_0} \vec{v}$

注意到: $i\nu_z \frac{d\vec{B}_0}{dz} = -i\frac{\vec{k} \cdot \vec{B}_0}{\omega \mu_0} \frac{d\vec{B}_0}{dz} \nu_z$ 与 $-\frac{B_0 \cdot \vec{k}}{\mu_0} \vec{B}'$ 中的第一项抵消, 将之第二项移至左侧, 得:

$(\omega^2 - \frac{(\vec{k} \cdot \vec{B}_0)^2}{\mu_0 \rho_0}) \vec{v} = -\frac{i\nu_z}{\rho_0} \frac{d\rho_0}{dz} \vec{k} - \frac{i\nu_z}{\mu_0 \rho_0} \frac{d\vec{B}_0}{dz} \cdot \vec{B}_0 \vec{k} - \frac{(\vec{k} \cdot \vec{B}_0)(\vec{v} \cdot \vec{B}_0)}{\mu_0 \rho_0} \vec{k} - \frac{\nu_z}{\rho_0} \frac{d\rho_0}{dz} + \frac{\nu_z}{\mu_0 \rho_0} \frac{d\vec{B}_0}{dz} \cdot \vec{B}_0 - \frac{i(\vec{k} \cdot \vec{B}_0)(\vec{v} \cdot \vec{B}_0)}{\mu_0 \rho_0}$

可得之拆分成 ν_k 分量与 ν_z 分量, 后者 $\nu_k = -\frac{i}{k} \frac{dv_x}{dz}$, 得:

$(\omega^2 - (\vec{k} \cdot \vec{v}_k)^2) i\frac{dv_x}{dz} = \left[+\frac{i\nu_z}{\rho_0} \frac{d\rho_0}{dz} + i\frac{\nu_z}{\mu_0 \rho_0} \frac{d\vec{B}_0}{dz} \cdot \vec{B}_0 \right] + \frac{(\vec{k} \cdot \vec{B}_0)(\vec{v} \cdot \vec{B}_0)}{\mu_0 \rho_0} \nu_k$

$(\omega^2 - (\vec{k} \cdot \vec{v}_k)^2) \nu_z = -\frac{d}{dz} \left[\frac{\nu_z}{\rho_0} \frac{d\rho_0}{dz} + \frac{\nu_z}{\mu_0 \rho_0} \frac{d\vec{B}_0}{dz} \cdot \vec{B}_0 - \frac{i(\vec{k} \cdot \vec{B}_0)(\vec{v} \cdot \vec{B}_0)}{\mu_0 \rho_0} \right] - \frac{\nu_z}{\rho_0} \frac{d\rho_0}{dz} g$

将上式代入下式, 得 $[\omega^2 - (\vec{k} \cdot \vec{v}_k)^2] \nu_z = +\frac{d}{dz} \left\{ [\omega^2 - (\vec{k} \cdot \vec{v}_k)^2] \frac{dv_x}{dz} \right\} / k^2 - \frac{\nu_z}{\rho_0} \frac{d\rho_0}{dz} g$

上式在 (I) (II) 均成立, 则在 (I) (II) 区有: $[\omega^2 - (\vec{k} \cdot \vec{v}_k)^2] (\nu_z k^2 - \frac{d^2 \nu_z}{dz^2}) = 0$, 即在 (I) (II) 区均有 $\frac{d^2 \nu_z}{dz^2} = k^2 \nu_z$.

同样, ~~在~~ $\nu_z = 0$ 处, 振幅 ν_z 为 0, 则 $\nu_z = \nu_z \exp(i\vec{k} \cdot \vec{r})$, $z=0^+$ 时, 取 "+", $z=0^-$ 时, 取 "-" 且对于 $z=0$ 面上下薄层线积分, 得:

在边界层处，满足

$$\left[\omega^2 - (\vec{k} \cdot \vec{v}_A)^2 \right] k^2 v_z = \frac{d}{dz} \left[\omega^2 - (\vec{k} \cdot \vec{v}_A)^2 \right] \frac{dv_z}{dz} + \left[\omega^2 - (\vec{k} \cdot \vec{v}_A)^2 \right] \frac{d^3 v_z}{dz^3} - \frac{k^2 g}{\rho_0} \frac{d\rho_0}{dz}$$

将连续性方程代入，得：
 $\frac{d}{dz} \left\{ \rho_0 \omega^2 - \frac{(\vec{k} \cdot \vec{B}_0)^2}{\mu_0} \right\} (\pm k) - k^2 g \frac{d\rho_0}{dz} = 0$

对子积分，得：
 $\left[\rho_{10} \omega^2 - \frac{(\vec{k} \cdot \vec{B}_0)^2}{\mu_0} \right] (-k) - k^2 g \rho_{10} = \left[\rho_{20} \omega^2 - \frac{(\vec{k} \cdot \vec{B}_0)^2}{\mu_0} \right] k - k^2 g \rho_{20}$

得：
$$\omega^2 = - \frac{k g (\rho_{10} - \rho_{20})}{\rho_{20} + \rho_{10}} + \frac{(\vec{k} \cdot \vec{B}_{10})^2 + (\vec{k} \cdot \vec{B}_{20})^2}{\mu_0 (\rho_{20} + \rho_{10})}$$

可知，磁场起致稳作用，若 $\vec{k} \perp \vec{B}_0$ ，则无作用；有条件稳定。
 $\rho_{10} = \rho_{20}$ 时， $\omega^2 = (k \cdot \vec{v}_A)^2$ ，Alfven 波。

5.3.2 KH 不稳定性：从流体力学到磁流体力学

不考虑力： $\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{v}) = 0$

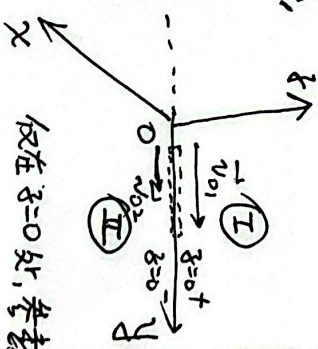
$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{v}) + (\gamma - 1) \rho \nabla \cdot \vec{v} = 0$$

$$\frac{\nabla \cdot \vec{v} = 0}{\text{不可压}} \quad \left\{ \begin{aligned} \rho \frac{d\vec{v}}{dt} &= -\nabla p = \rho \left(\frac{\partial \vec{v}}{\partial t} + \vec{v} \cdot \nabla \vec{v} \right) \end{aligned} \right.$$

$$\frac{\partial \rho'}{\partial t} + \vec{v}' \cdot \nabla \rho_0 + \vec{v}_0 \cdot \nabla \rho' + \rho' \nabla \cdot \vec{v}_0 + \rho_0 \nabla \cdot \vec{v}' = 0$$

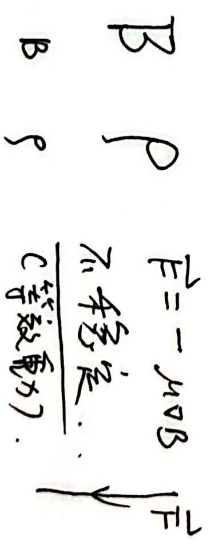
$$\rho_0 \left(\frac{\partial \vec{v}'}{\partial t} + \vec{v}_0 \cdot \nabla \vec{v}' + \vec{v}' \cdot \nabla \vec{v}_0 \right) = -\nabla p'$$

$$\frac{\partial p'}{\partial t} + \underbrace{\gamma \rho' \nabla \cdot \vec{v}_0 + \delta \rho_0 \nabla \cdot \vec{v}'}_{=0} + \vec{v}_0 \cdot \nabla p' + \vec{v}' \cdot \nabla \rho_0 = 0$$



只在 $z=0$ 处，考虑有跳变

交换不稳定性 Interchange Instab.



上下界面压力连续条件。

将扰动量写成 $(\rho', p', \vec{v}') \sim (\rho', p', \vec{v}') \exp [i(\vec{k} \cdot \vec{r} - \omega t) \pm k_z z]$ ， $z=0^+$ 时，取“+”； $z=0^-$ 时，取“-”。



典型磁结构

结合适当的边界条件，可以只需求处理子问题的方程。

(6)

$$\rho_0 \left(\frac{\partial v'_x}{\partial t} + \vec{v}_0 \cdot \nabla v'_x \right) = - \frac{\partial p'}{\partial z} \Rightarrow -i \rho_0 (\omega - \vec{k} \cdot \vec{v}_0) v'_z = - \frac{\partial p'}{\partial z}$$

① 分界面处位置移 ~~量~~ 量表示：
 将速度应用 得 $\rho_0 (\omega - \vec{k} \cdot \vec{v}_0) v'_z = - \frac{\partial p'}{\partial z}$
 $\xi = \sqrt{\epsilon} \exp(i(\vec{k} \cdot \vec{r} - \omega t))$, 得 $v'_z = \frac{dp'}{dz} = (\frac{\partial}{\partial z} + \vec{v}_0 \cdot \nabla) \xi = -i(\omega - \vec{k} \cdot \vec{v}_0) \xi$

② 压强连续，在分界面处取无穷薄片，体积分，可和体积内质量 $\rightarrow 0$ 故与密度相关项 $\rightarrow 0$ ，仅余下压强。

分界处 得： $-\rho_{10} (\omega - \vec{k} \cdot \vec{v}_{10})^2 \xi_1 = \rho_{20} (\omega - \vec{k} \cdot \vec{v}_{20})^2 \xi_2$ [面积元的量连续]， $\xi_1 = \xi_2$ ，得

$$\rho_{10} (\omega^2 - 2i\vec{k} \cdot \vec{v}_{10} \omega + (\vec{k} \cdot \vec{v}_{10})^2) + \rho_{20} [\omega^2 - 2i\vec{k} \cdot \vec{v}_{20} \omega + (\vec{k} \cdot \vec{v}_{20})^2] = 0$$

$$\omega^2 (\rho_{10} + \rho_{20}) - 2i\omega [\rho_{10} \vec{k} \cdot \vec{v}_{10} + \rho_{20} \vec{k} \cdot \vec{v}_{20}] + \rho_{10} (\vec{k} \cdot \vec{v}_{10})^2 + \rho_{20} (\vec{k} \cdot \vec{v}_{20})^2 = 0$$

$$\text{得： } \omega = \frac{\rho_{10} \vec{k} \cdot \vec{v}_{10} + \rho_{20} \vec{k} \cdot \vec{v}_{20} \pm i \sqrt{\rho_{10} \rho_{20} (\vec{k} \cdot \vec{v}_{10} - \vec{k} \cdot \vec{v}_{20})^2}}{\rho_{10} + \rho_{20}}$$

同样是绝对不稳定， $\vec{v}_{10} = \vec{v}_{20}$ ， $\rho_{10} = \rho_{20}$ 时， $\omega = \vec{k} \cdot \vec{v}_0$ ，Doppler 位移。

[MHD-KH] (不可压)

$$\rho_0 \left(\frac{\partial \vec{v}'}{\partial t} + \vec{v}_0 \cdot \nabla \vec{v}' \right) = - \nabla (p' + \frac{\vec{B}_0 \cdot \vec{B}'}{\mu_0}) + \vec{B}_0 \cdot \nabla \vec{B}' + \frac{\vec{B}' \cdot \nabla \vec{B}_0}{\mu_0}$$

$$\text{子方向分量： } \rho_0 \left(\frac{\partial v'_x}{\partial t} + \vec{v}_0 \cdot \nabla v'_x \right) = - \frac{\partial}{\partial z} (p' + \frac{\vec{B}_0 \cdot \vec{B}'}{\mu_0}) + \vec{v}_0 \cdot \nabla B'_z$$

$$- \rho_0 (\omega - \vec{k} \cdot \vec{v}_0)^2 \xi - \frac{i \vec{k} \cdot \vec{B}_0 B'_z}{\mu_0} = - \frac{\partial}{\partial z} (p' + \frac{\vec{B}_0 \cdot \vec{B}'}{\mu_0})$$

[\vec{k} 与 \vec{B}_0 均位于 xy 面]

① $\frac{\partial p'}{\partial z} \sim \frac{p' - p_0}{\Delta z}$
 ② $\frac{\partial v'_z}{\partial z} \sim \frac{v'_z - v'_z}{\Delta z}$
 = 者相反，大小相等

$$\text{由 } \frac{\partial \vec{B}}{\partial t} = \nabla \times (\vec{v} \times \vec{B}) \text{, 得 } \frac{\partial \vec{B}'}{\partial t} = \vec{B}_0 \cdot \nabla \vec{v}' - \vec{v}' \cdot \nabla \vec{B}_0 \text{, } -i\omega \vec{B}'_z = \vec{v}_0 \cdot \nabla B'_z - i\vec{v}_0 \cdot \vec{k} B'_z \Rightarrow (\omega - \vec{k} \cdot \vec{v}_0) B'_z = - \vec{k} \cdot \vec{B}_0$$

得：

$$B_k' = \frac{-\vec{k} \cdot \vec{b}_0 \nu_k'}{\omega - \vec{k} \cdot \vec{v}_0}$$

$$B_k' = i \vec{k} \cdot \vec{b}_0 \xi$$

$$\Rightarrow -\rho_{10} (\omega - \vec{k} \cdot \vec{v}_0)^2 \xi + \frac{(\vec{k} \cdot \vec{b}_0)^2}{\mu_{10}} \xi = -\frac{\partial}{\partial k} (\phi' + \frac{\vec{b}_0 \cdot \vec{k}'}{\mu_{10}})$$
(7)

同样基于压强连续条件，得： $-\rho_{10} (\omega - \vec{k} \cdot \vec{v}_0)^2 + \frac{(\vec{k} \cdot \vec{b}_{10})^2}{\mu_{10}} = \rho_{20} (\omega - \vec{k} \cdot \vec{v}_{20})^2 - \frac{(\vec{k} \cdot \vec{b}_{20})^2}{\mu_{20}}$

得 $\rho_{10} (\omega - \vec{k} \cdot \vec{v}_{20})^2 + \rho_{20} (\omega - \vec{k} \cdot \vec{v}_{20})^2 - \frac{(\vec{k} \cdot \vec{b}_{10})^2}{\mu_{10}} - \frac{(\vec{k} \cdot \vec{b}_{20})^2}{\mu_{20}} = 0$

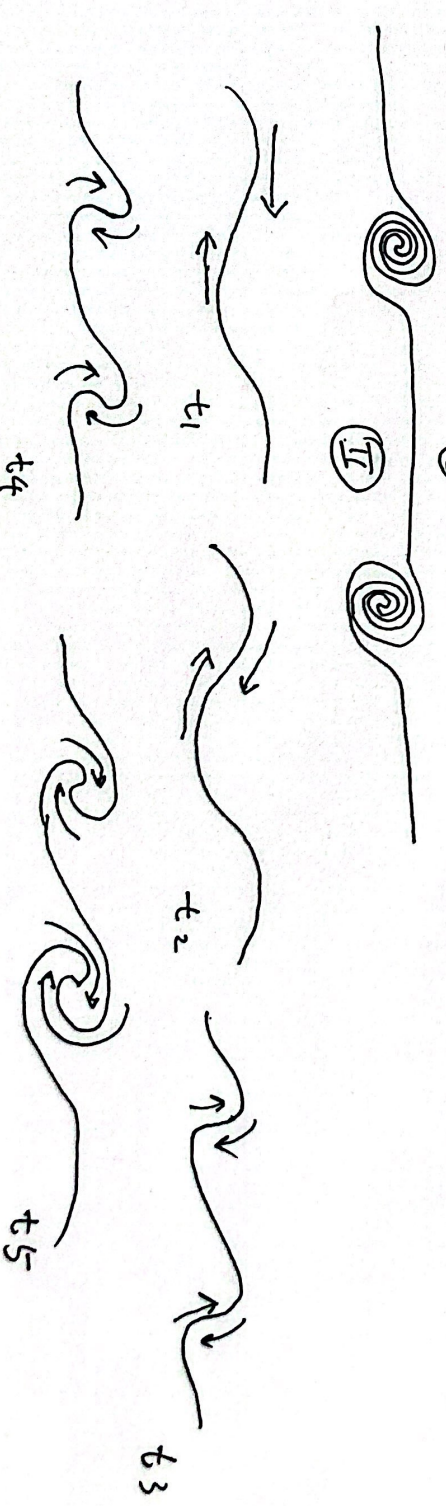
$$\Rightarrow \omega = \frac{\rho_{10} \vec{k} \cdot \vec{v}_0 + \rho_{20} \vec{k} \cdot \vec{v}_{20} \pm \sqrt{\frac{\rho_{10} + \rho_{20}}{\mu_{10}} [(\vec{k} \cdot \vec{b}_{10})^2 + (\vec{k} \cdot \vec{b}_{20})^2]} - \rho_{10} \rho_{20} (\vec{k} \cdot \vec{v}_0 - \vec{k} \cdot \vec{v}_{20})^2}}{\rho_{10} + \rho_{20}}$$

可知： $\omega \vec{v}_{10} = \vec{v}_{20}$, $\vec{b}_{10} = \vec{b}_{20}$ 时， $\omega = \vec{k} \cdot (\vec{v}_0 + \vec{v}_A)$ ，Alfvén 波的增长。

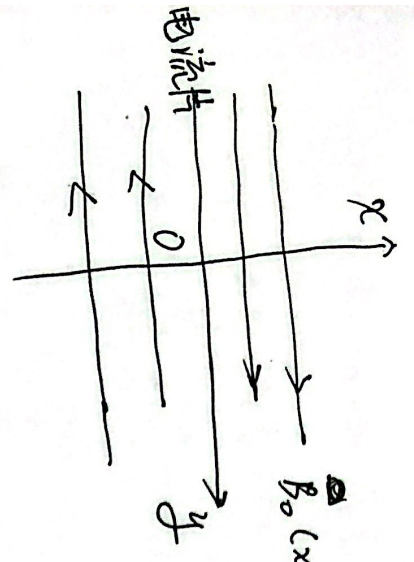
- ② 磁场起致稳作用，有条件稳定，可得稳定条件： $\frac{\rho_{10} + \rho_{20}}{\mu_{10}} [(\vec{k} \cdot \vec{b}_{10})^2 + (\vec{k} \cdot \vec{b}_{20})^2] \geq \rho_{10} \rho_{20} (\vec{k} \cdot \vec{v}_0 - \vec{k} \cdot \vec{v}_{20})^2$
- ③ $\vec{k} \perp \vec{b}_0$ 时，磁场无影响。

- ④ $\vec{k} \parallel \vec{b}_0$, $\rho_{10} = \rho_{20}$ 时，不稳定条件为： $\Delta v > 2v_A$

⑤ 典型湍流结构：



5.4 撕裂模不稳定性 (Tearing-mode Instability) —— 磁岛的开线 (Magnetic Island) (18)



背景磁场在 $x=0$ 处, 反向, 开线电流片. 设不可压, 不考虑热效应, 有

$$\rho \frac{d\vec{v}}{dt} = \vec{j} \times \vec{B}, \quad \frac{\partial \vec{B}}{\partial t} = -\nabla \times \vec{E}, \quad \vec{E} + \vec{v} \times \vec{B} = \eta \vec{j}, \quad \nabla \cdot \vec{v} = 0, \quad \nabla \cdot \vec{E} = 0.$$

设扰动参量 $A(x, y, t) = A(x) e^{vt} e^{iky}$, 则 $\frac{\partial}{\partial t} \sim v$, $\nabla \sim ik e_y + \frac{\partial}{\partial x} e_x$

$\frac{\partial}{\partial t} = 0$ (= 准稳)

得: $\gamma \rho v_x = -j_z B_0$, $\gamma B_x = -ik E_z$, $E_z + v_x B_0 = \eta j_z$, $ik v_y = -\frac{\partial v_x}{\partial x}$, $ik B_y = -\frac{\partial B_x}{\partial x}$

$\vec{r} = k e_y$.

共六个扰动参量 ($v_x, v_y, B_x, B_y, E_z, j_z$), 均可用 B_x 表示:

$$B_y = \frac{v}{k} \frac{\partial B_x}{\partial x}, \quad E_z = \frac{v \gamma B_x}{k}, \quad v_x = -\frac{v \gamma B_x B_0}{k(\eta \gamma \rho + B_0^2)}, \quad j_z = -\frac{\gamma \rho v_x}{B_0} = \frac{v \gamma \rho^2 B_x}{k(\eta \gamma \rho + B_0^2)}, \quad v_y = \frac{\partial}{\partial x} \left[\frac{B_x B_0}{\eta \gamma \rho + B_0^2} \right]$$

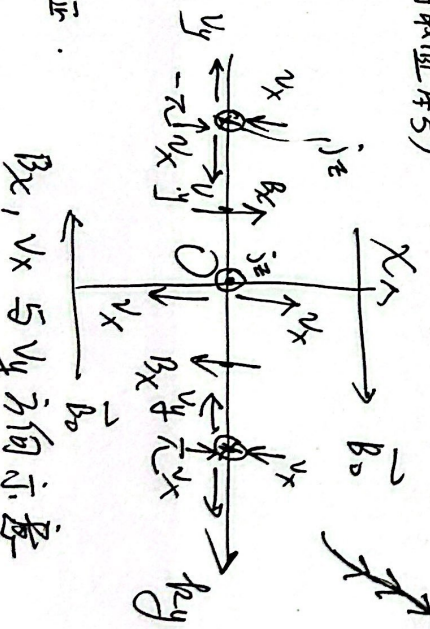
主要观察: v_x, v_y 与 B_x 反号, 磁岛开线, 注意: $x > 0$ 时, $B_0 > 0$; $x < 0$ 时, $B_0 < 0$.

可设 $B_x = |B_x| e^{vt} e^{iky + i\frac{z}{L}} = |B_x| e^{vt} (-\sin ky + i \cos ky)$

得各物理量实部 (观察 $\eta = \pm \pi, \pm \frac{\pi}{2}, 0$ 时取值符号)

$B_x \sim -\sin ky$
 $v_x \sim B_0 \cos ky$
 $v_y \sim -\sin ky \frac{\partial}{\partial x} \left[\frac{|B_x| B_0}{\eta \gamma \rho + B_0^2} \right]$
 $j_z \sim -\cos ky$

$x > 0$ 时, 为正
 $x < 0$ 时, 为负
 振荡为正



则 $x=0$ 处, 磁力线反号排斥, 电流流向外
 则 $x=\pm \pi$ 处, 磁力线被挤压, 电流流向
 方向与 B_0 电流方向相同, 电流增强,
 有限电阻情况下, 可形成撕裂, 切割磁力线
 磁力线被割开后, 向中心收缩, 呈岛状.

5.5 束流不稳定性 (streaming instability)

不同成份之间有流速差时, 可激发流不稳定性。考虑静电, 非磁化情况, 多元流体系组:

$$\frac{\partial N_\alpha}{\partial t} + \nabla \cdot (N_\alpha \vec{v}_\alpha) = 0$$

$$N_\alpha m_\alpha \left(\frac{\partial \vec{v}_\alpha}{\partial t} + \vec{v}_\alpha \cdot \nabla \vec{v}_\alpha \right) = -\nabla p_\alpha + N_\alpha q_\alpha \vec{E}$$

$$p_\alpha = c_\alpha p_{\alpha 0}$$

$$\nabla \cdot \vec{E} = \sum_\alpha N_\alpha q_\alpha / \epsilon_0$$

① 小扰动 $N_\alpha = N_{\alpha 0} + N_\alpha'$, $\sum_\alpha N_{\alpha 0} q_\alpha = 0$

$$\vec{v}_\alpha = \vec{v}_{\alpha 0} + \vec{v}_\alpha', \quad p_\alpha = p_{\alpha 0} + p_\alpha'$$

② 线性化 $\frac{\partial N_\alpha'}{\partial t} + \vec{v}_{\alpha 0} \cdot \nabla N_\alpha' + N_{\alpha 0} \nabla \cdot \vec{v}_\alpha' = 0$

$$N_{\alpha 0} m_\alpha \left(\frac{\partial \vec{v}_\alpha'}{\partial t} + \vec{v}_{\alpha 0} \cdot \nabla \vec{v}_\alpha' \right) = -\nabla p_\alpha' + N_{\alpha 0} q_\alpha \vec{E}$$

$$p_\alpha' = p_{\alpha 0}' c_\alpha^2, \quad c_\alpha^2 = \frac{\gamma_\alpha p_{\alpha 0}}{p_{\alpha 0}}$$

$$\nabla \cdot \vec{E} = \sum_\alpha N_\alpha' q_\alpha / \epsilon_0$$

③ FT \Rightarrow

$$(w - \vec{k} \cdot \vec{v}_{\alpha 0}) N_\alpha' = N_{\alpha 0} \vec{k} \cdot \vec{v}_\alpha'$$

$$(w - \vec{k} \cdot \vec{v}_{\alpha 0}) \vec{v}_\alpha' = -\frac{N_{\alpha 0} q_\alpha \vec{E}}{m_\alpha}$$

$$\vec{k} \cdot \vec{E} = \sum_\alpha N_\alpha' q_\alpha / \epsilon_0$$

$$N_{\alpha 0} \vec{k} \cdot \vec{v}_\alpha' = \frac{q_\alpha}{\epsilon_0} \sum_\alpha N_\alpha'$$

$$\vec{k} \cdot \vec{v}_\alpha' = \frac{N_{\alpha 0} q_\alpha}{w - \vec{k} \cdot \vec{v}_{\alpha 0}} \left[(w - \vec{k} \cdot \vec{v}_{\alpha 0})^2 - k^2 c_\alpha^2 \right] = \frac{N_{\alpha 0} q_\alpha \vec{k} \cdot \vec{E}}{m_\alpha}$$

$$\Rightarrow 1 = \sum_\alpha \frac{w p_{\alpha 0}^2}{(w - \vec{k} \cdot \vec{v}_{\alpha 0})^2 - k^2 c_\alpha^2}$$

考虑电子、质子等离子体 ($\vec{v}_e, p_0 = 0$) 及束流电子 ($T_{b0} = 0$, \vec{v}_{b0} , N_{b0} , $\alpha = N_{b0}/N_{e0}$), 得:

$$1 = \frac{w p_{pe}^2}{w^2 - k^2 c_e^2} + \frac{w p_{pi}^2}{w^2 - k^2 c_i^2} + \frac{\alpha w p_{pe}^2}{(w - \vec{k} \cdot \vec{v}_{b0})^2}$$

对于静电波, 可设 $\vec{k} \parallel \vec{v}_{b0}$.

① $\alpha = 0$ 时, Langmuir 波色散关系.

② 可忽略质子贡献, 得 $1 = \frac{w p_e^2}{w^2 - k^2 c_e^2} + \frac{\alpha w p_e^2}{(w - k v_{b0})^2}$

可设 $w \gg k v_{b0}$, 得: $f(w) = 1$ 或右侧 1.

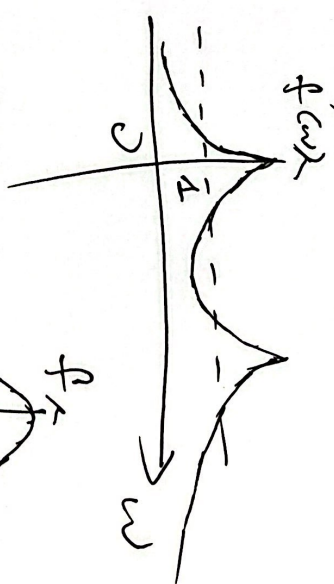
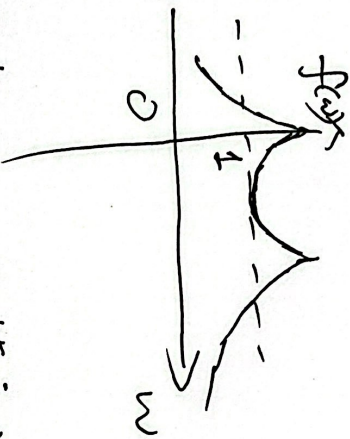
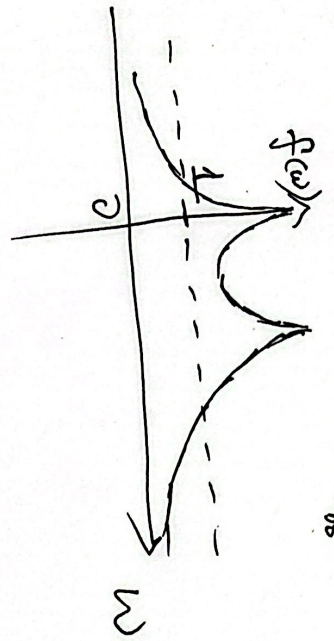
$$\left\{ \begin{array}{l} w \rightarrow 0, \text{ 及 } w \rightarrow k v_{b0} \text{ 时, } f(w) \rightarrow \infty \\ w \rightarrow \pm \infty \text{ 时, } f(w) \rightarrow 0 \end{array} \right.$$

由 $\frac{df}{d\omega} = 0$, 可求得 $\omega_m = \frac{kU_{b0}}{1 + \alpha^2}$, 得 $f(\omega_m) = \frac{\omega_{pe}^2}{k^2 U_{b0}^2} (1 + \alpha^2)^3$, 当 $f(\omega_m) > 1$ 时, 存在虚根, 即不稳定.

得 $k^2 v(\frac{2\pi}{\lambda})^2 < \frac{\omega_{pe}^2 (1 + \alpha^2)^3}{U_{b0}^2}$

, 即 k 较小 (λ 较大) 时, 更利于不稳定性的发生.

(10)



三种情况.

在理论中, 对应于尾瘤不稳定性, 相应速度分布函数为:

